

The role of the cohesive law shape and mixed-mode interpolation when modeling delamination failure involving large fracture process zones

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Background

A Continuum Damage Model for the Simulation of Delamination under Variable-Mode Ratio in Composite Materials

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**DEMEGI, Faculdade de Engenharia, Universidade do Porto, 4200-465 Porto, Portugal.

***NASA Langley Research Center, Hampton VA, U.S.A.

Best poster of the session 😊



Almost 20 years ago!!!

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Motivation and Objectives

Delamination is one of the predominant forms of failure in many laminated composites systems, especially when there is no reinforcement in the thickness direction. The numerical simulation of delamination can be developed within the framework of Damage Mechanics by means of a cohesive crack model: a cohesive damage zone - or softening plasticity - develops near the crack front. The critical driving force for delamination, G_c , strongly depends on the crack propagation mode. Therefore, it is important to formulate the cohesive models so that do not exhibit inconsistencies (i.e. restoration of the cohesive state) when the mode of propagation changes. Therefore, a thermodynamically consistent damage model for the simulation of progressive delamination under variable mode ratio has been developed in this work.

Approach

The model is formulated in the context of the Continuum Damage Mechanics (CDM). The constitutive equations that result from the variation of the free energy with damage are used to model the initiation and propagation of delamination. Interfacial penetration of two adjacent layers after complete decohesion is prevented by the formulation of the free energy. The equations of the Constitutive Damage Model are:

Table 1. Equations of the constitutive damage model:

Free Energy	$\psi(\Delta, \delta) = (1 - \delta) \psi^0(\Delta) + \delta \psi^d(\Delta, \delta)$
Constitutive equation	$\sigma_i = \frac{\partial \psi}{\partial \Delta_i} = (1 - \delta) E_{ij} \epsilon_j - \delta E_{ij} K_{ij}(\epsilon - \Delta_i)$
Displacement jump	$\Delta = \sqrt{(\Delta_0)^2 + (\Delta_{max})^2}$
Damage criterion	$F(\mathcal{N}, \mathcal{P}) = \Phi(\mathcal{N}) - \Phi(\mathcal{P}) \leq 0 \quad \forall \mathcal{P} \geq \mathcal{N}$ $\Phi(\mathcal{N}) = \frac{\mathcal{N}^2}{2G_c}$
Evolution law	$\dot{\delta} = \mu \frac{\partial F}{\partial \delta} \dot{\mathcal{N}} - \mu \frac{\partial F}{\partial \delta} \dot{\mathcal{P}}; \quad \dot{\delta} \geq 0$
Localized condition	$\mu \geq 0; \quad F(\mathcal{N}, \mathcal{P}) \leq 0; \quad \mu F(\mathcal{N}, \mathcal{P}) = 0$ $\mathcal{P} = \max[\mathcal{N}, \max_{\mathcal{P} \leq \mathcal{N}} \mathcal{P}] \quad 0 \leq \mathcal{P} \leq \mathcal{N}$

A bilinear constitutive equation is used to model the behaviour of the interface. The bilinear constitutive equation is defined by the initiation and propagation criteria. A new delamination initiation criterion is developed to assure that the formulation can account for changes in the loading mode in a thermodynamically consistent way. The propagation criterion used is the same proposed by Benzougagh and Kanane.

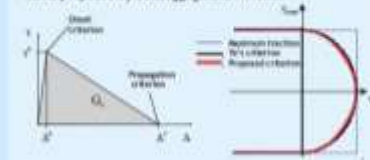


Figure 1. (a) Bilinear constitutive equation (b) Onset damage surface.

The formulation presented assures a smooth transition for all mixed mode ratios between the initial damage surface to the propagation surface through damage evolution.

Results

The model is implemented in the ABAQUS Finite Element code as a user-written element subroutine (UEL). To verify the element under different loading conditions, the double cantilever beam (DCB) test, the end notched flexure (ENF) test, and the mixed-mode bending (MMB) tests are simulated. The numerical predictions are compared with experimental data. (Fig. 3) A good agreement between the numerical predictions and the experimental results is obtained.

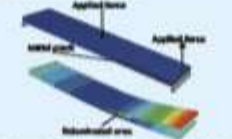


Figure 2. Undeformed and deformed mesh for an MMB test FE simulation.

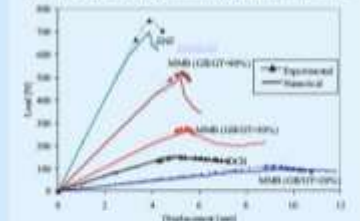


Figure 3. Numerical and experimental results.

Conclusions

The formulation proposed can predict the strength of composite structures that exhibit progressive delamination, even when the loading conditions, including the mixed-mode ratio, change.

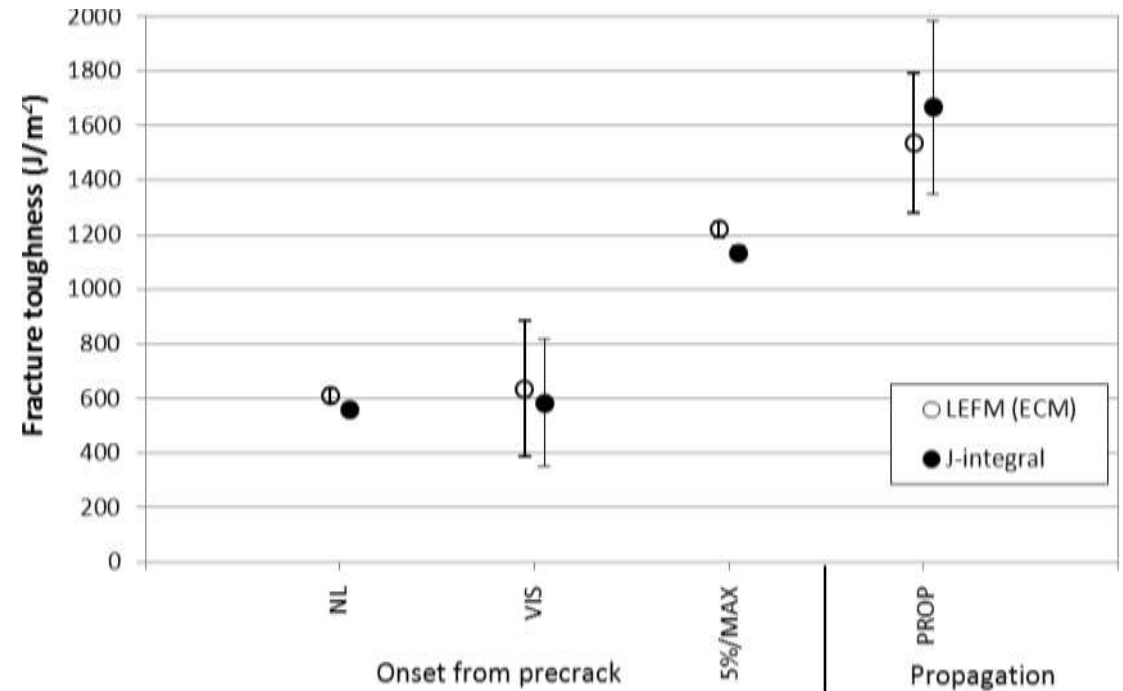
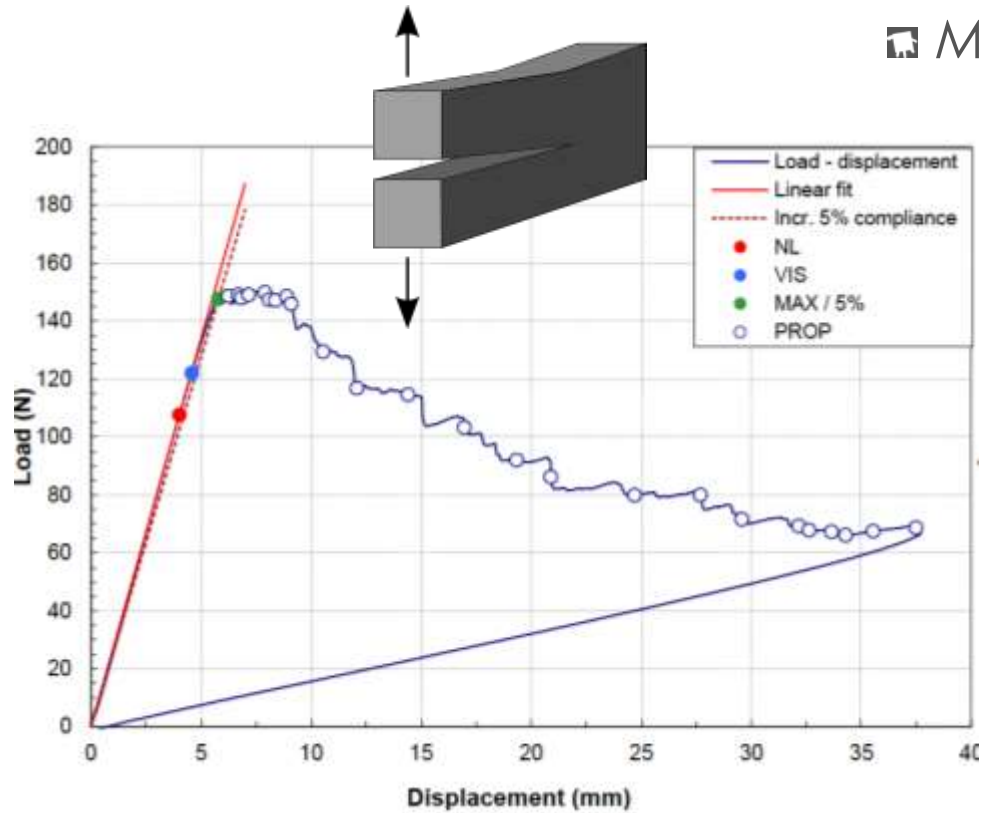
The model is easily implemented in a FE element environment. Currently, it is implemented using decoupled elements, but it also can be used in other element technologies such as continuum elements with embedded discontinuities.

Keynote speakers selection by the conference committee (Sept. 2022)

- ▣ *there are many researchers who use cohesive elements and never ask questions*
- ▣ *there is another (smaller) group that considers all this as nonphysical and rejects the method in spite of its applicability and practical usefulness*
- ▣ *there is a third group that HAS to use cohesive elements, but they want answers based on physics. (I hope we all belong to this group...)*
 - *Obviously, the answer there is in experimental identification of cohesive laws (in elastic, viscoelastic problems and also in the change of these laws in fatigue+ other things)*
 - *I believe that the group in Girona (Josep or Albert) could prepare an excellent presentation of methodologies for experimental determination of cohesive laws in all these different cases.*

Prompt: I need to capture delamination with my FEM model

Material data

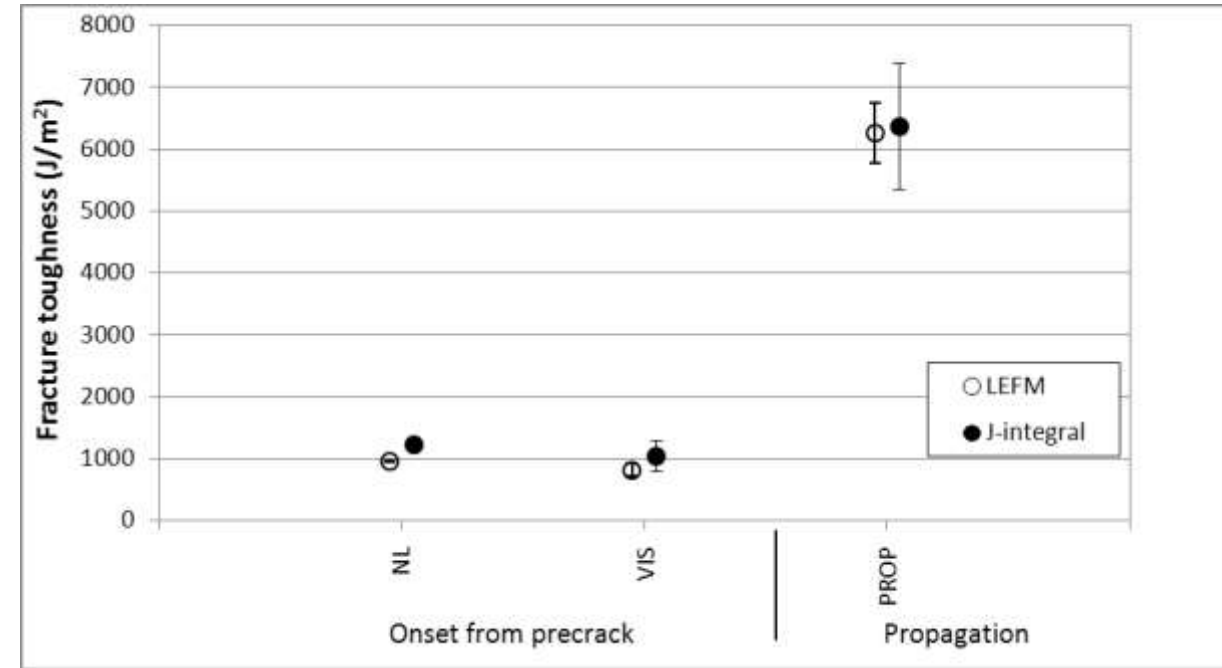
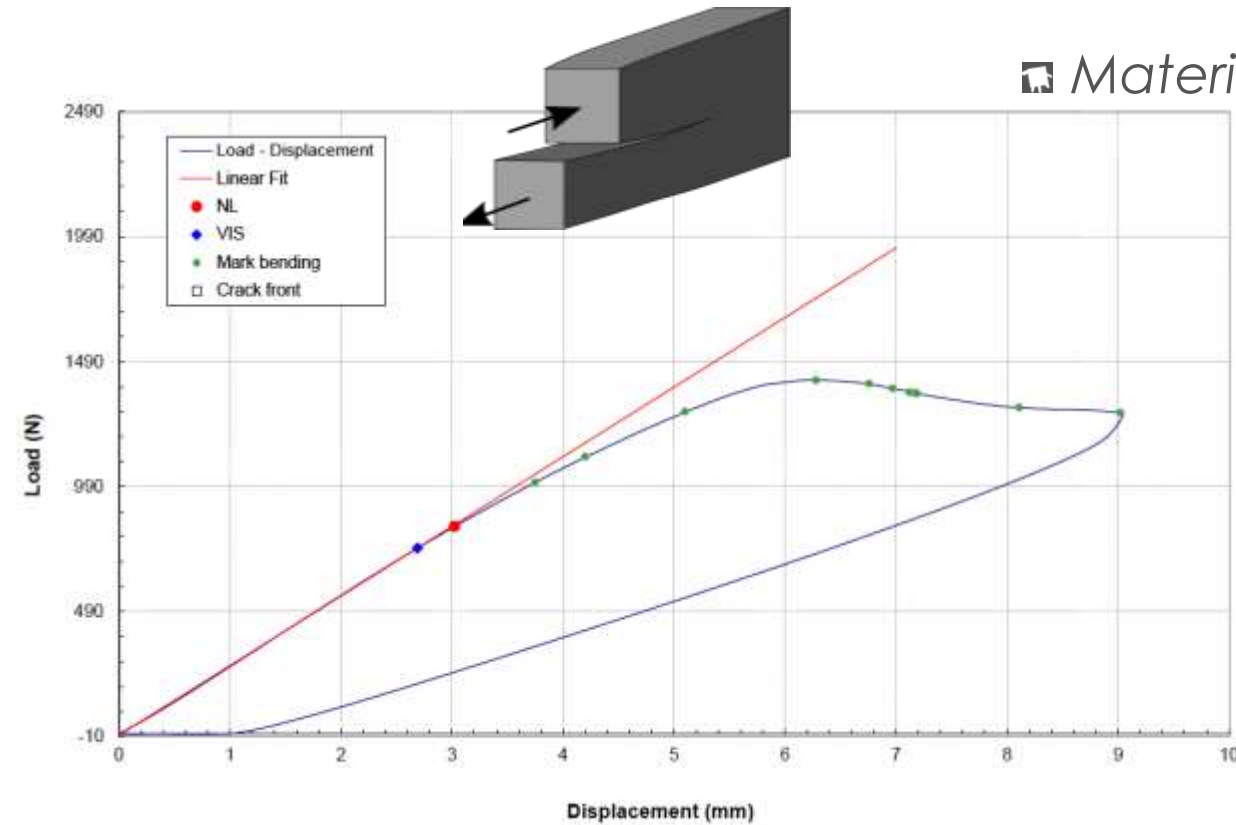


Specimen (internal code)	Propagation data	
	G _{IC} ECM (J/m ²) AVERAGE OF ECM PROPAGATION DATA*	J integral (J/m ²) AVERAGE OF PROPAGATION DATA*
14-1823	1354	1442
14-1824	1719	1891
Average	1536	1667
Standard deviation	258.09	317.46

Onset data from insert					
G _{IC} ECM (J/m ²)			J integral (J/m ²)		
NL	VIS	5%/MAX	NL	VIS	5%/MAX
628	811	1240	577	750	1152
591	460	1199	544	419	1116
610	635	1219	561	584	1134
25.98	248.25	29.32	23.60	234.10	25.23

Prompt: I need to capture delamination with my FEM model

Material data

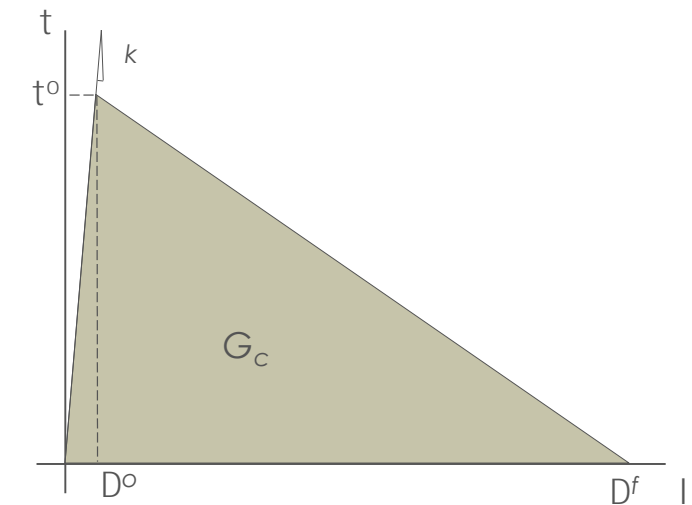


Specimen (internal code)	Propagation data		Onset data from insert			
	G _{IIC} (J/m ²) AVERAGE OF ECM PROPAGATION DATA*	J integral (J/m ²) AVERAGE OF PROPAGATION DATA*	G _{IIC} (J/m ²)		J integral (J/m ²)	
			NL	VIS	NL	VIS
14-1829	5914	5638	968	743	1147	861
14-1830	6597	7083	953	896	1303	1220
Average	6255	6360	960	819	1225	1041
Standard deviation	483,30	1021,86	10,24	107,86	110,67	253,69

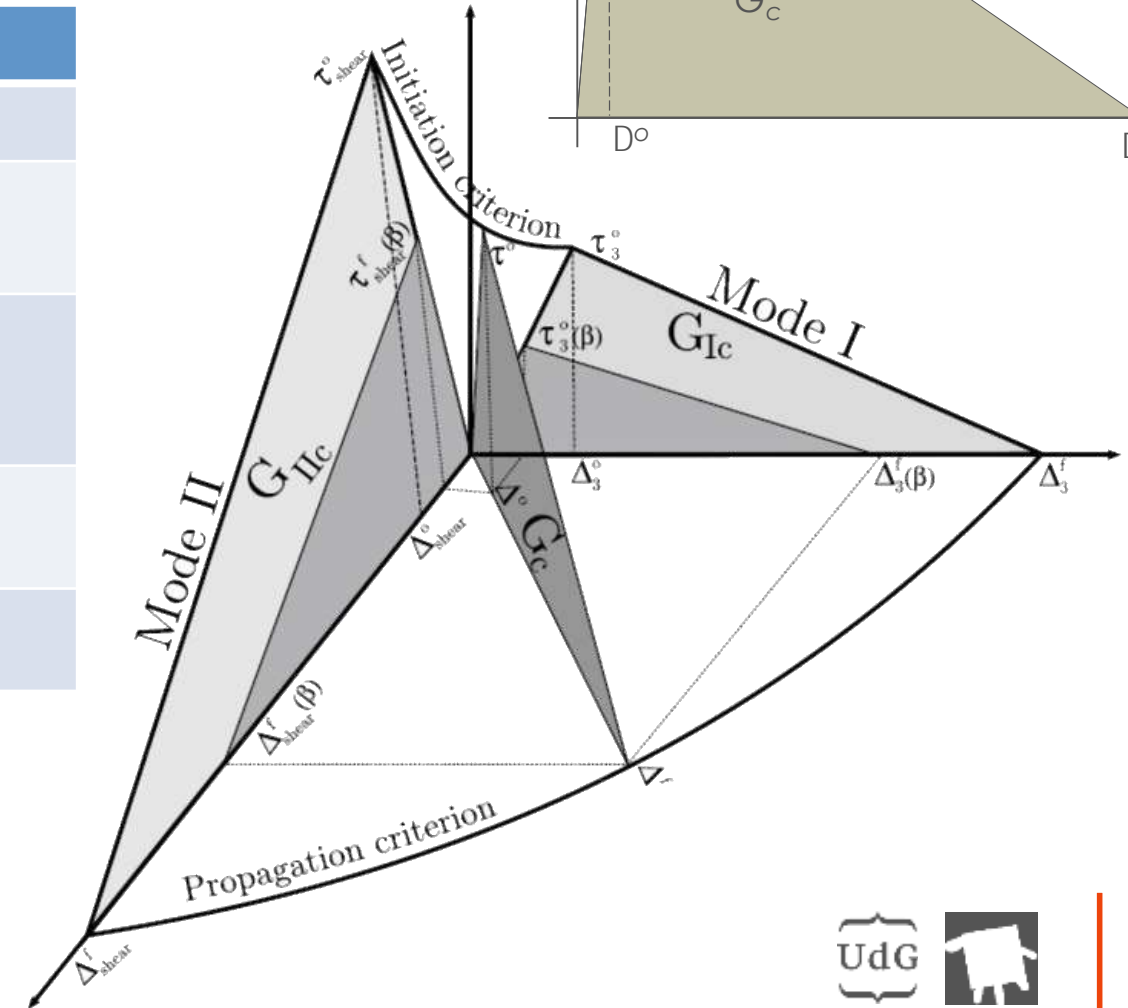
Prompt: I need to capture delamination with my FEM model

Input properties for my fem model?

5+1 parameters:
 G_{Ic} , G_{IIc} , τ_3 , τ_{sh} , η , k



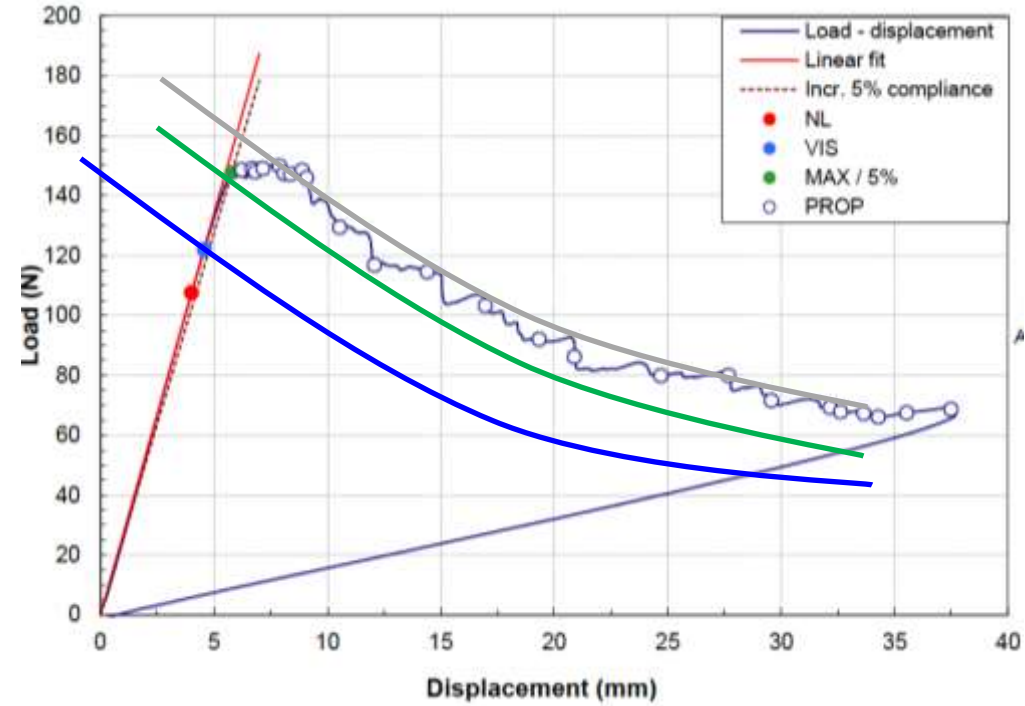
Reference	Test	Procedure/standard	Property
DCB	Mode I delamination test	ISO 25217	G_{Ic}
ENF	Mode II delamination test	ASTM	G_{IIc}
CELS		ESIS protocol	
MMB	Mixed mode delamination test	ASTM D6671M:13	Power law: $\langle , \textcircled{R}, \textcircled{C} \rangle$ BK:
L-angle	Curved beam in for point bending	ASTM D6415	l_3
ILSS	Intherlaminar shear strength	ASTM D2344	l_{sh}



Prompt: I need to capture delamination with my FEM model

5+1 parameters:
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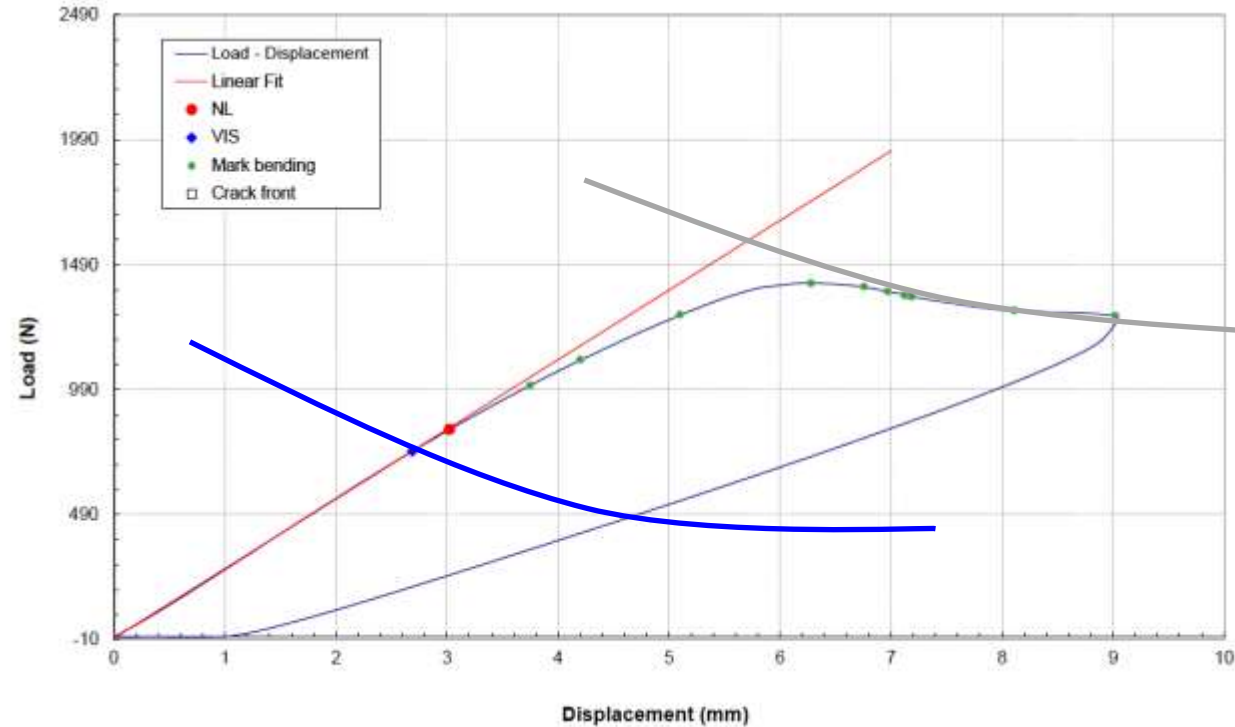


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Prompt: I need to capture delamination with my FEM model

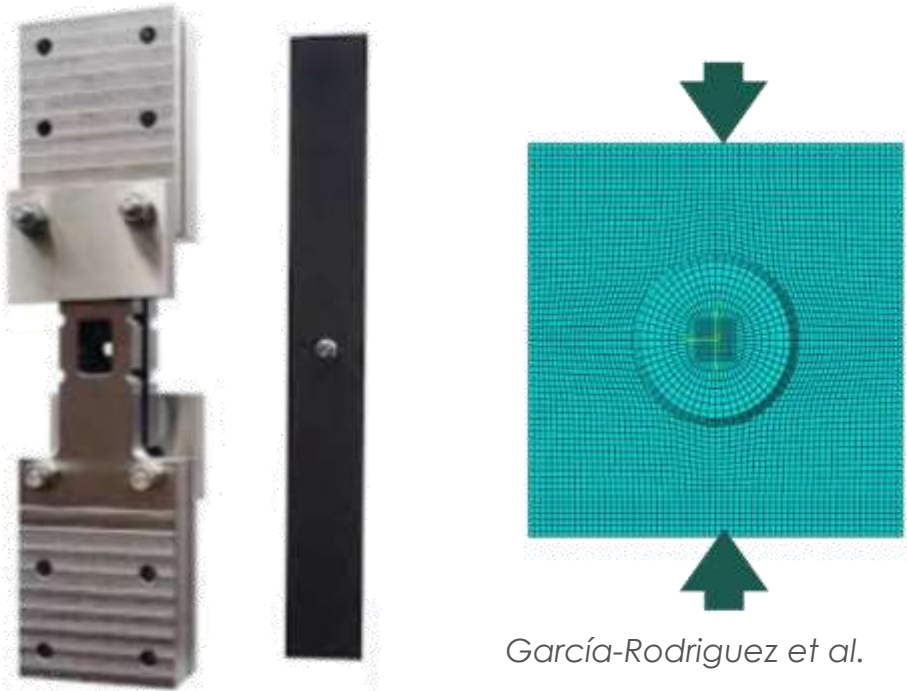
5+1 parameters:
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Input properties for my fem model?



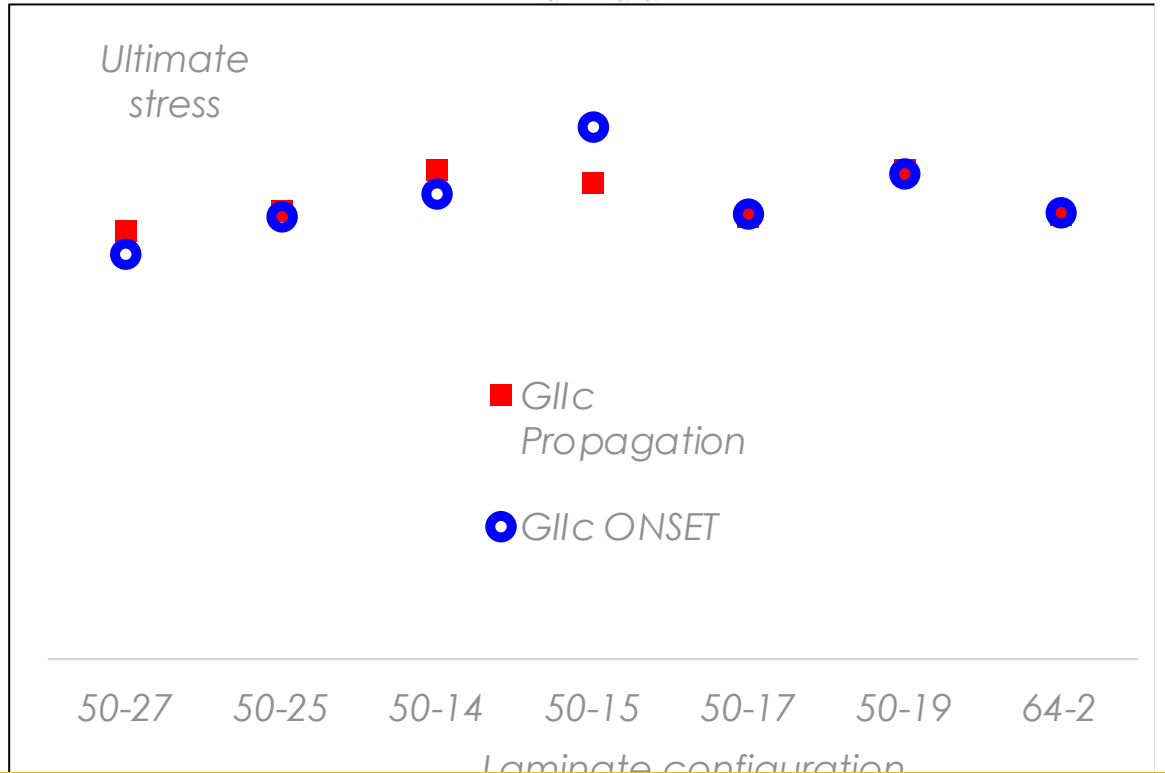
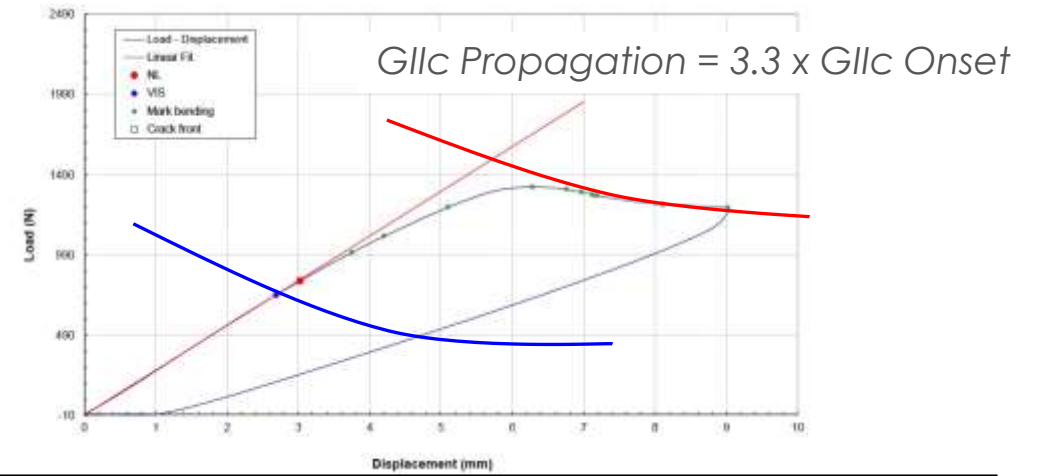
Specimen (internal code)	Propagation data		Onset data from insert			
	G_{IIc} (J/m ²) AVERAGE OF ECM PROPAGATION DATA*	J integral (J/m ²) AVERAGE OF PROPAGATION DATA*	G_{Ic} (J/m ²)		J integral (J/m ²)	
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Standard deviation	483,30	1021,86	10,24	107,86	110,67	253,69

Implications on a filled hole simulation



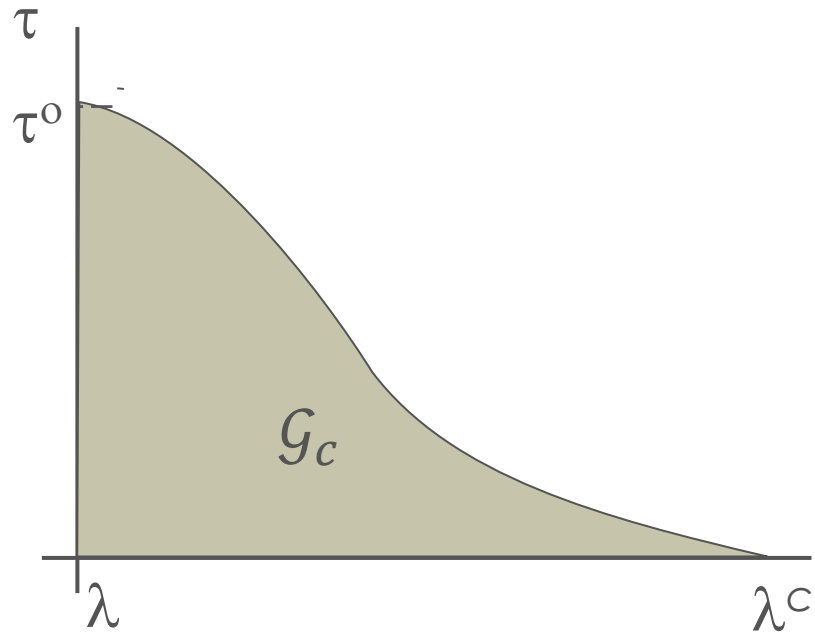
García-Rodríguez et al.

❏ “Most conservative” option?



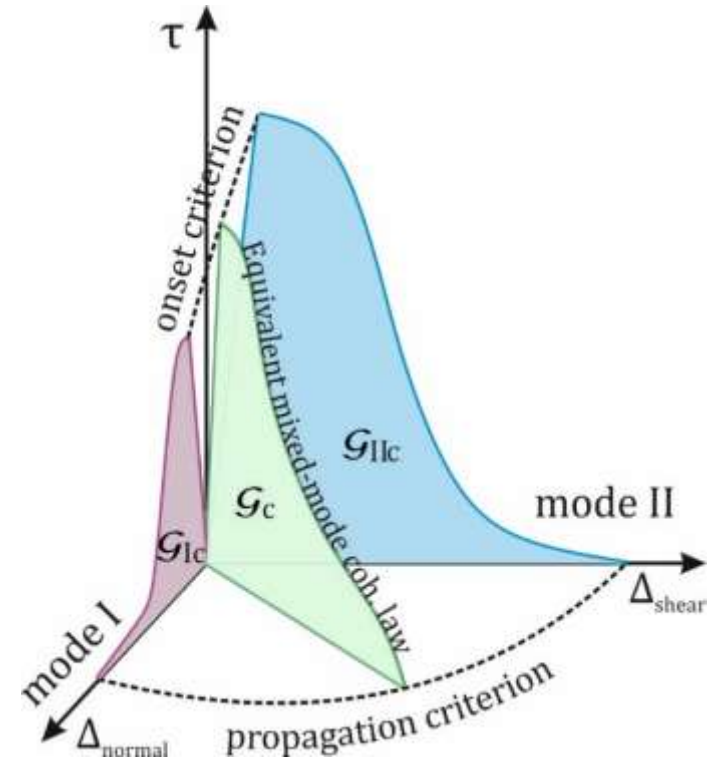
Complex scenarios, damage interaction/load redistribution
 → selecting lower input values not necessary means being more conservative

Input properties for my fem model?



+ CL shape

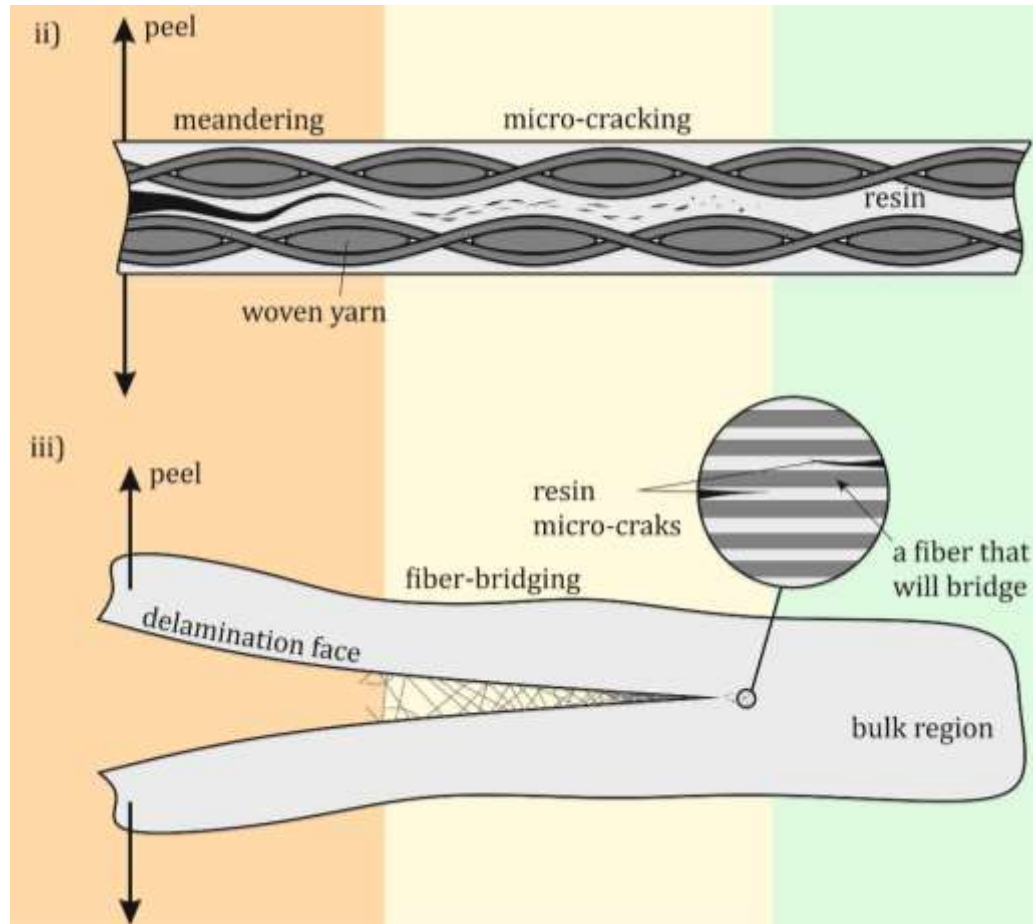
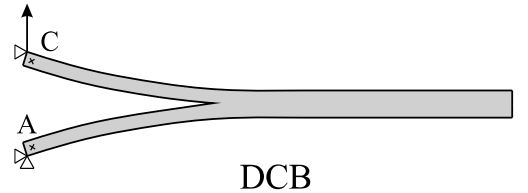
Cohesive law!



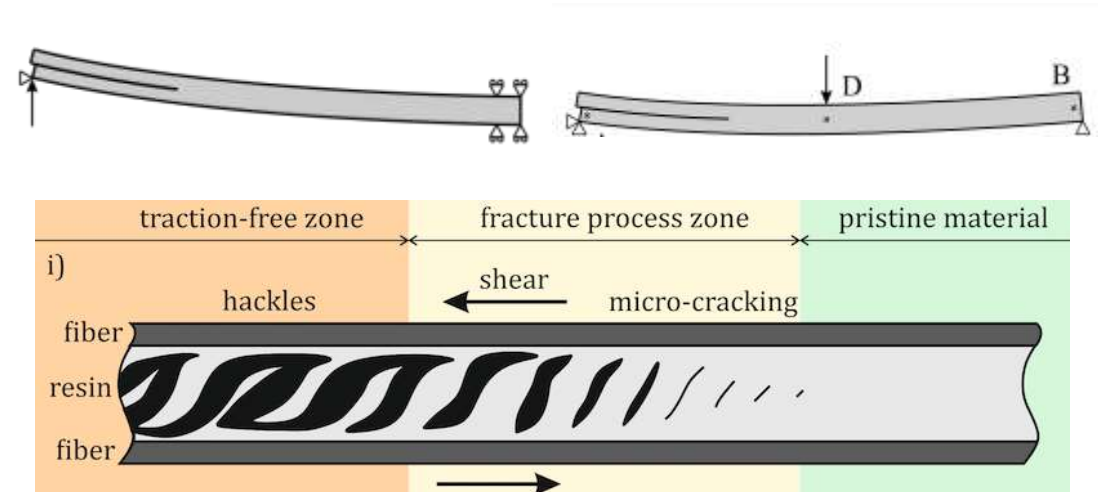
5+1 parameters:
 G_{Ic} , G_{IIc} , τ_3 , τ_{sh} , η , k

Mechanics of delamination onset and propagation

□ Micromechanical point of view



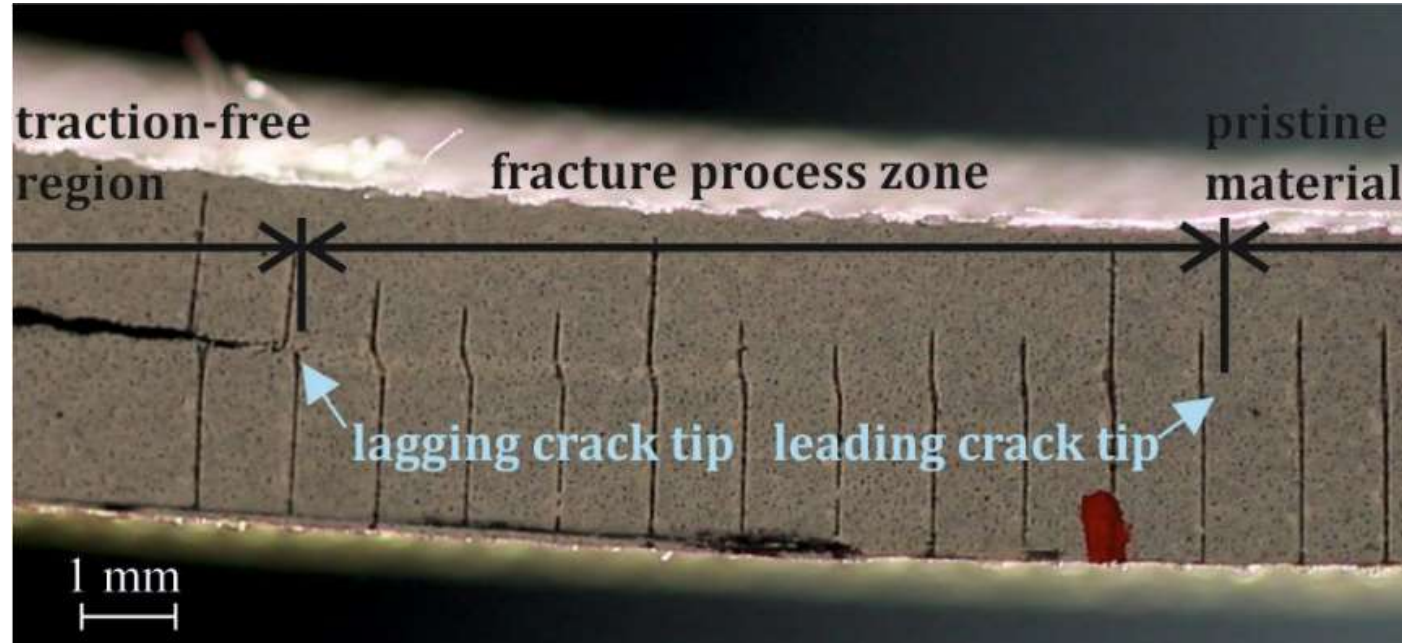
- sequence of different failure events (damage mechanisms) occurring at the microscopic level



Mechanics of delamination onset and propagation

□ Macroscopic (mesoscale) point of view

→ all the failure processes occur in a region called a Fracture Process Zone (FPZ)

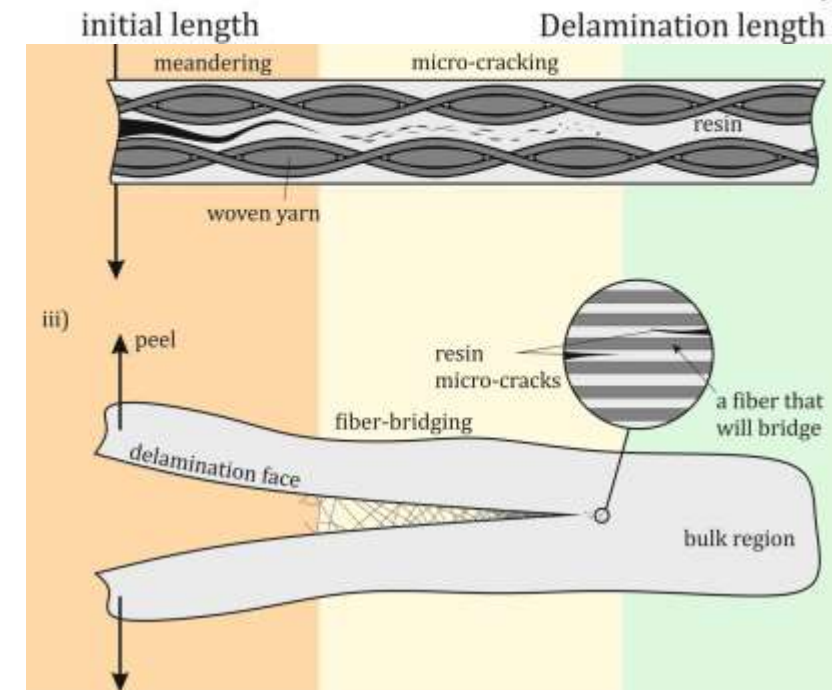
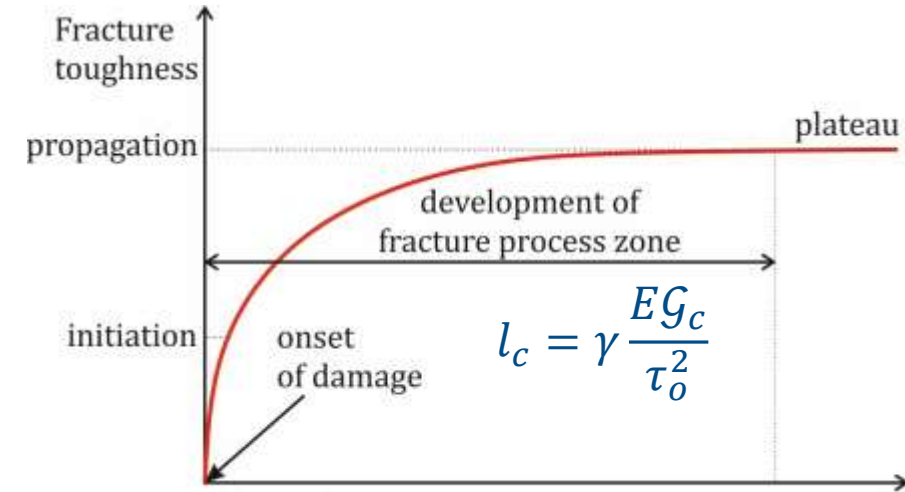


The FPZ is bound by the “lagging” crack tip, i.e., the limit point where the interface is not able to withstand any traction (stress free region), and the “leading” crack tip, i.e., the limit point where the interface in the pristine material is starting to degrade)

Mechanics of delamination onset and propagation

□ R-Curve

- The combined effect of the various micromechanical damage mechanisms is a fracture toughness that increases as the FPZ develops → R-curve.
- R-curve starts with the onset of early degradation processes (onset of damage) and converges to a plateau value (propagation toughness).
- The more convoluted the microscopic crack path, together with the presence of bridging elements or other blunting mechanisms, the higher the toughness for propagation.
- When the effective toughness reaches the plateau value, the FPZ is completely developed, and the delamination starts to propagate in a self-similar manner.

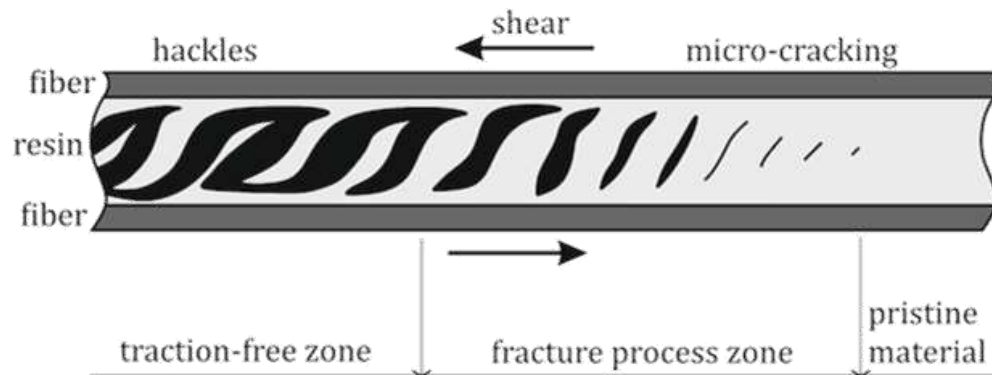


Mechanics of delamination onset and propagation

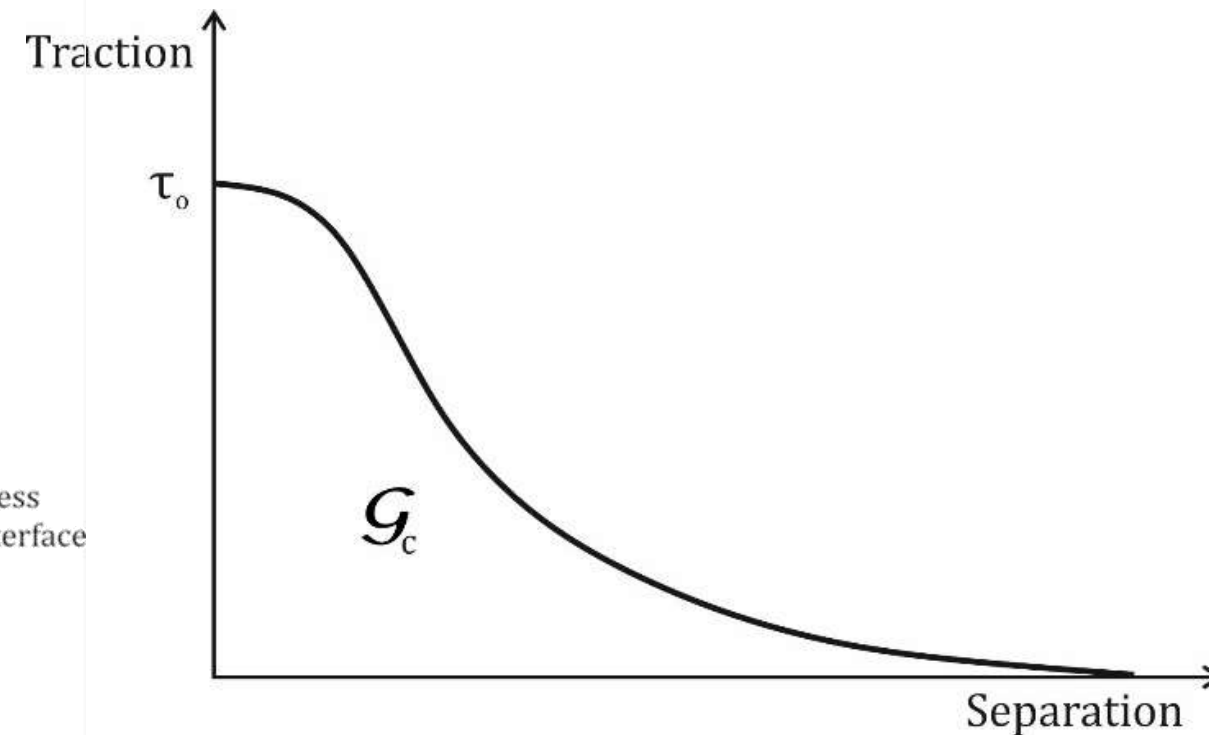
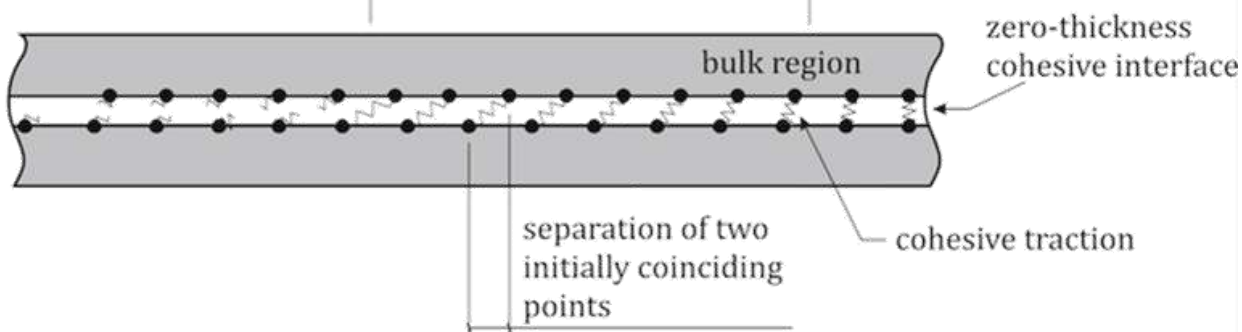
“all the material deformation and degradation of the mechanical properties due to microscopic failure processes can be lumped into a surface”

Cohesive zone model approach

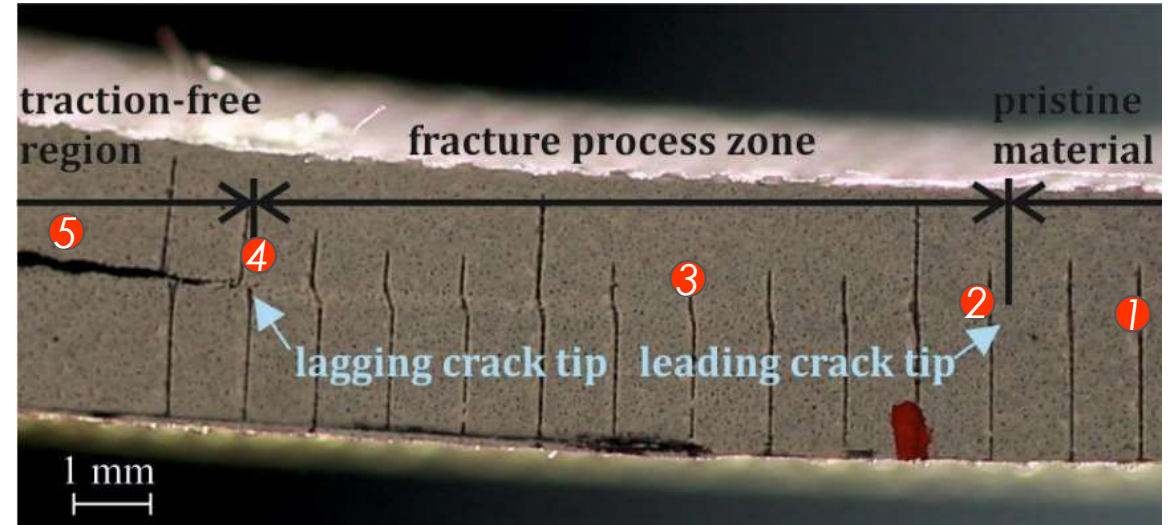
Physical failure process



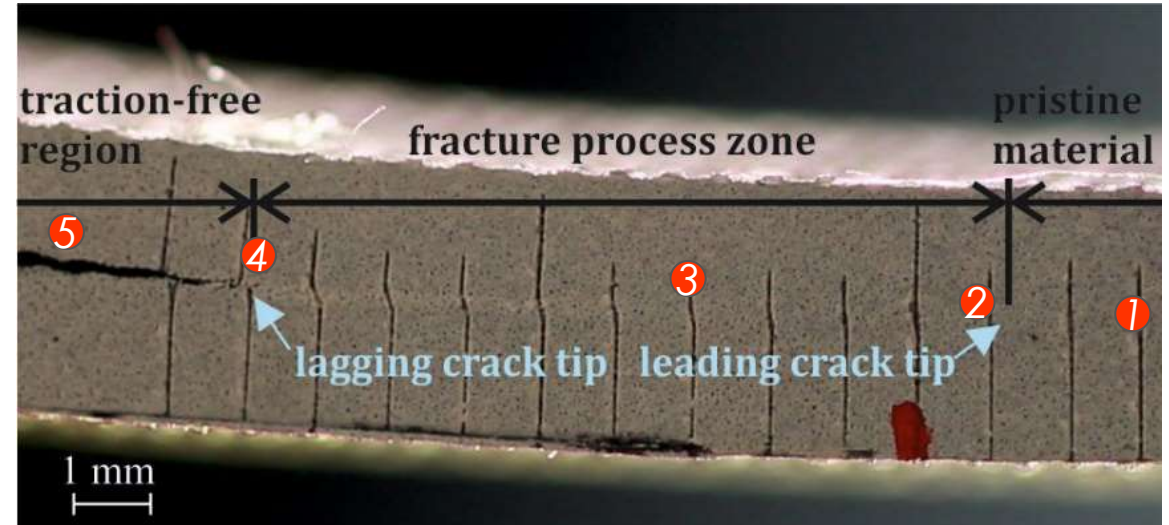
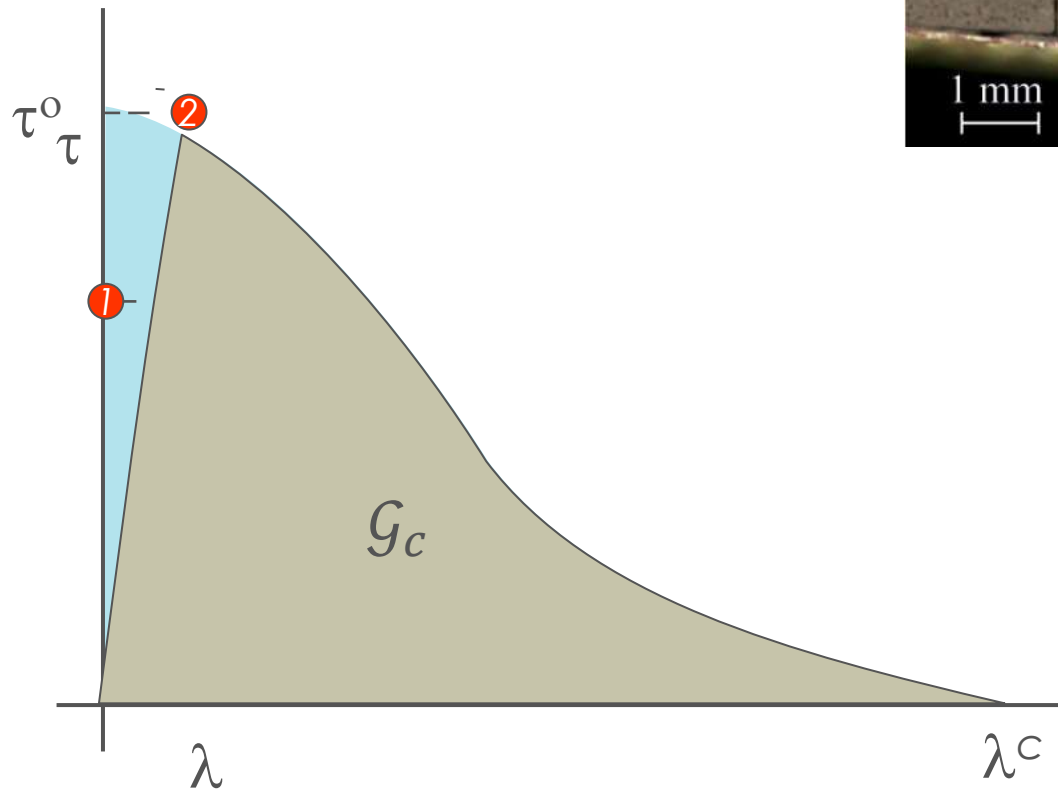
Cohesive zone modelization



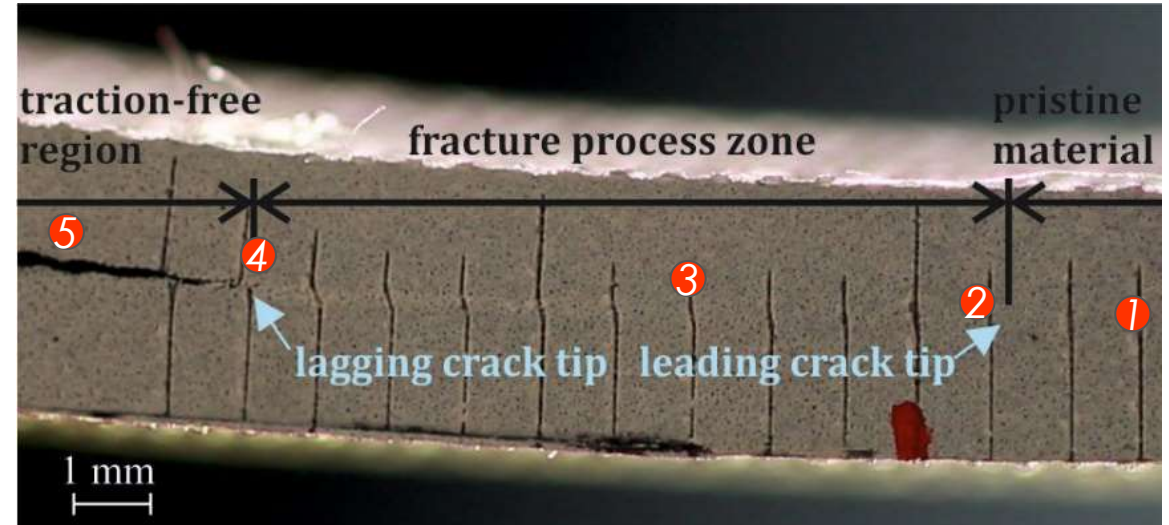
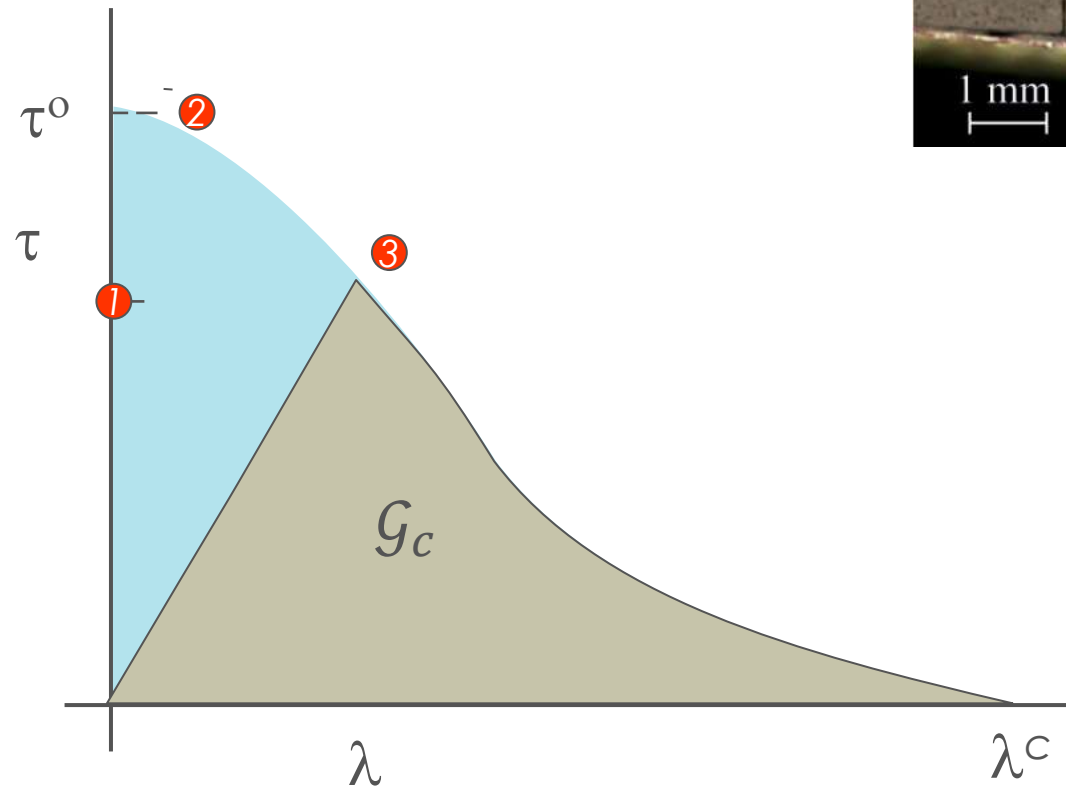
■ Cohesive zone model approach



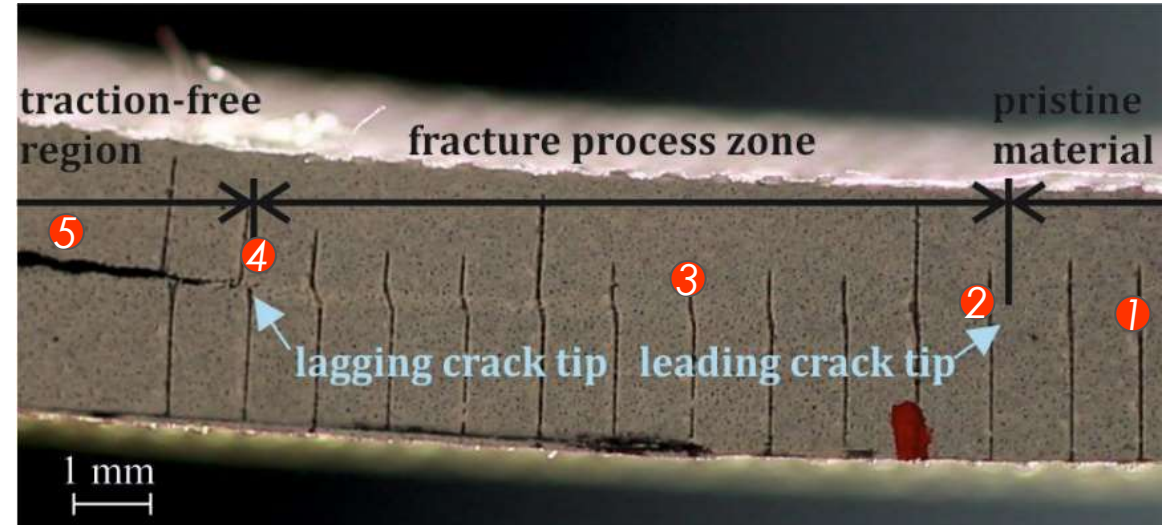
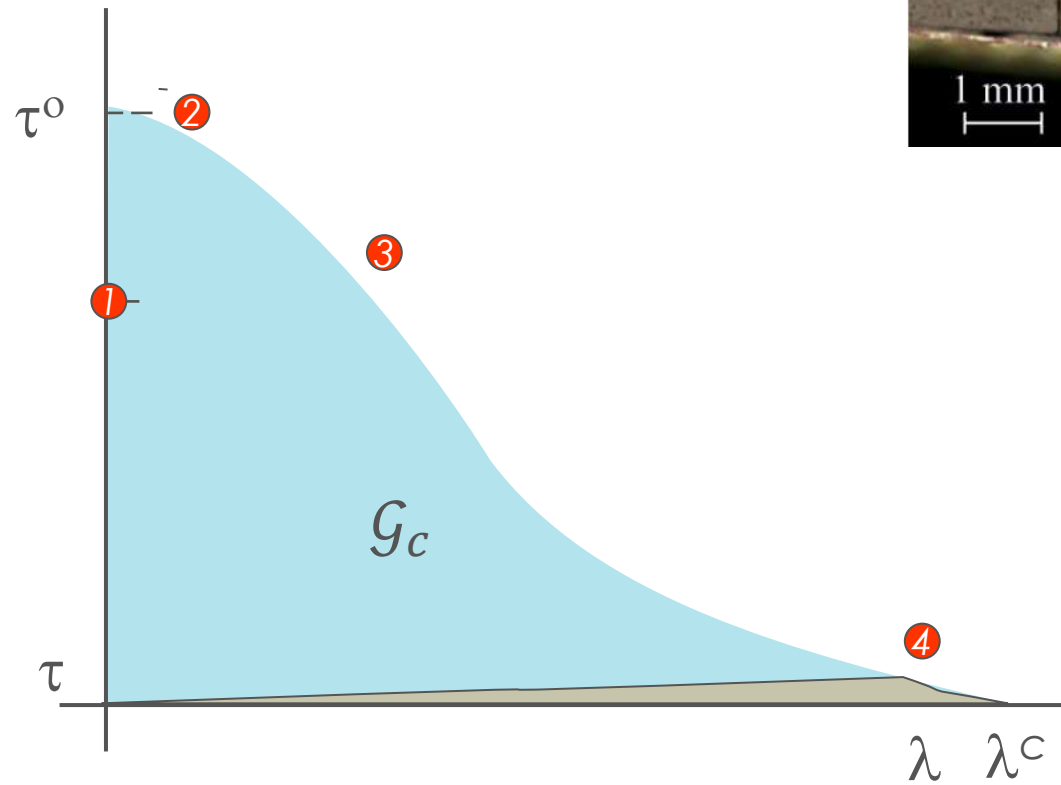
■ Cohesive zone model approach



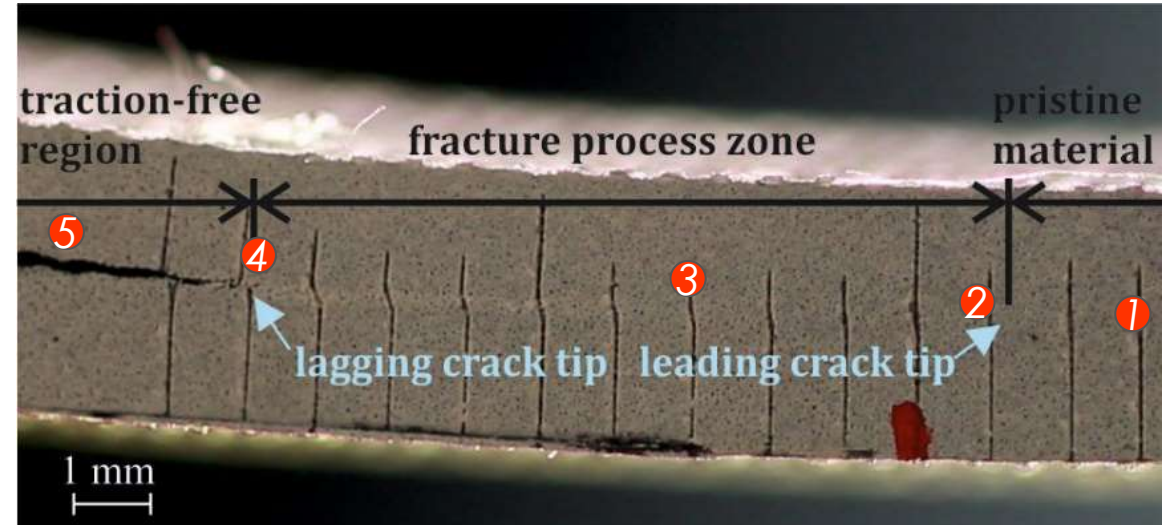
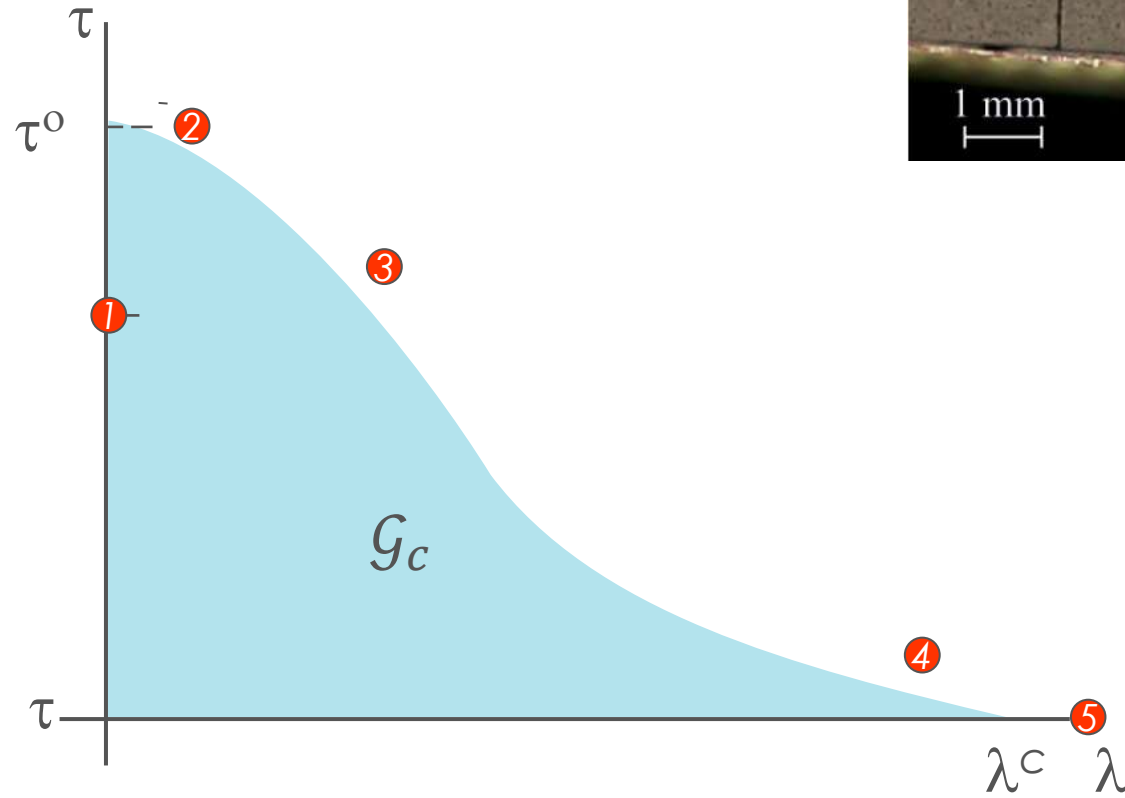
■ Cohesive zone model approach



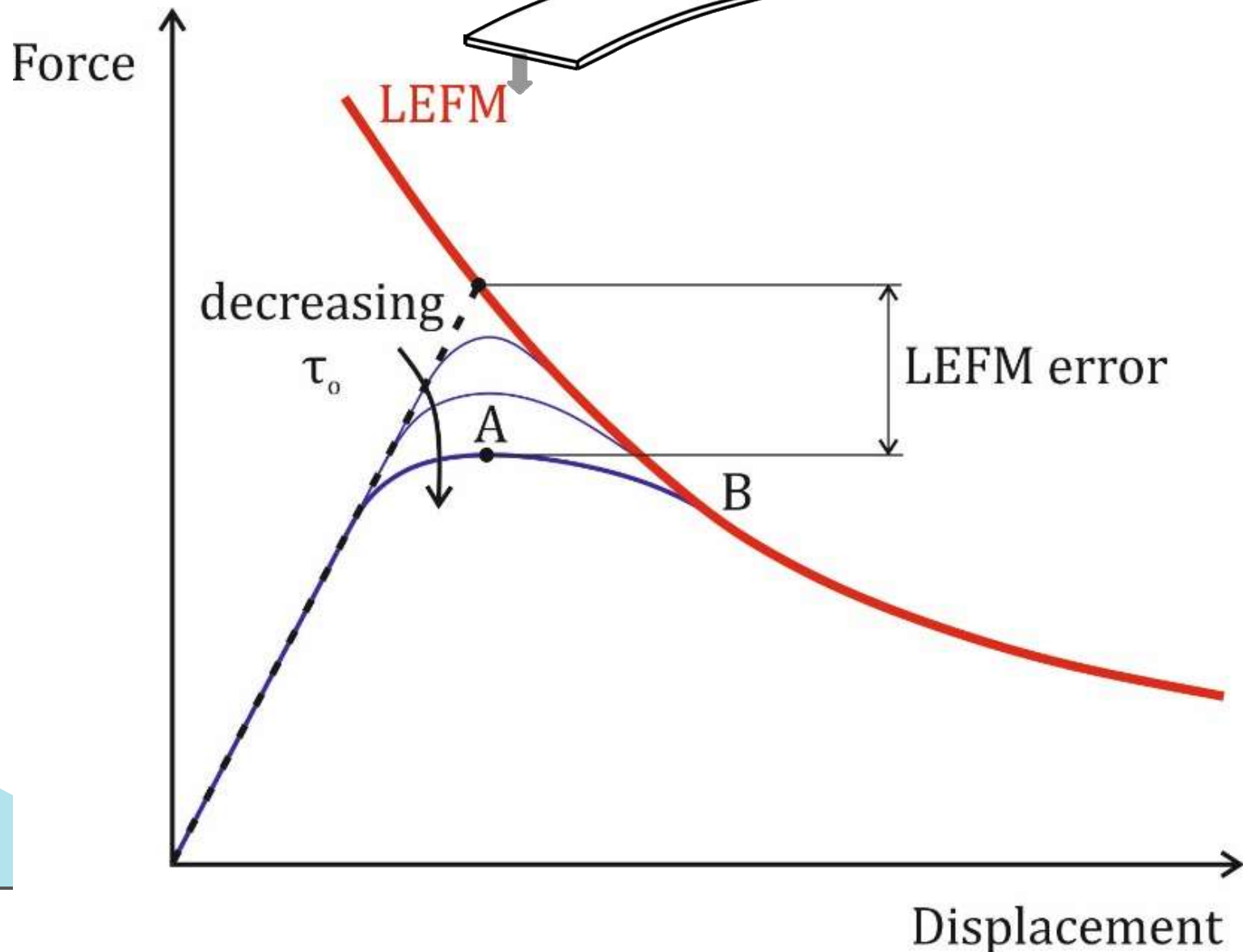
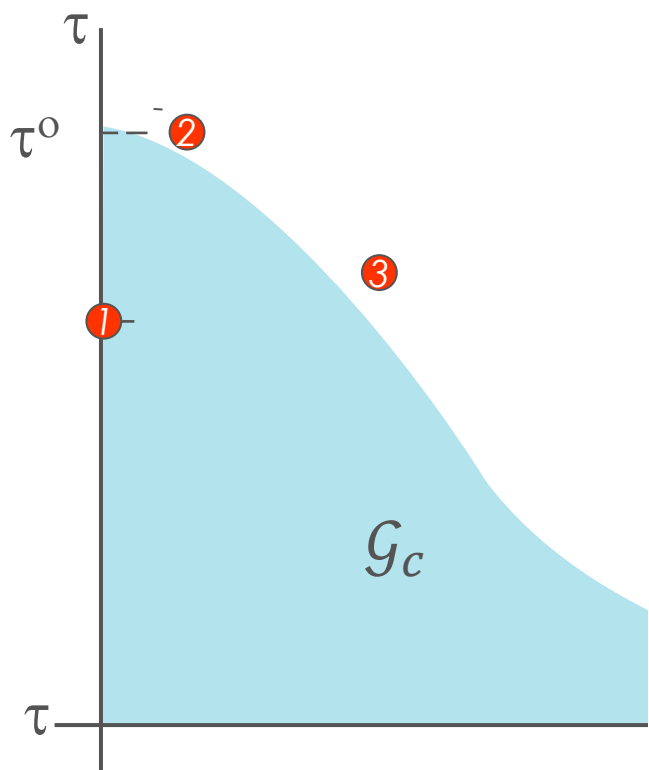
■ Cohesive zone model approach

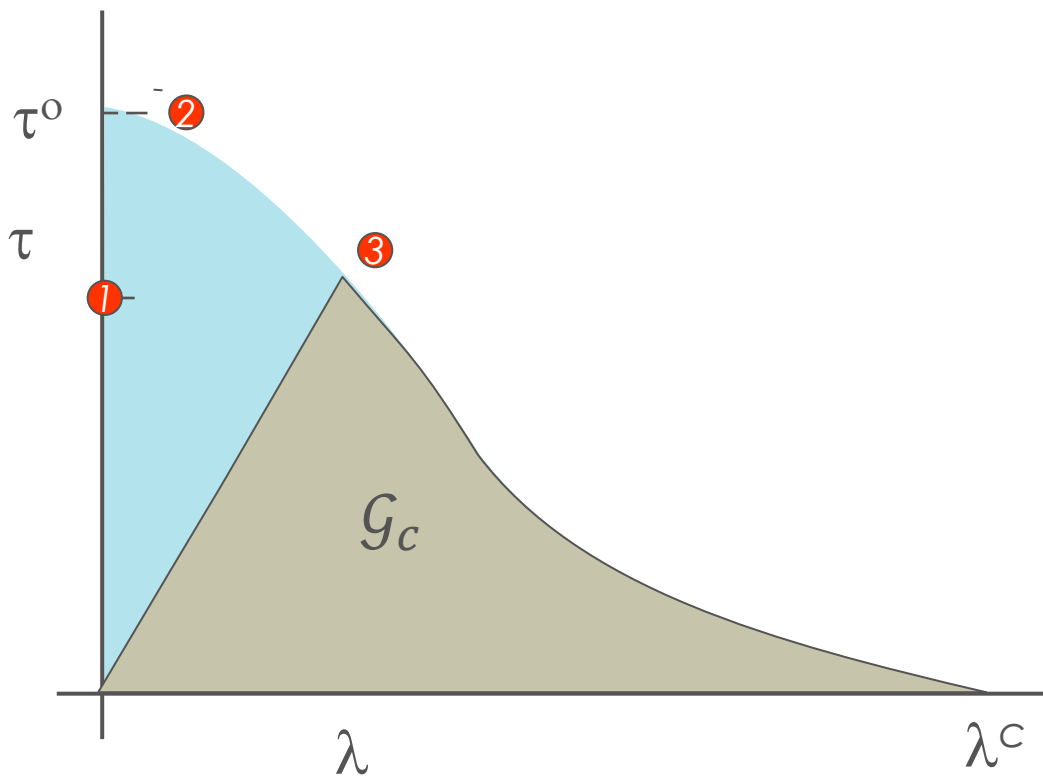
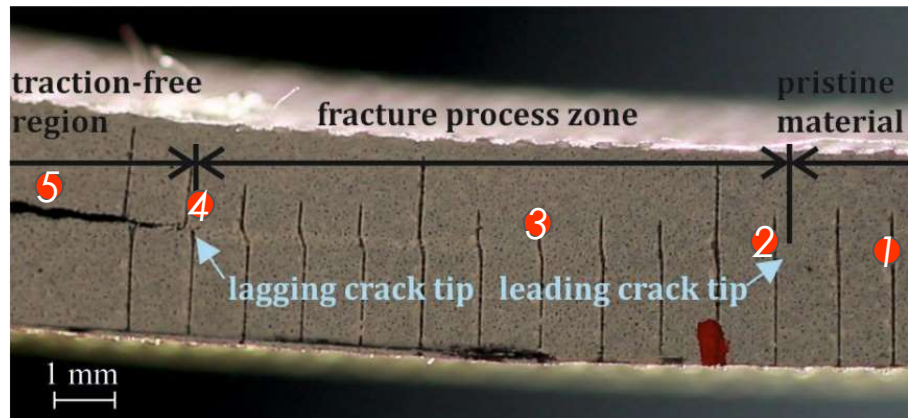


■ Cohesive zone model approach

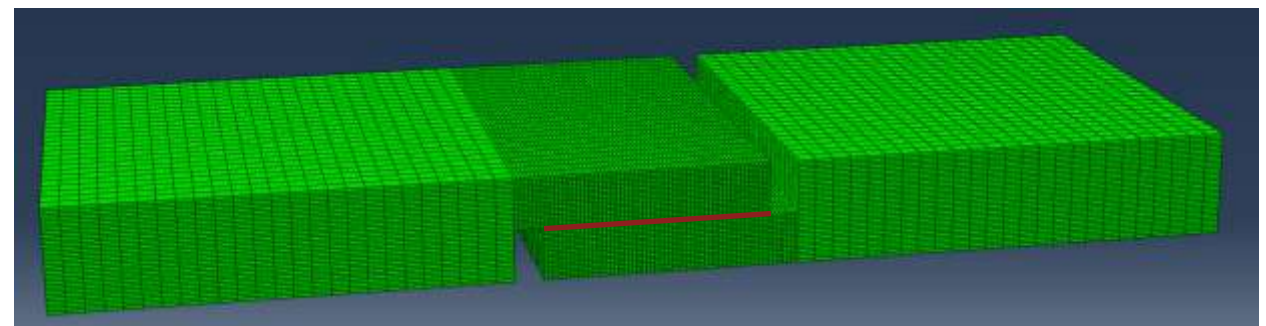
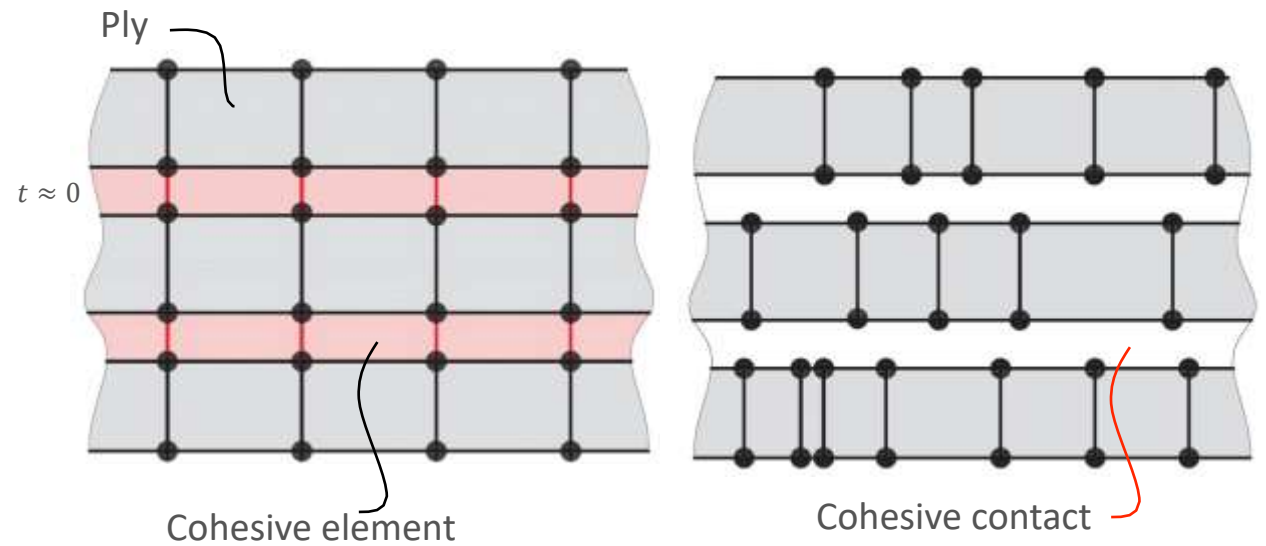


▣ Cohesive zone model approach





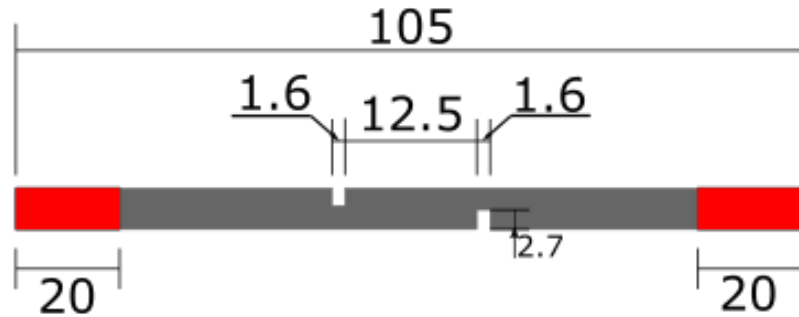
FEM Implementation



Does it work?

→ Single Lap Shear example

▣ Dimensions of the specimen

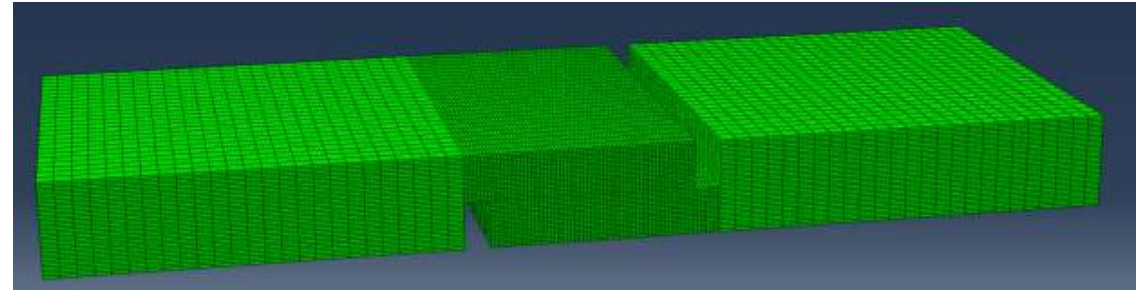


- Width = 25 mm

▣ Lay-up

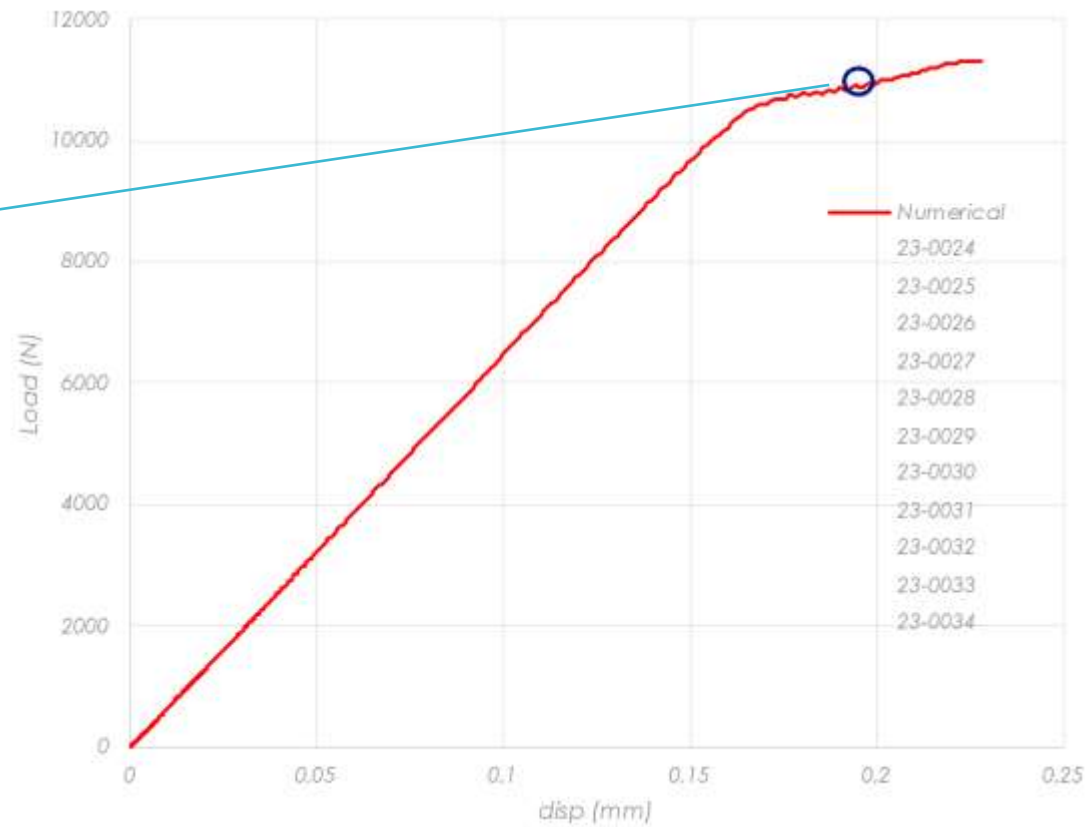
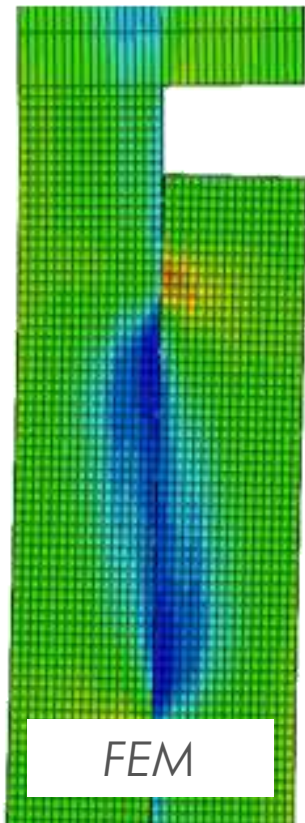
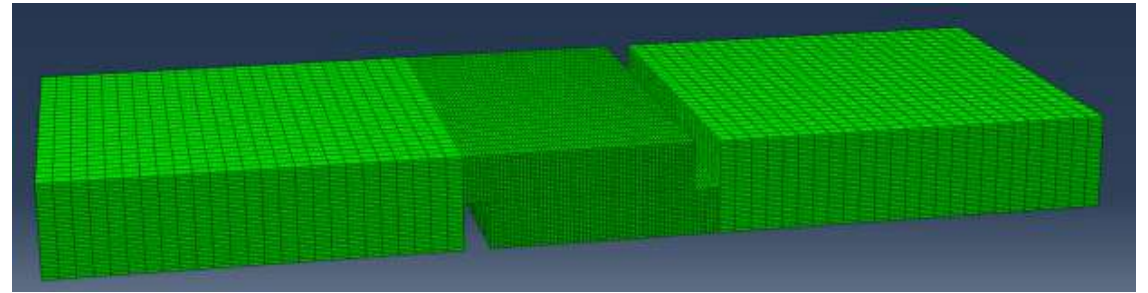
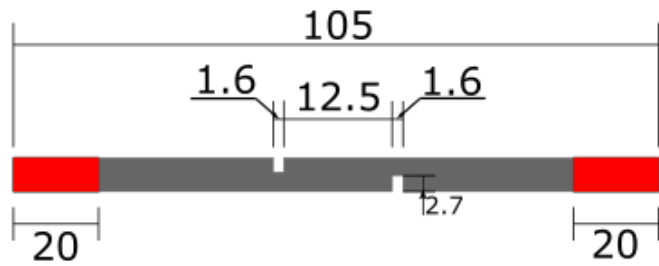
- 16 plies per arm, $[0/45/90/-45]_2s$
- Thickness per arm $0.165 \times 16 = 2.64$ mm (experimentally measured)

▪ Numerical Model



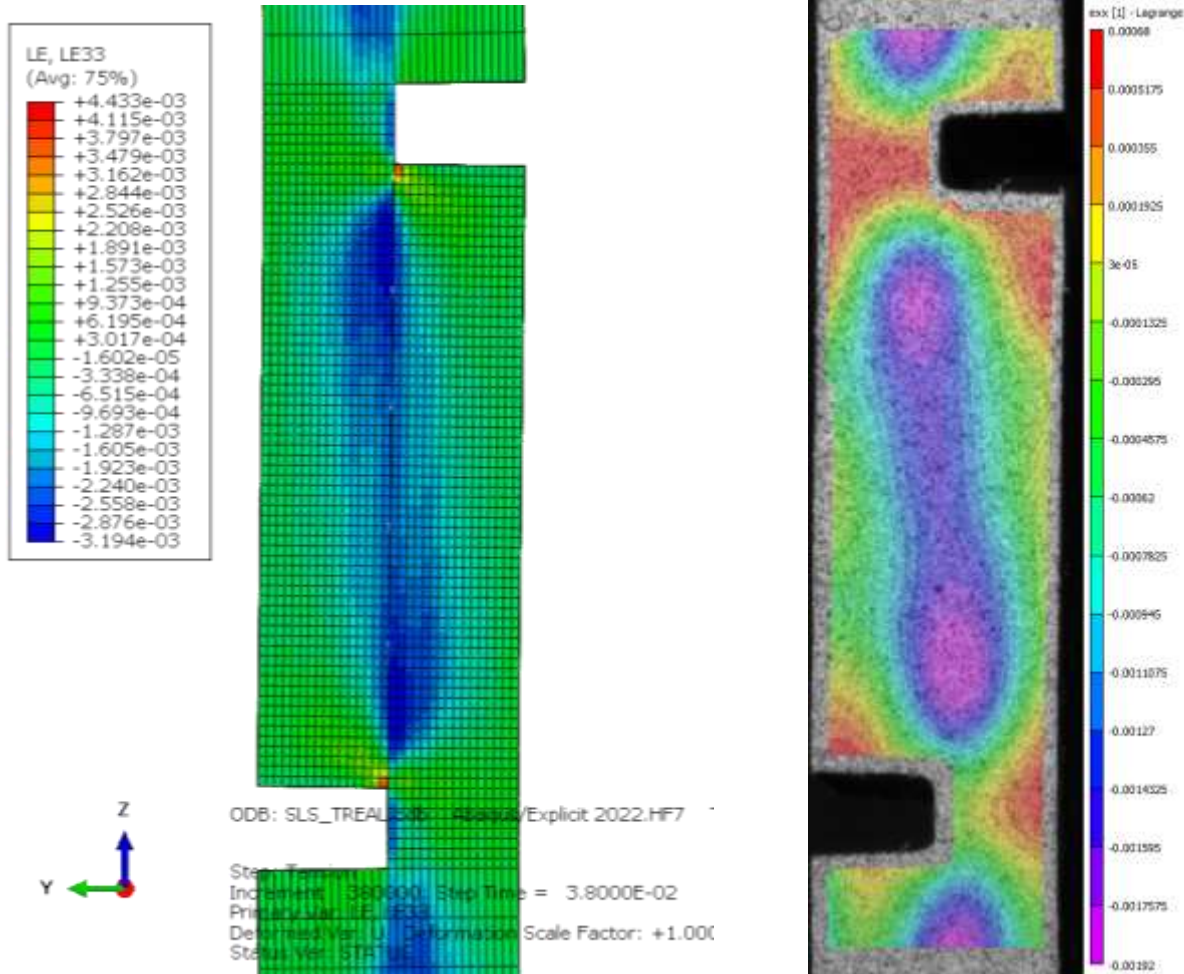
- Solid Elements (plies)
 - 0.2 mm in the fiber direction
 - Thickness = 2 plies per element
- Cohesive Element size
 - 0.2 mm in the fiber direction
 - VUMAT

Example: Single Lap Shear

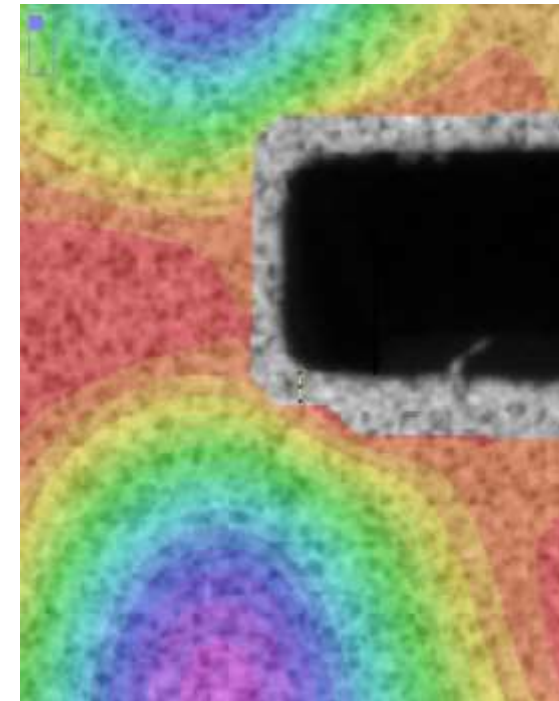


Example: Single Lap Shear

Specimen 23-0032 Picture 113

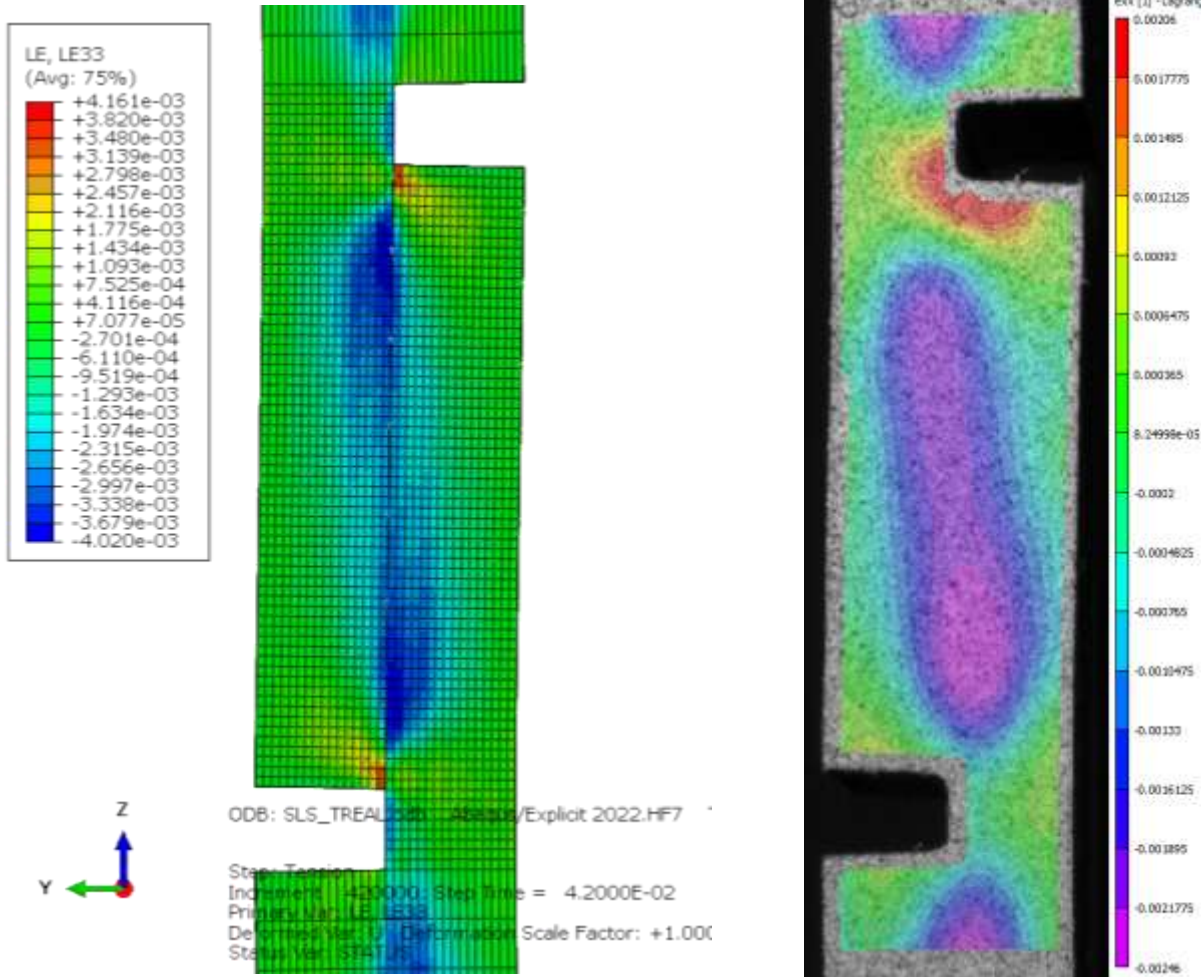


Magnitude	Numerical	23-0026
Load (N)	8149	8150
Displacement (mm)	0.1285	0.1220
Crack grow (mm)	0	0.200

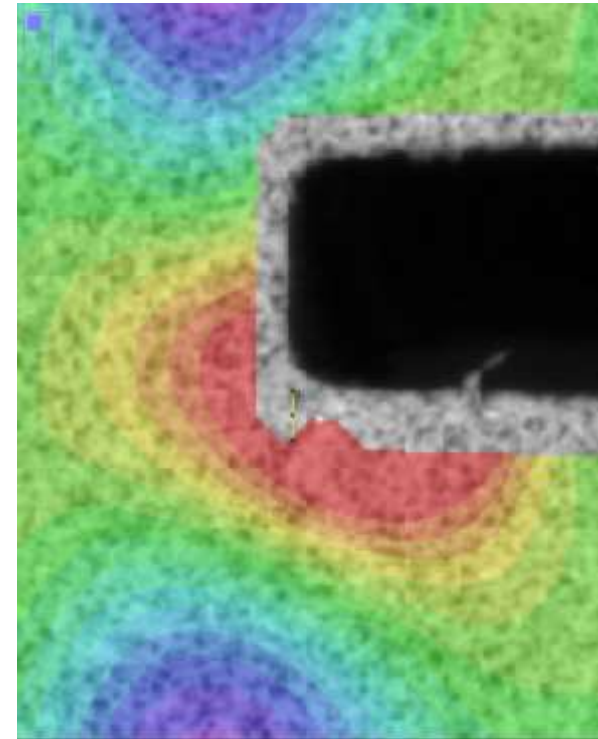


Example: Single Lap Shear

Specimen 23-0032 Picture 150

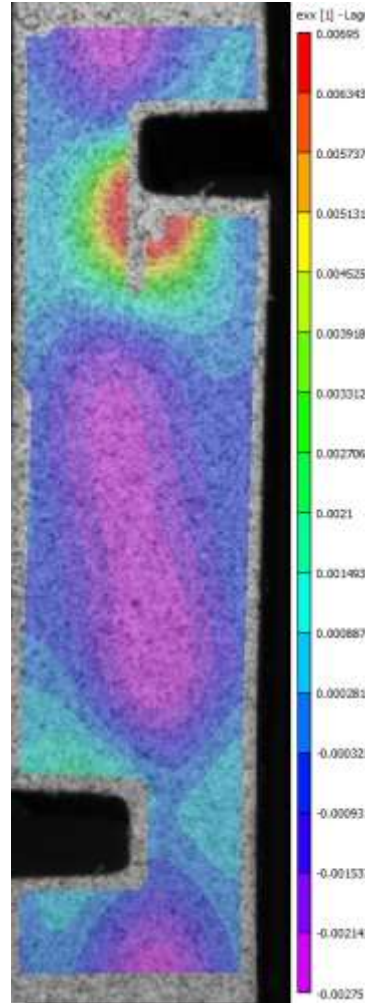
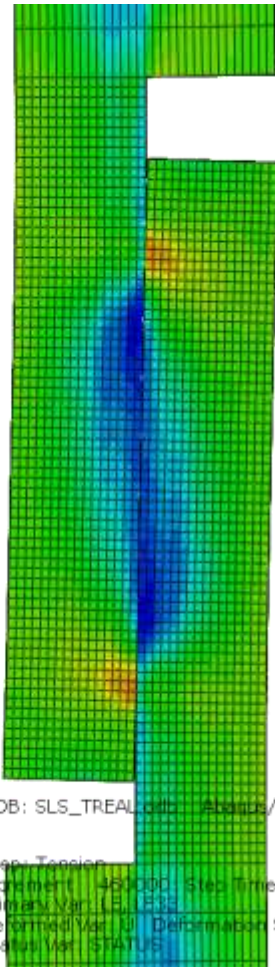
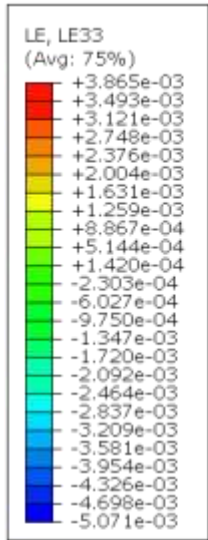


Magnitude	Numerical	23-0026
Load (N)	10046.2	10045.3
Displacement (mm)	0.1541	0.1545
Crack grow (mm)	0	0.36

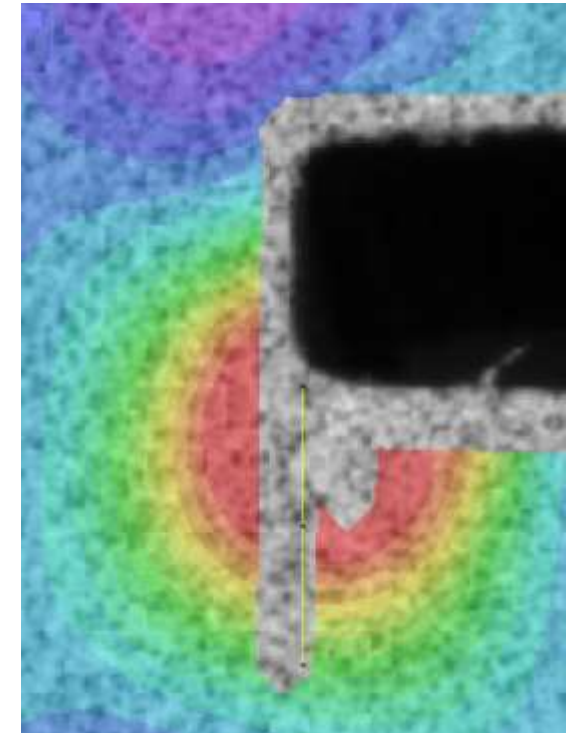


Example: Single Lap Shear

Specimen 23-0032 Picture 174

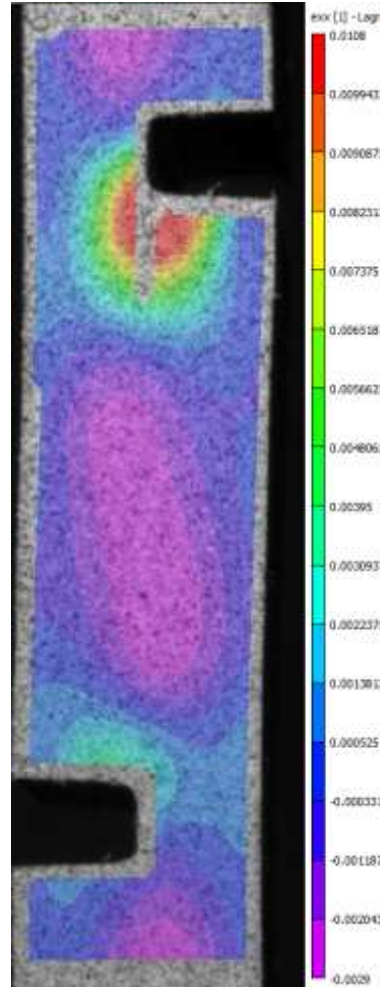
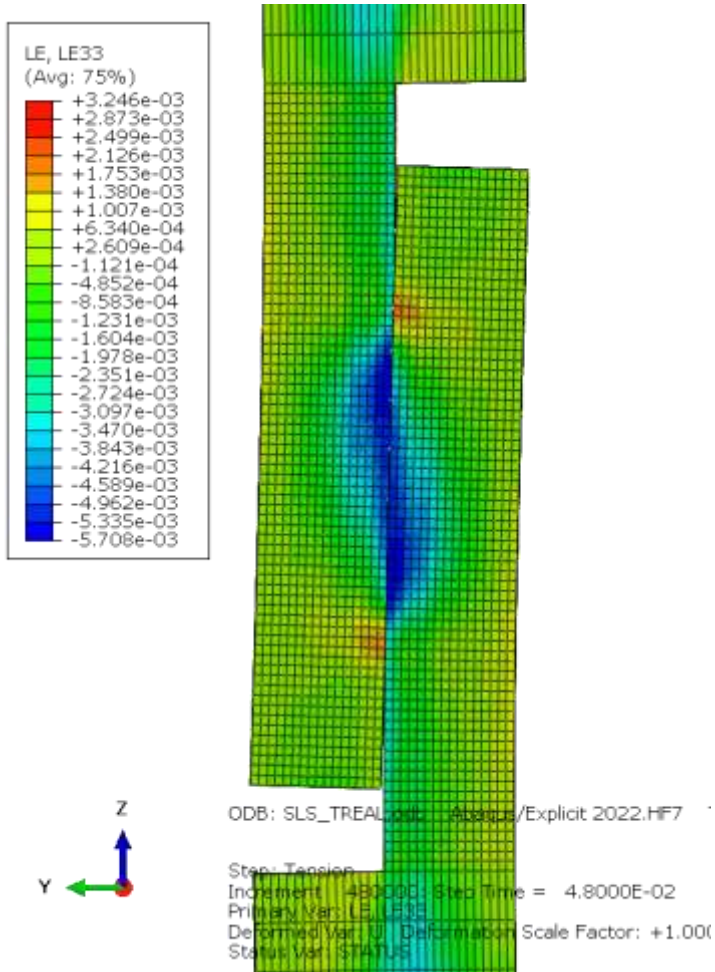


Magnitude	Numerical	23-0026
Load (N)	10892.9	10892.2
Displacement (mm)	0.1951	0.1772
Crack grow (mm)	1.411	1.808

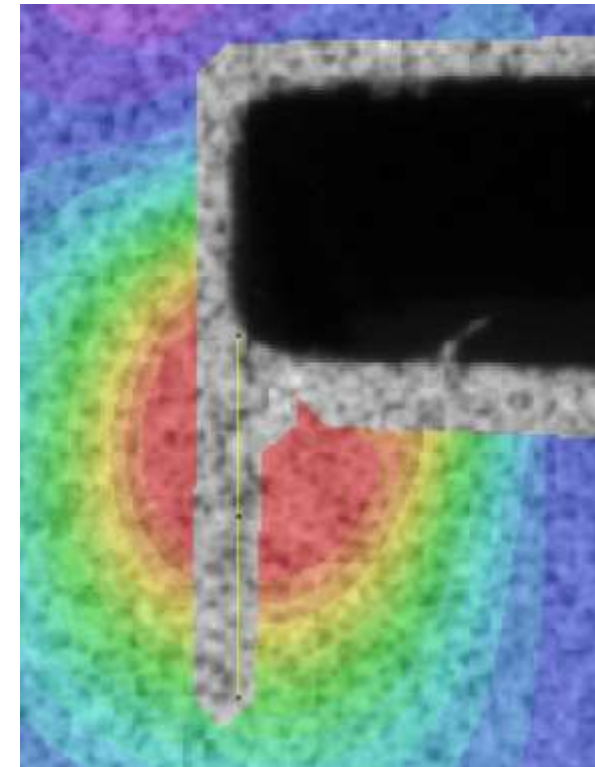


Example: Single Lap Shear

Specimen 23-0032 Picture 186

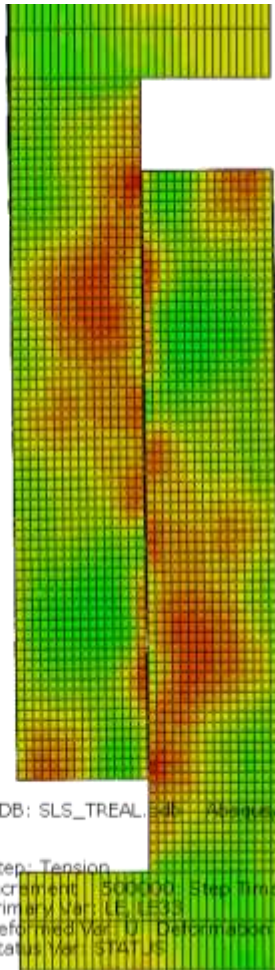
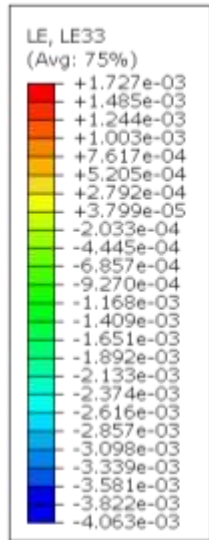


Magnitude	Numerical	23-0026
Load (N)	11164.7	11164.6
Displacement (mm)	0.2132	0.1883
Crack grow (mm)	2.217	2.076

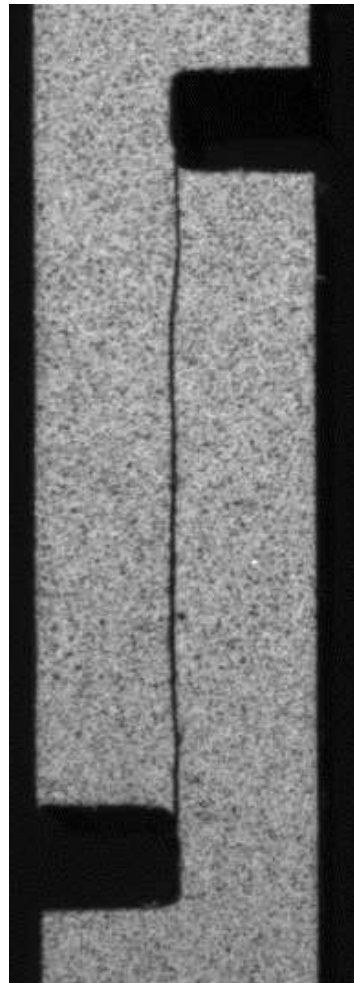


Example: Single Lap Shear

Specimen 23-0032 Picture 203

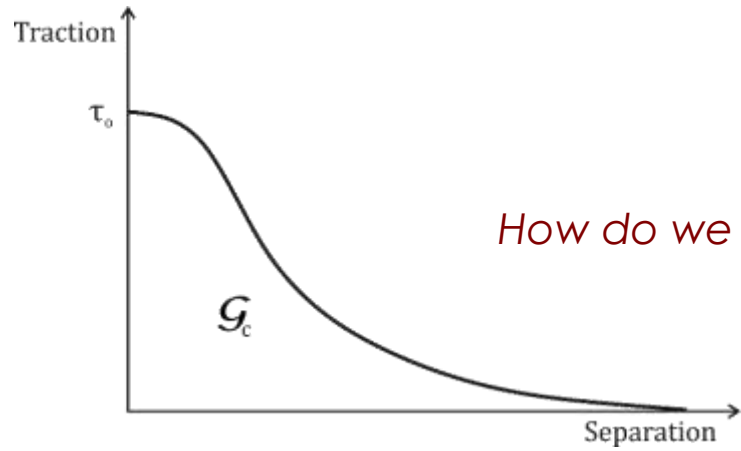


ODB: SLS_TREAL=JL - Abaqus/Explicit 2022.HF7
 Step: Tension
 Increment: 500000; Step Time = 5.0000E-02
 Primary Var: LE, LE33
 Deformed Var: U; Deformation Scale Factor: +1.00
 Status Var: STAT JS



Magnitude	Numerical	23-0026
Max Load (N)	11318.1	11499
Displacement (mm)	0.2269	0.2216
Crack grow (mm)	Open	Open

Shape of the cohesive law



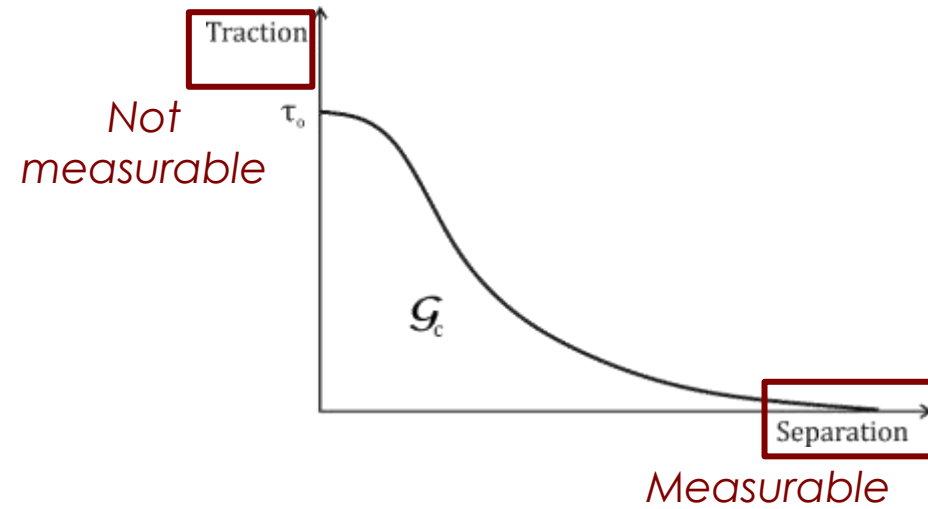
How do we measure it?

▣ *Direct methods*

▣ *Inverse methods*

Shape of the cohesive law

Direct method



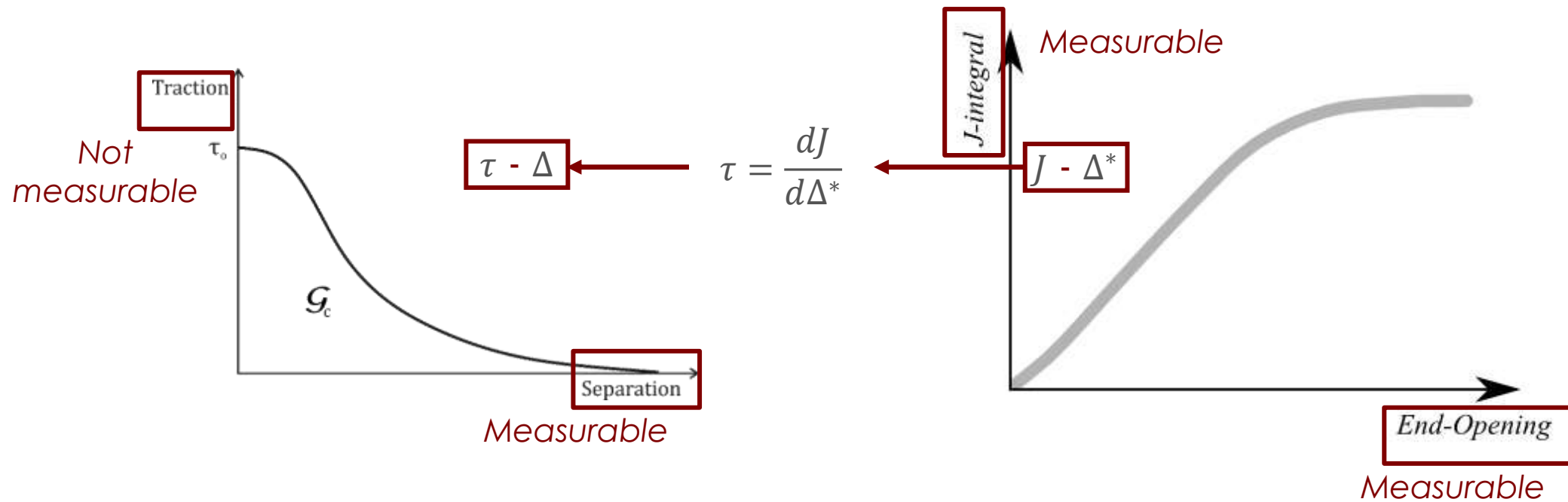
Shape of the cohesive law

Direct method



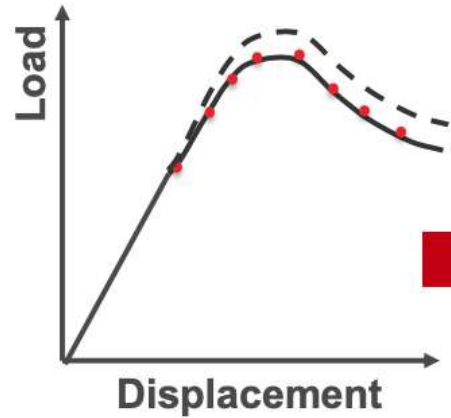
$$J = \int_0^{\Delta^*} \tau(\Delta) d\Delta$$

Sørensen and Jacobsen (2003)

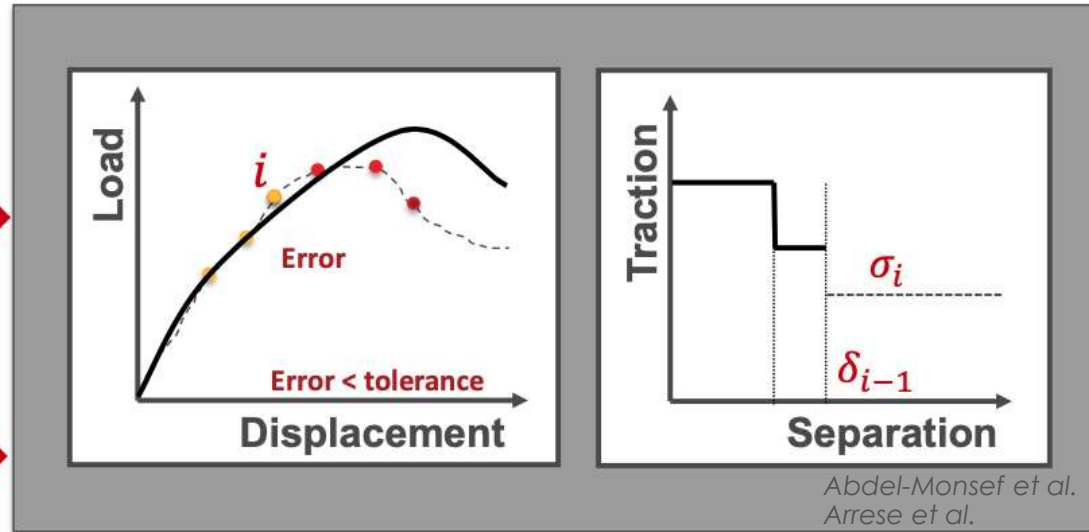


Shape of the cohesive law

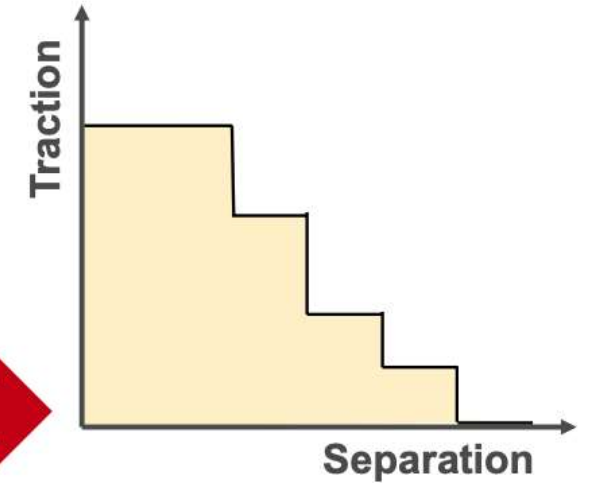
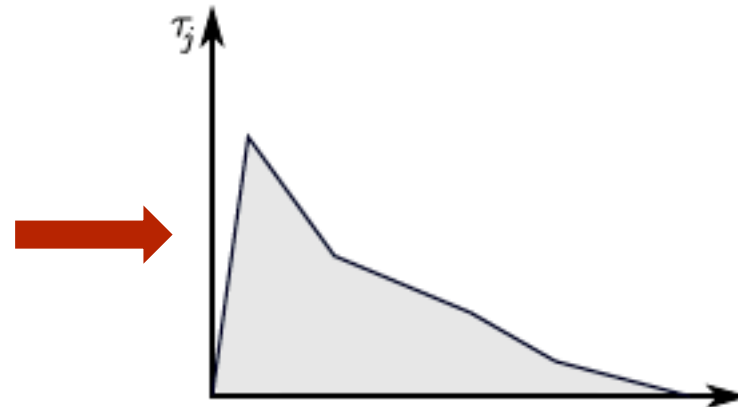
 Inverse method

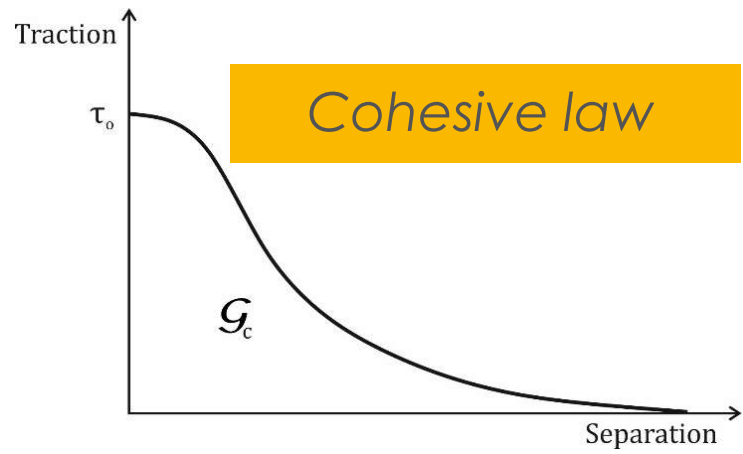


Inverse Method



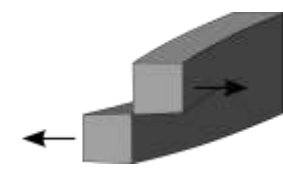
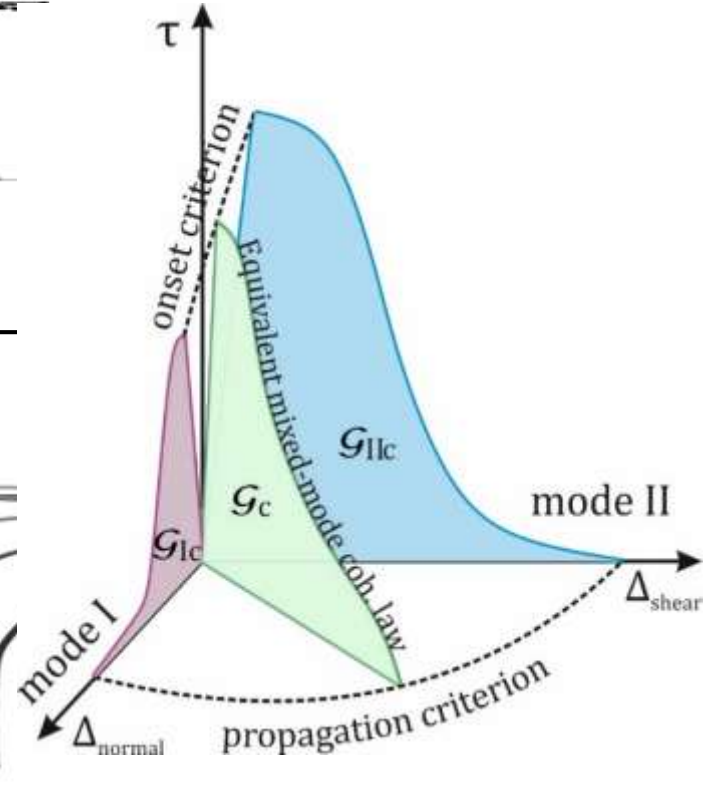
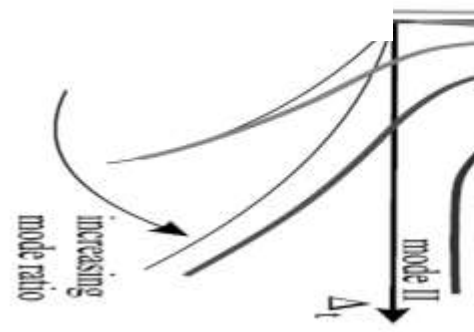
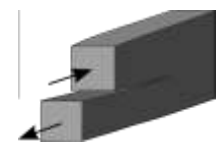
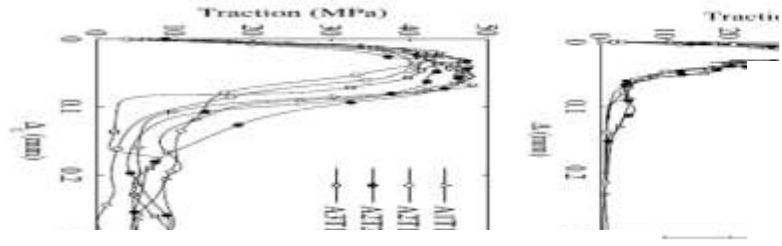
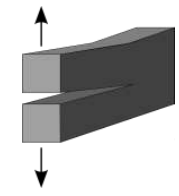
Geometry





- τ_0
- G_c
- *CL shape*

Mode dependent



Cohesive law dependence

Two Epoxy adhesives

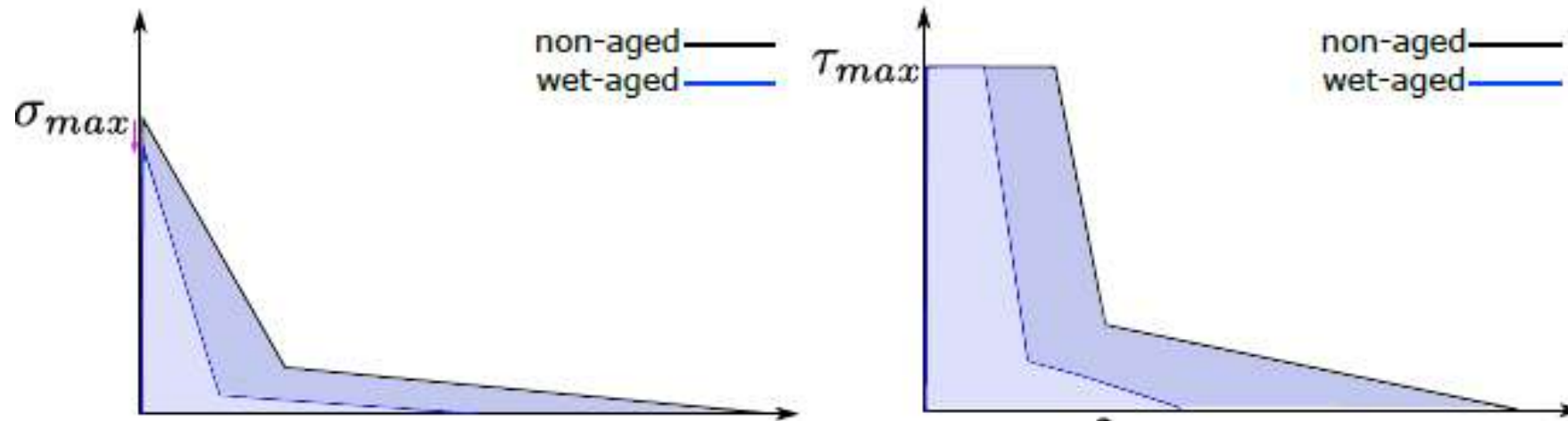
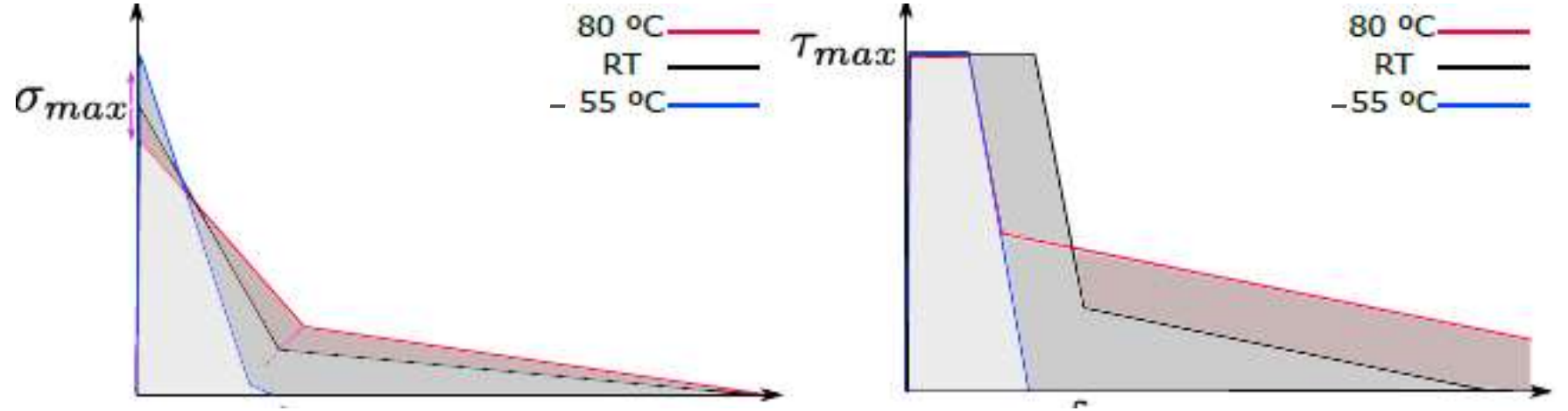
Wet-aged (4 years)/ non-aged

Testing Configuration

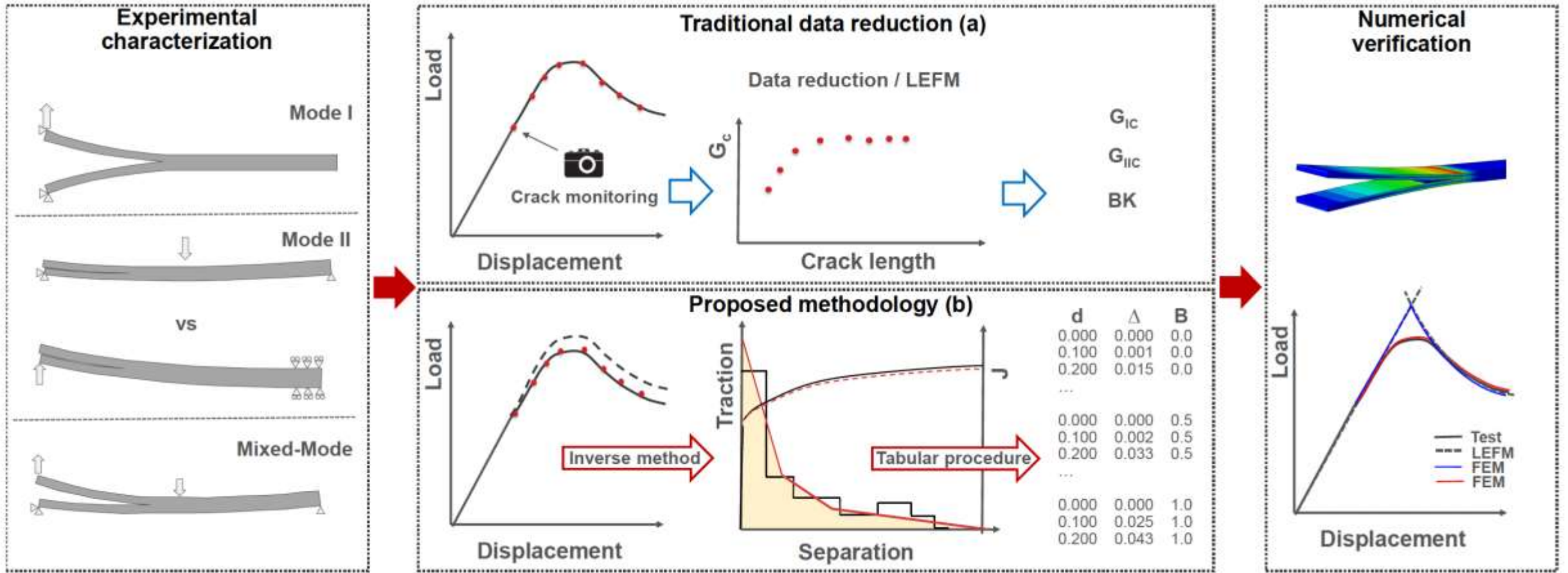
Testing temperature (-55 C, RT , 80 C)



Cohesive law dependence



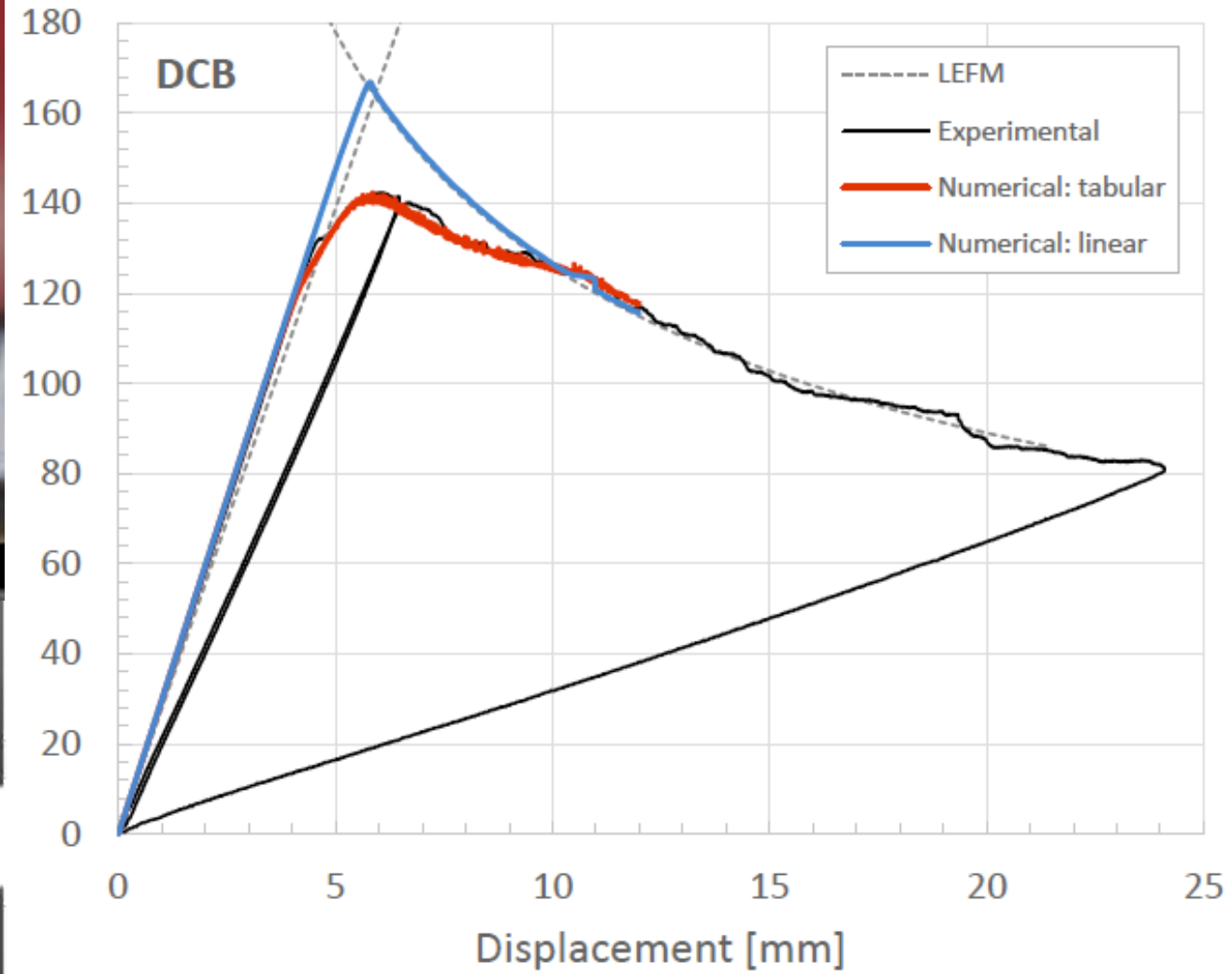
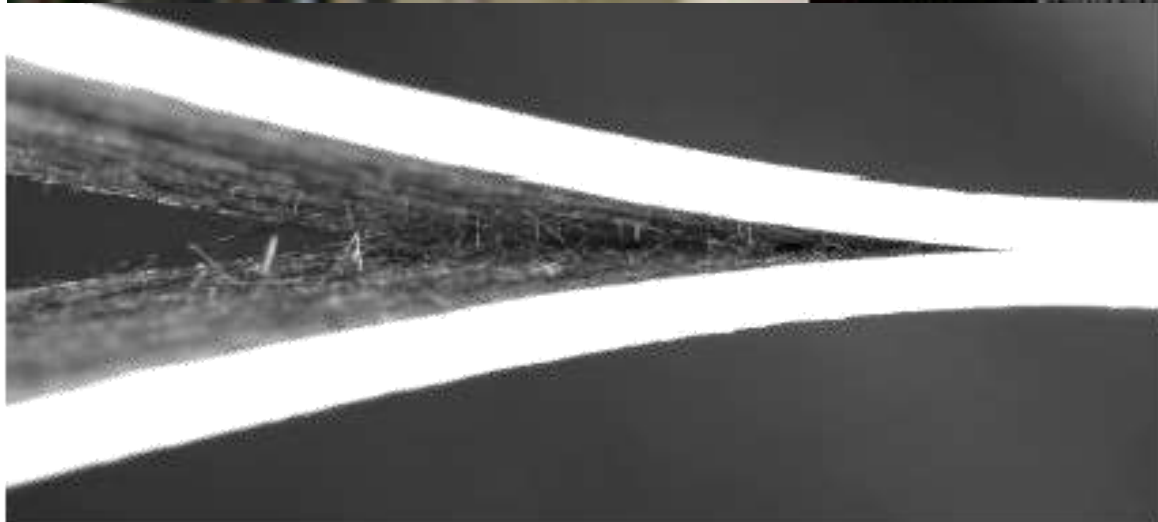
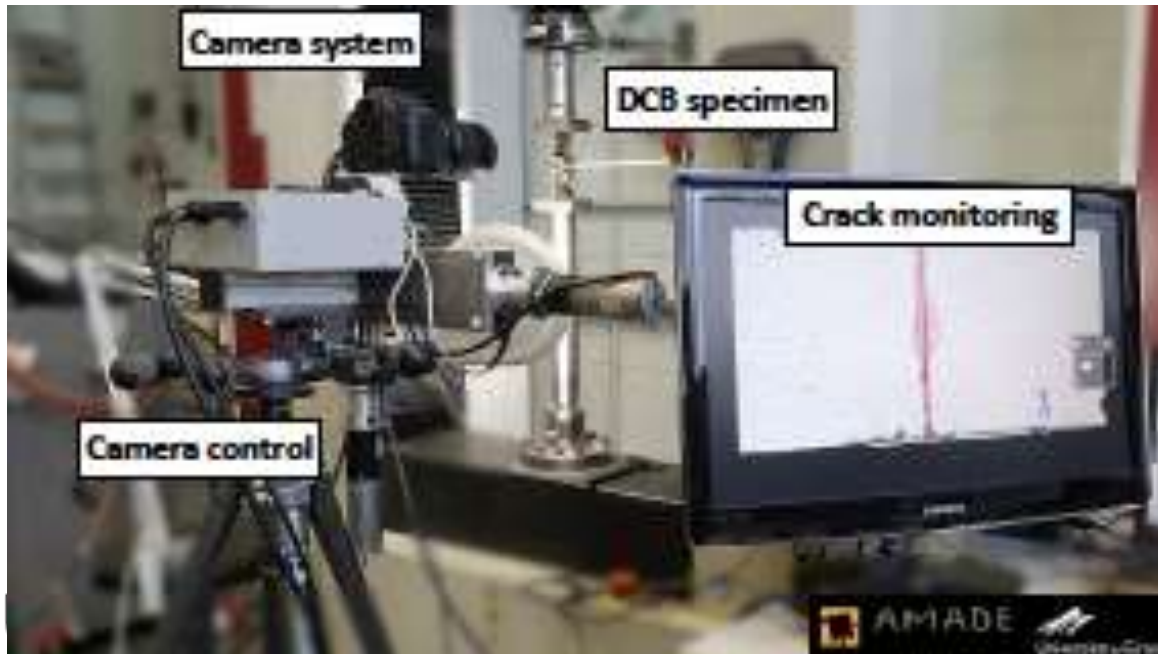
Implementation in FE (Option 1: TABULAR)



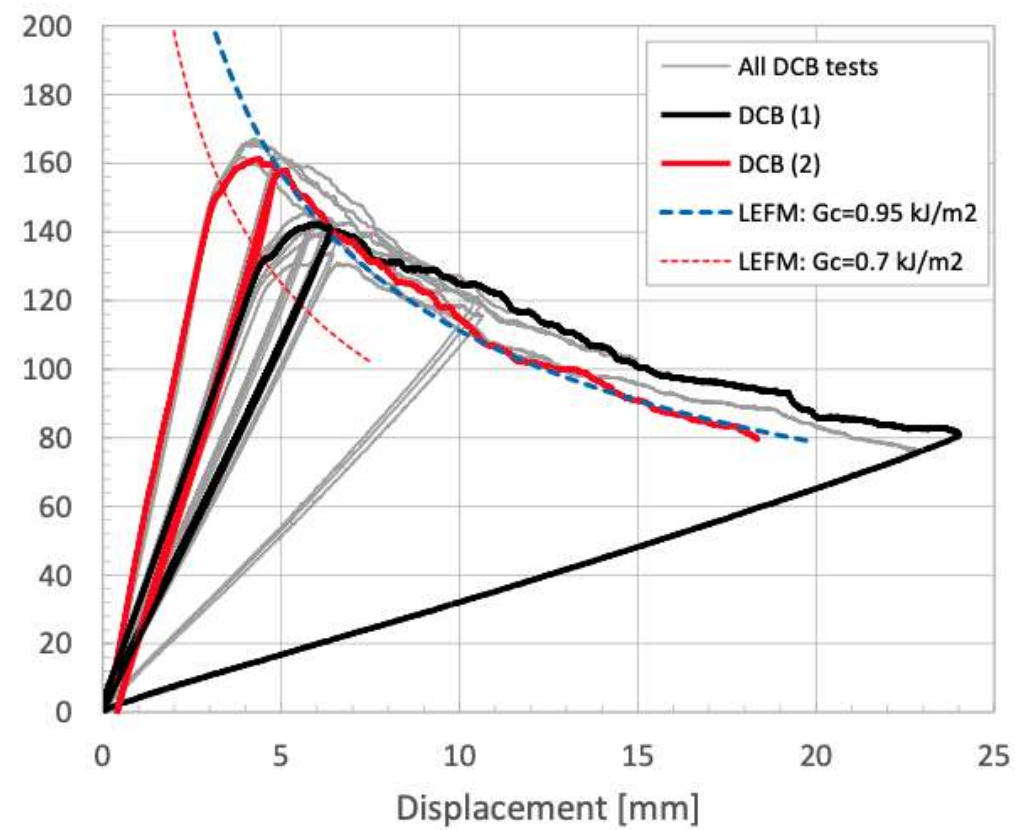
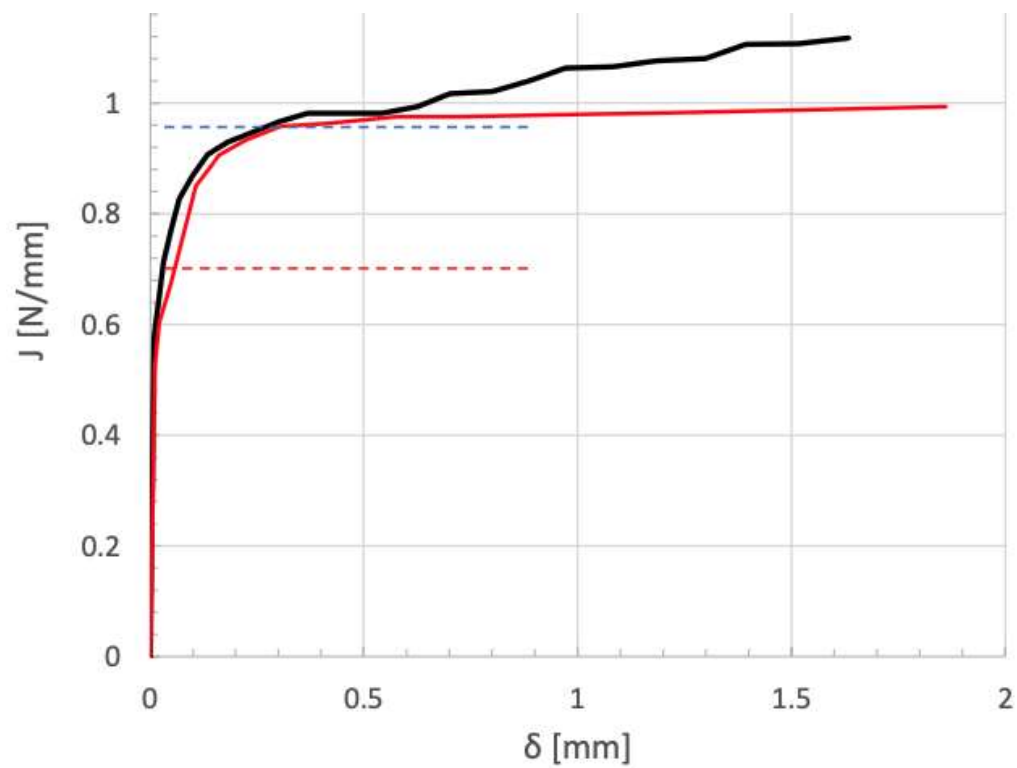
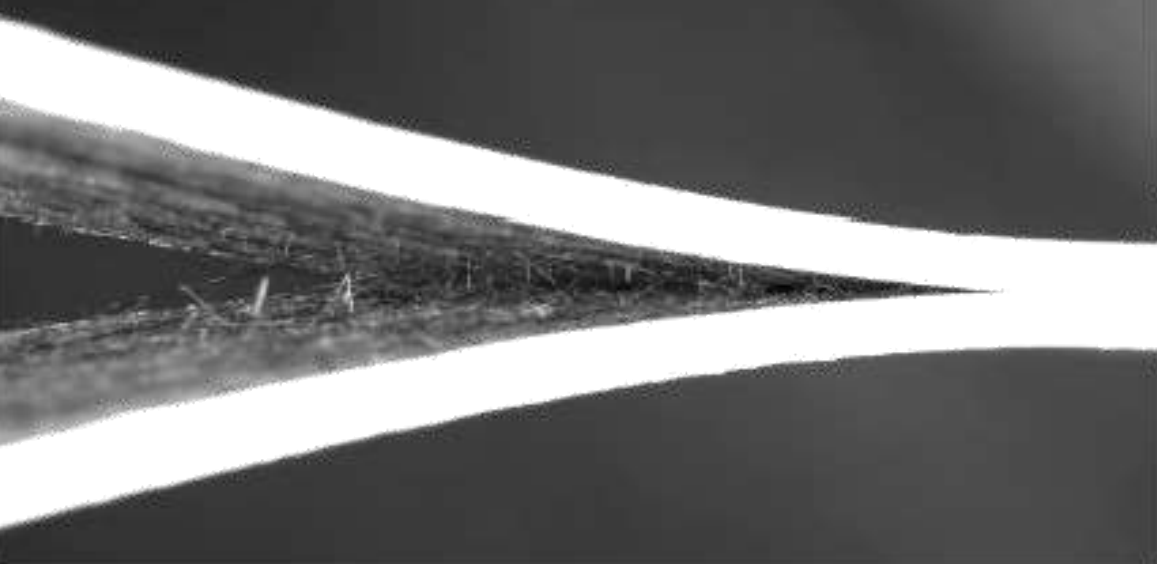
Tijs et al. 2022

Mixed-mode interpolation "managed" by abaqus

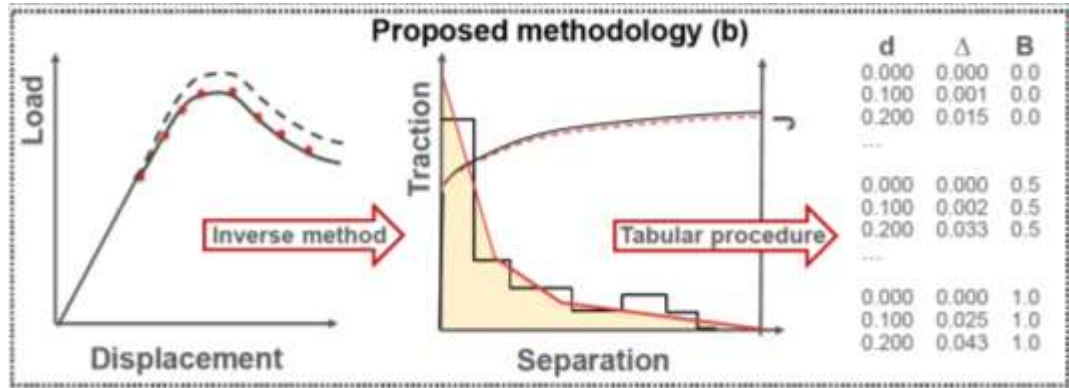
Shape of the cohesive law



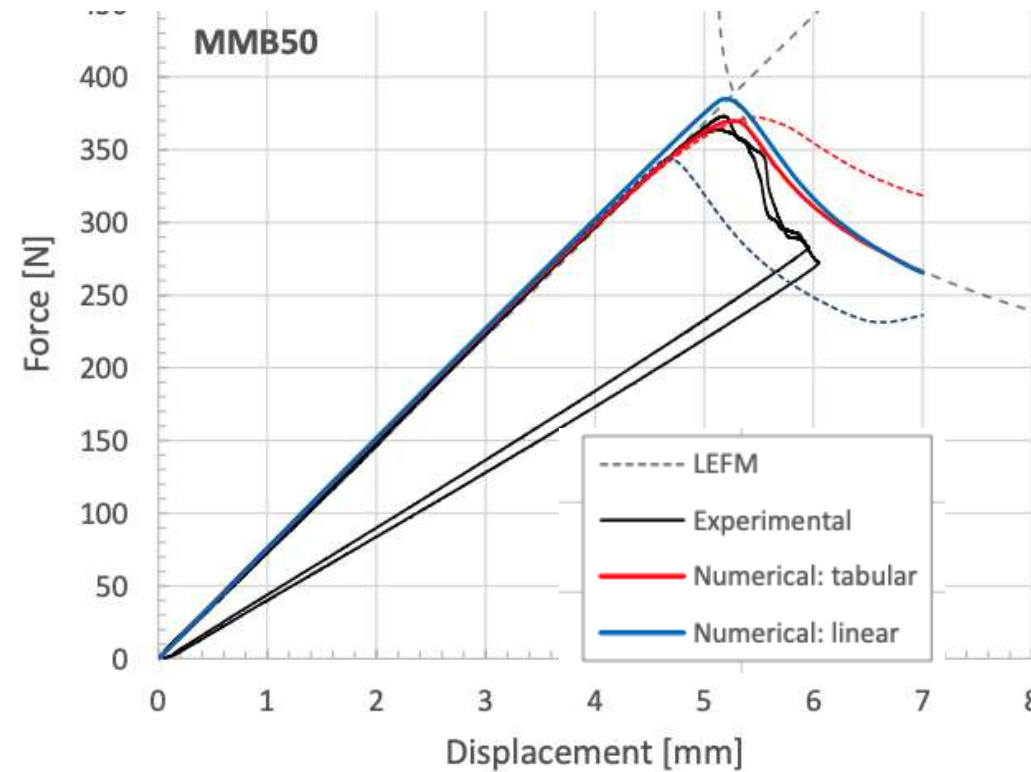
Tijs et al. 2022



Implementation in FE (Option 1: TABULAR)



Mixed-mode interpolation "managed by abaqus"

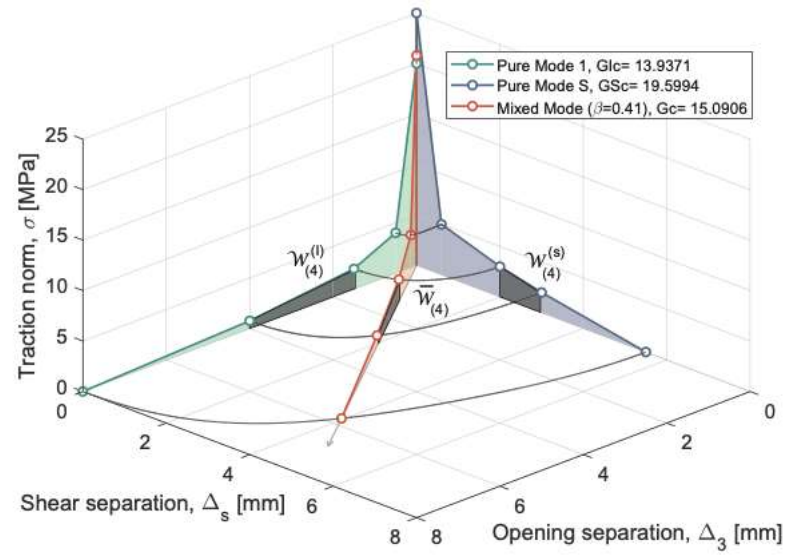


"dotted lines" excluding $B=0.1$ cohesive law

Tijs et al. 2022

Implementation in FE (Option 2: Superposition)

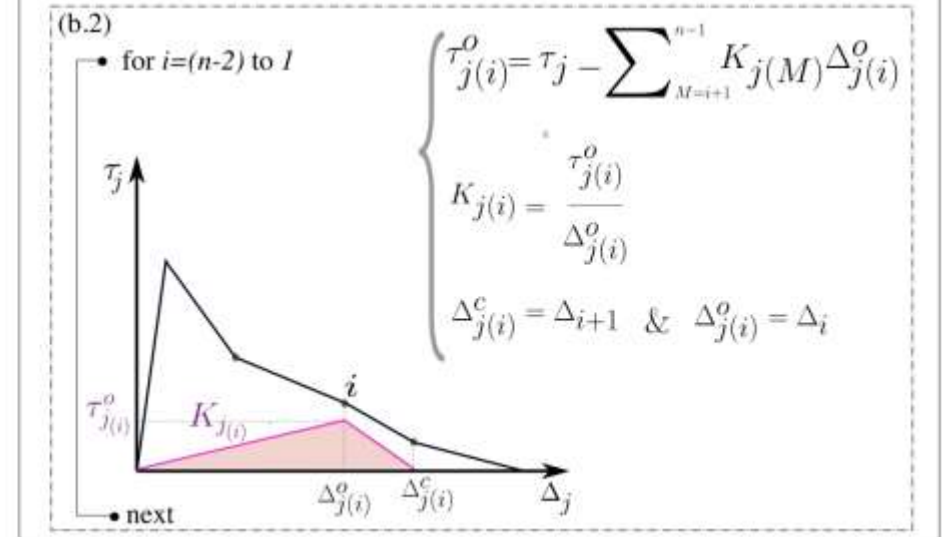
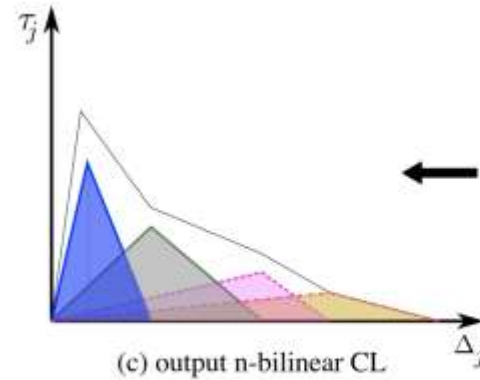
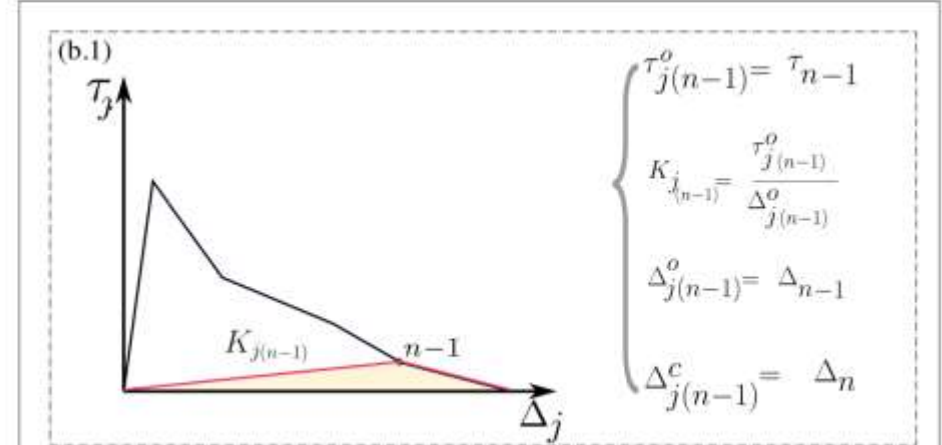
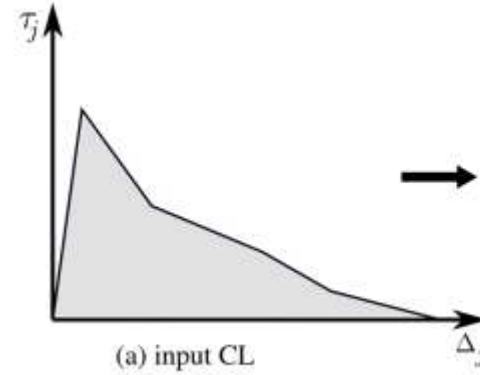
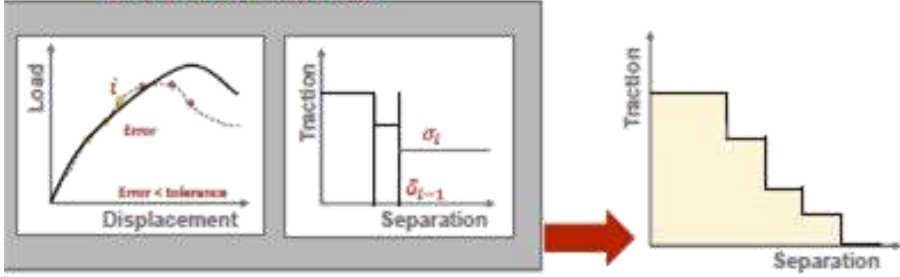
S.M. Jensen, et al.



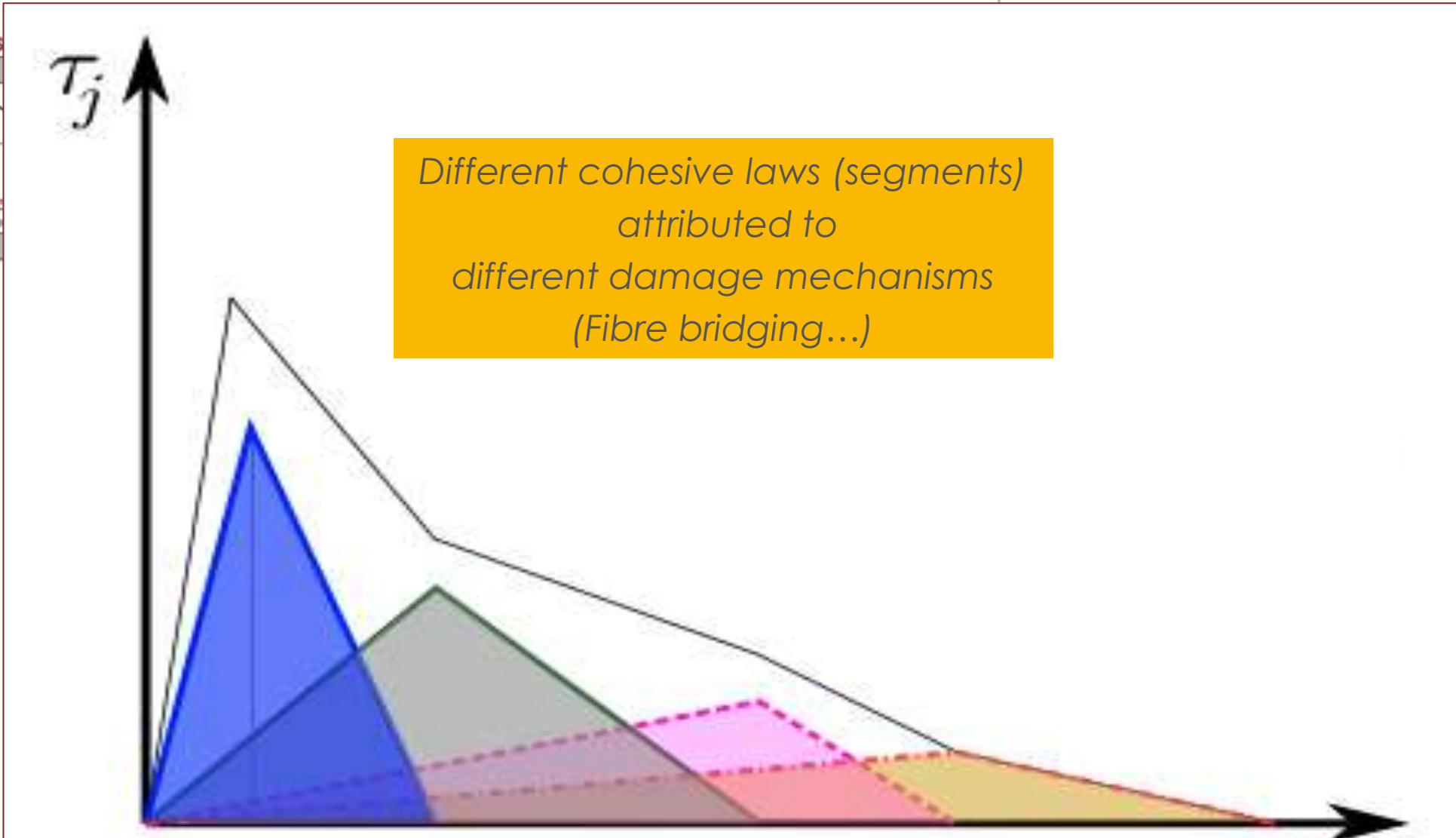
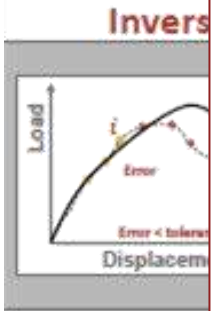
Jensen et al. 2019

Implementation in FE (Option 2: Superposition)

Inverse Method



Implementation in FE (Option 2: Superposition)



$$\tau_{j(n-1)}^o = \tau_{n-1}$$

$$K_{j(n-1)} = \frac{\tau_{j(n-1)}^o}{\Delta_{j(n-1)}^o}$$

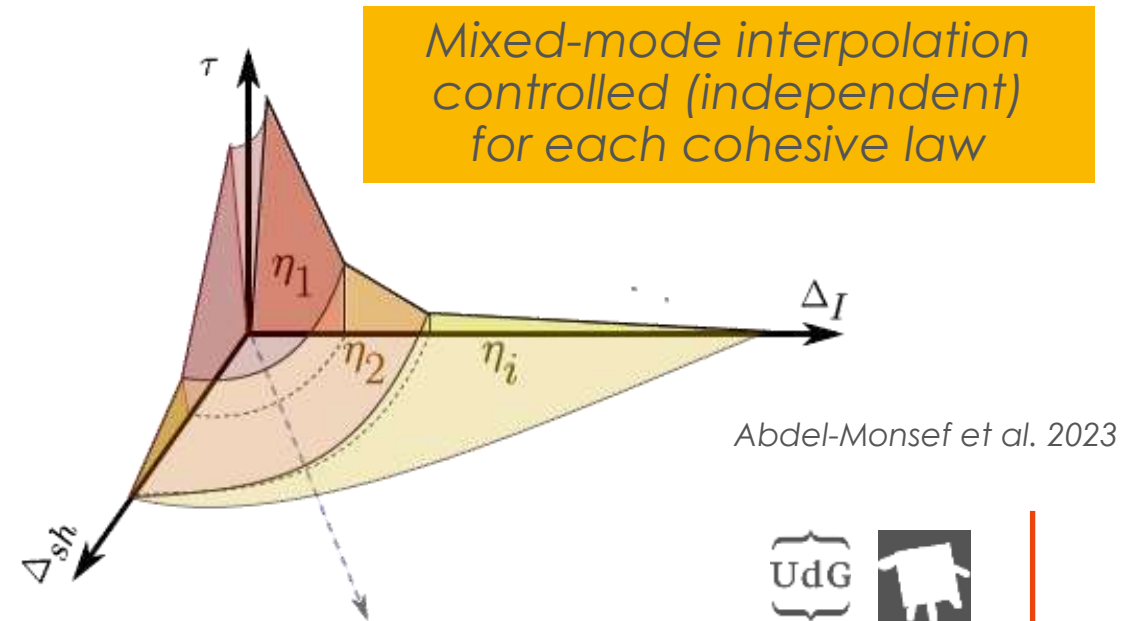
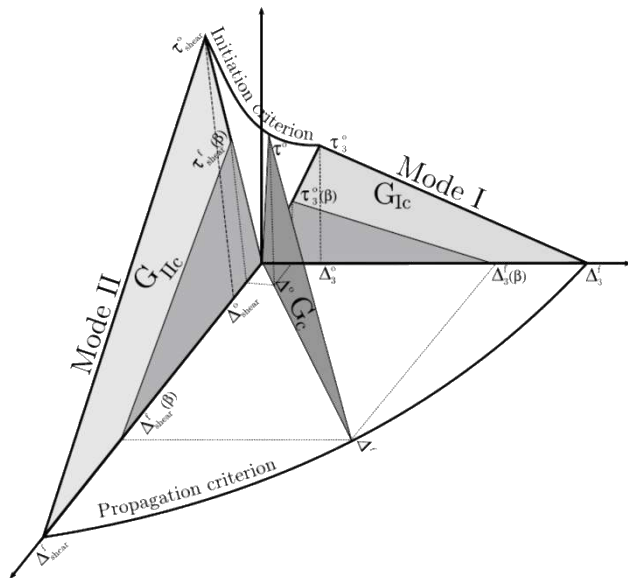
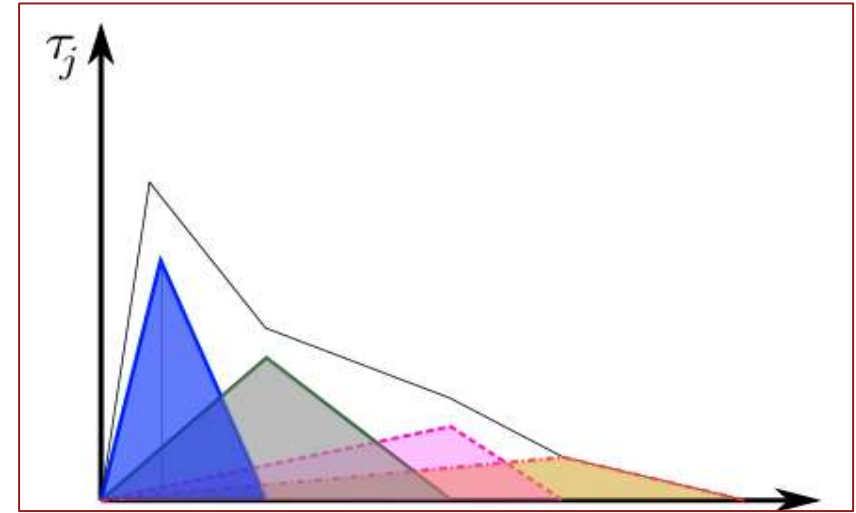
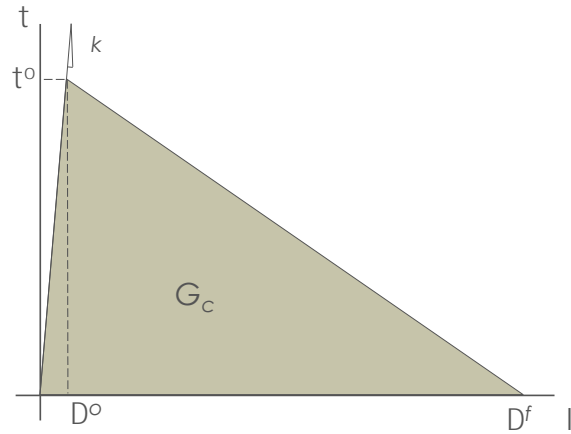
$$\Delta_{j(n-1)}^o = \Delta_{n-1}$$

$$\Delta_{j(n-1)}^c = \Delta_n$$

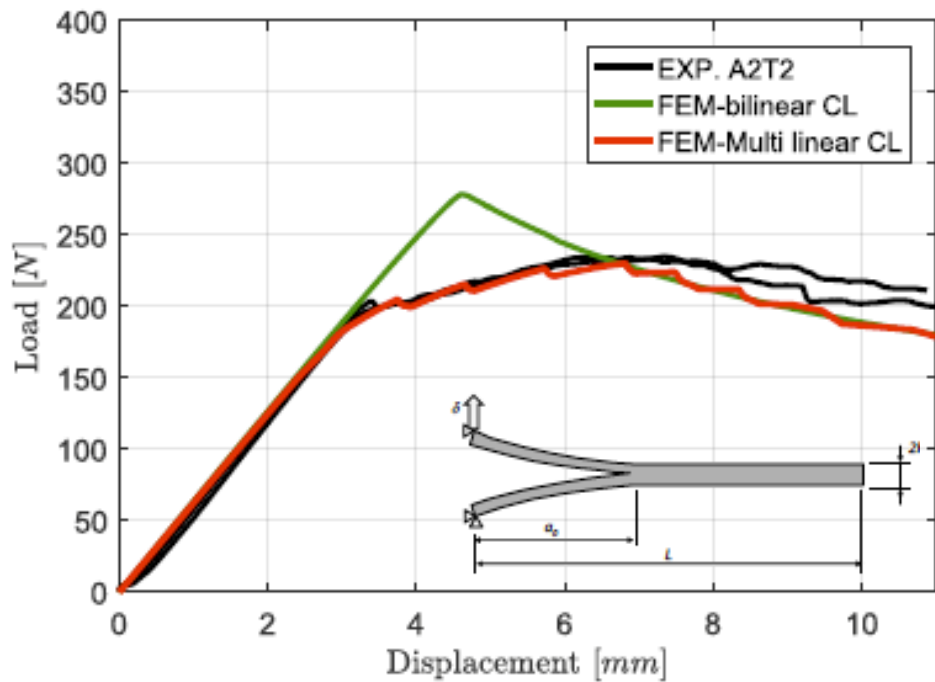
$$\sum_{M=1}^{n-1} K_{j(M)} \Delta_{j(i)}^o$$

$$\& \Delta_{j(i)}^o = \Delta_i$$

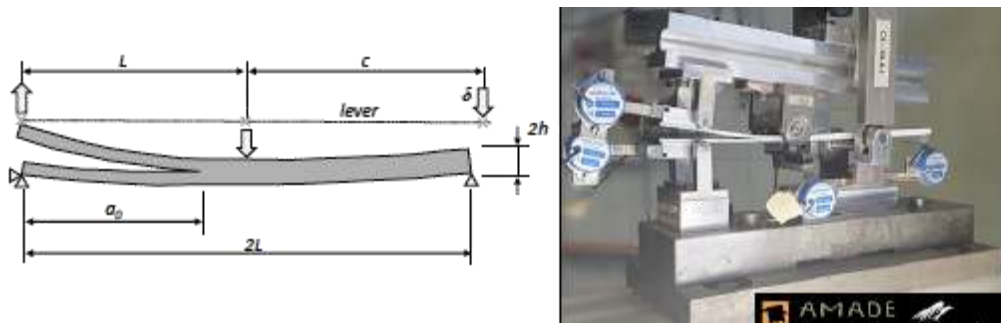
Implementation in FE (Option 2: Superposition)



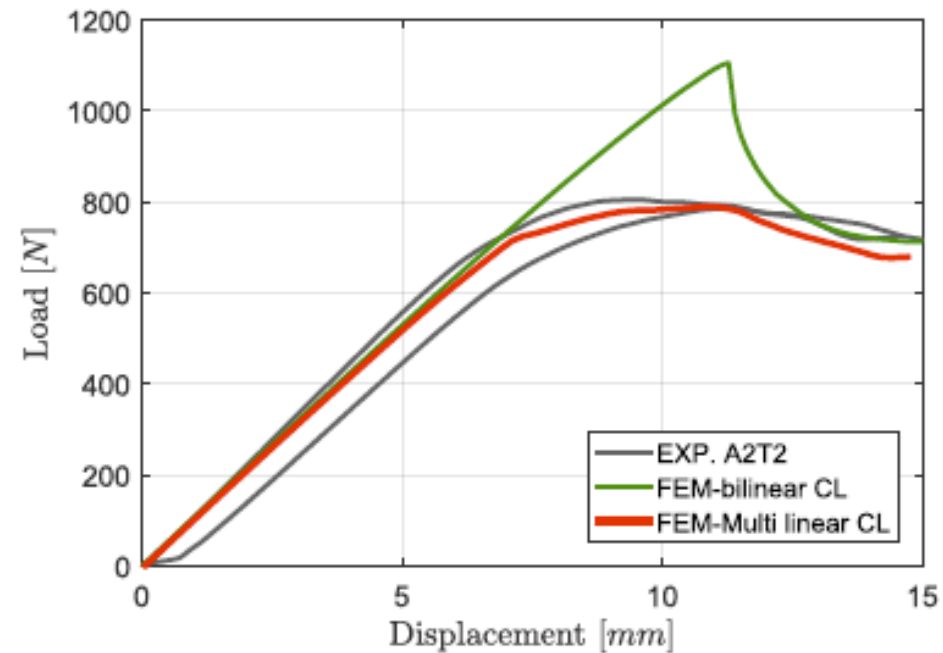
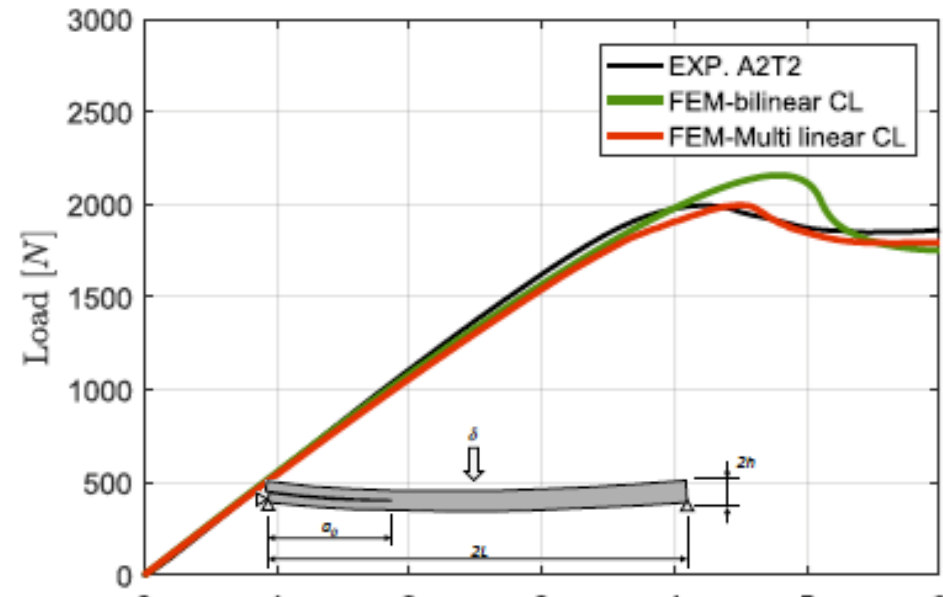
Abdel-Monsef et al. 2023



(a) DCB

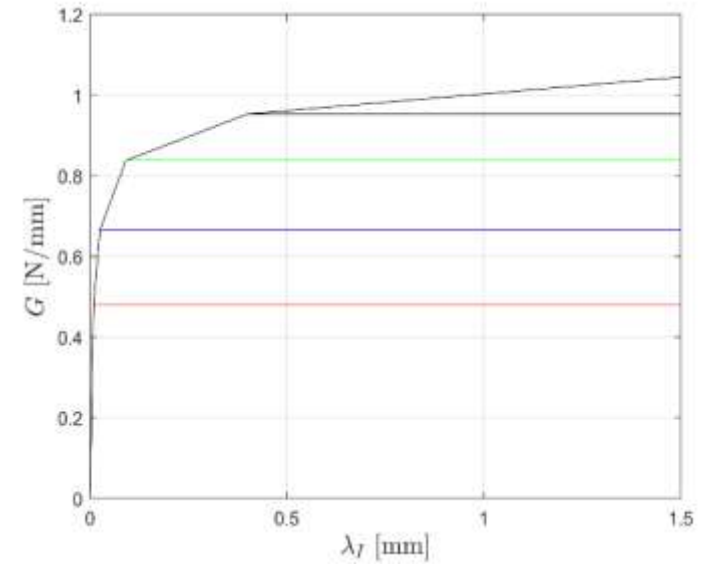
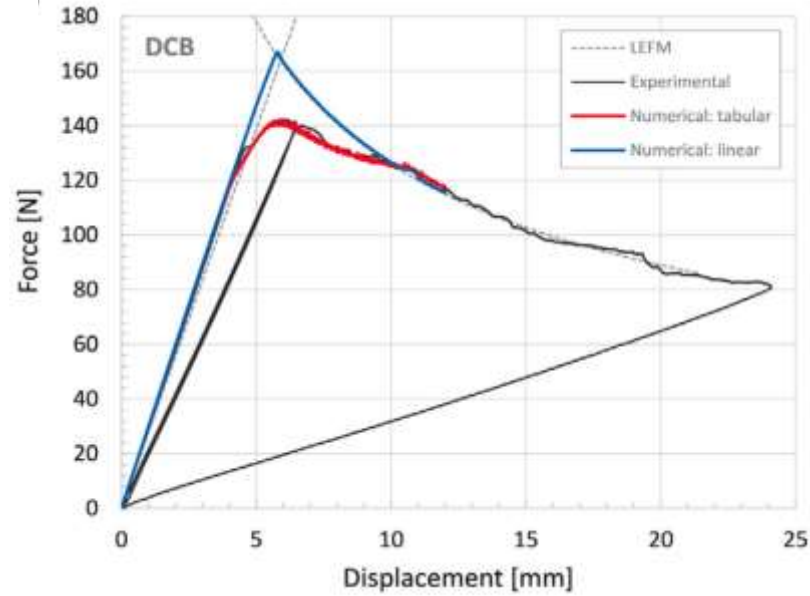
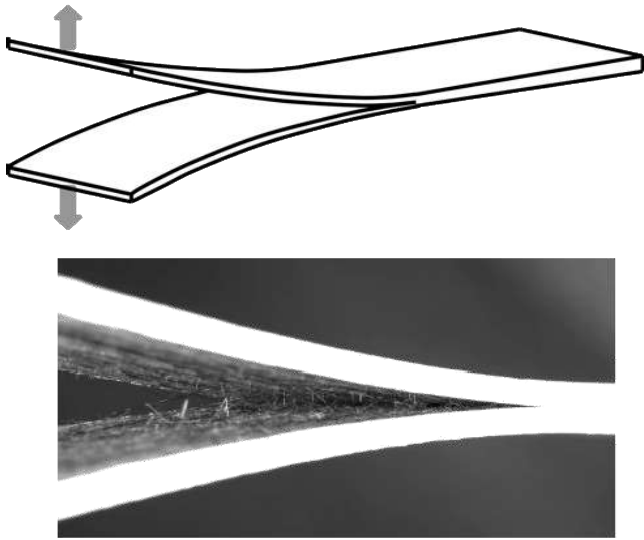


Bonded joint configuration

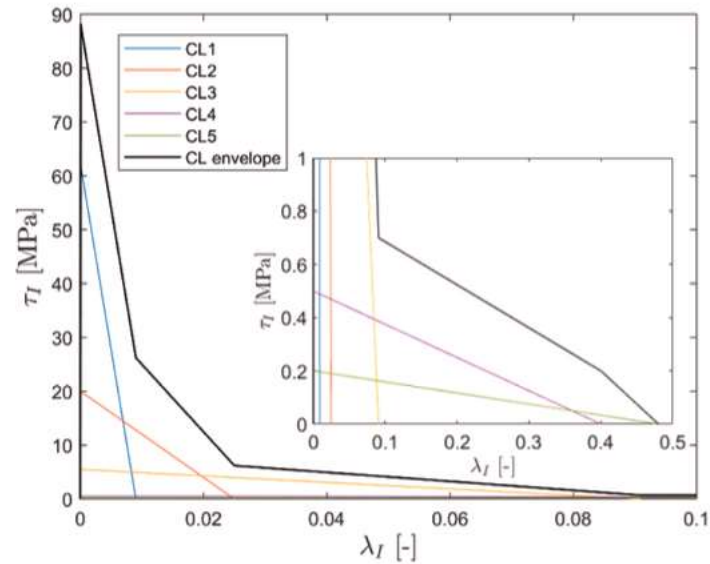


(c) MMB 75%

Static loading

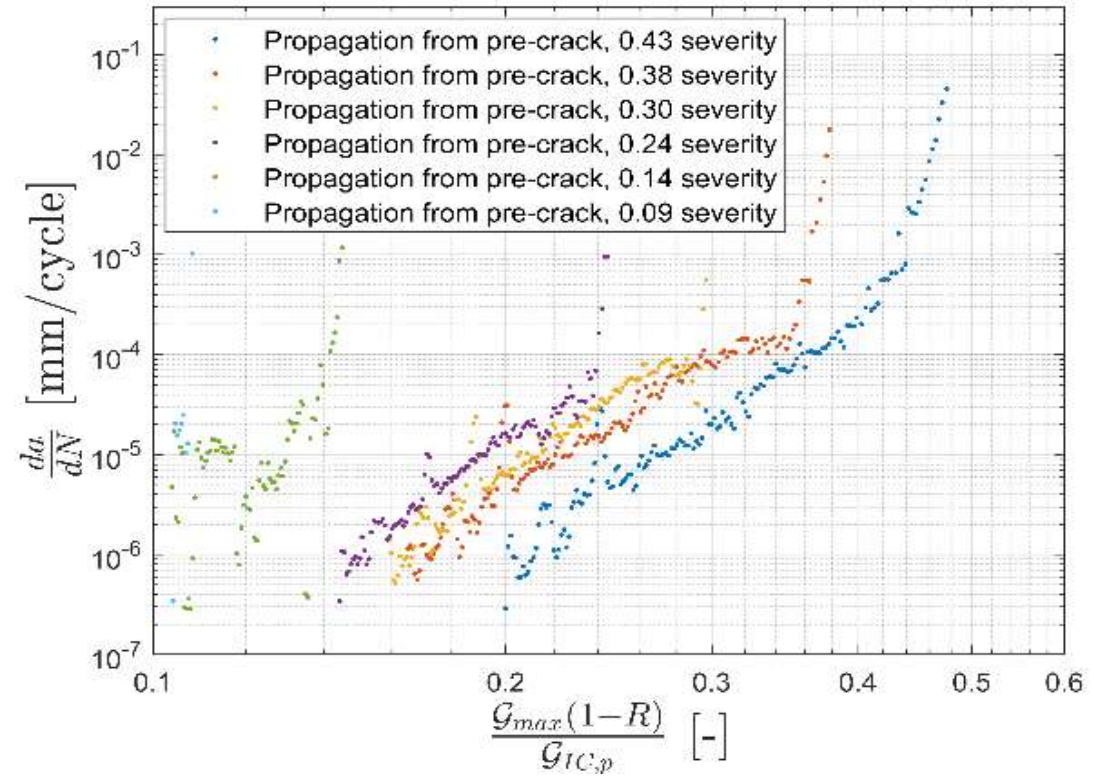
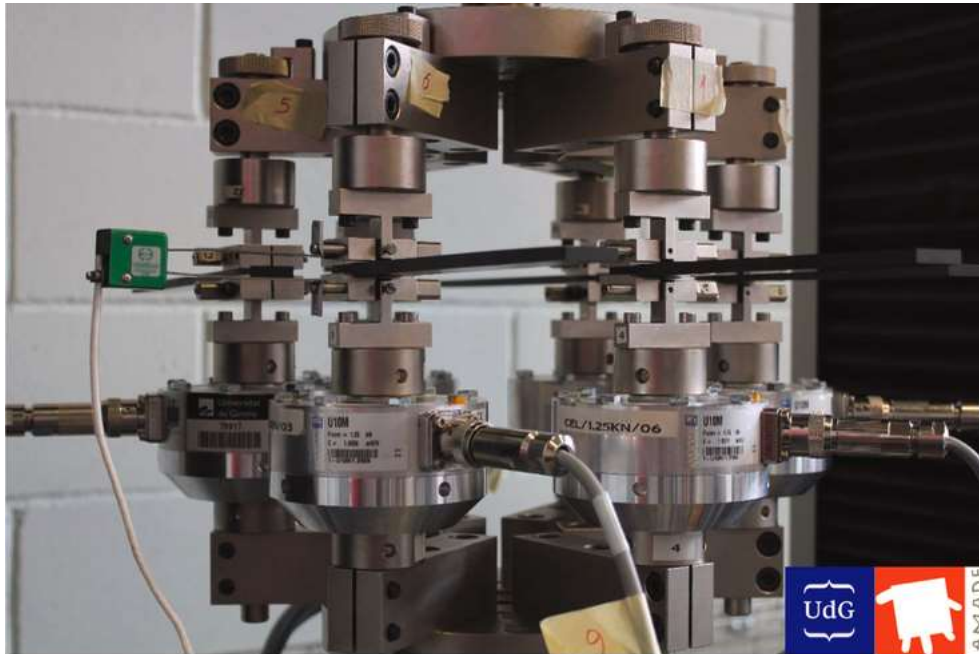


Modelling approach → Superposition of 5 linear (bilinear) cohesive laws



Fatigue response

Experimental crack growth curve



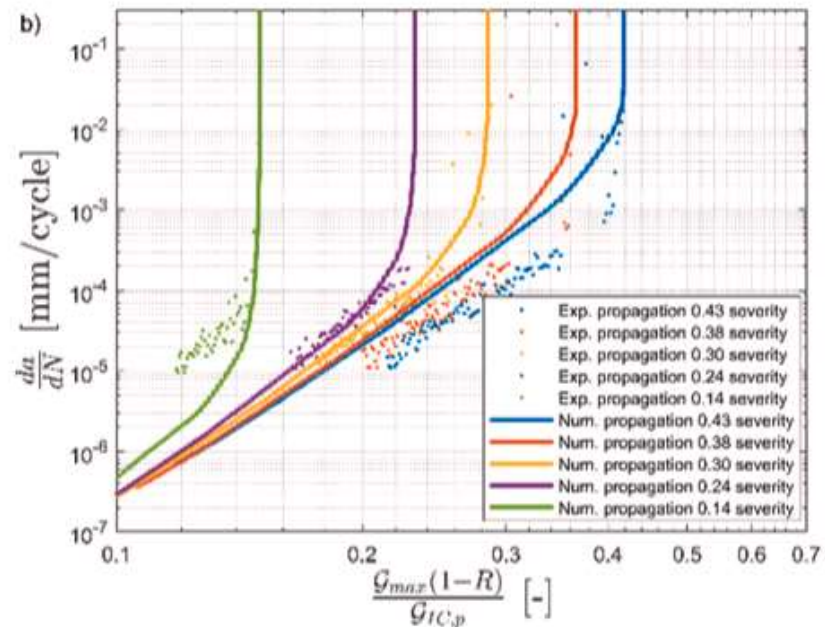
Fatigue simulation

Modelling approach

- Superposition of 5 CL (static)
- CL1, CL2 and CL3 undergo static and fatigue degradation
- CL4 and CL5 only static degradation

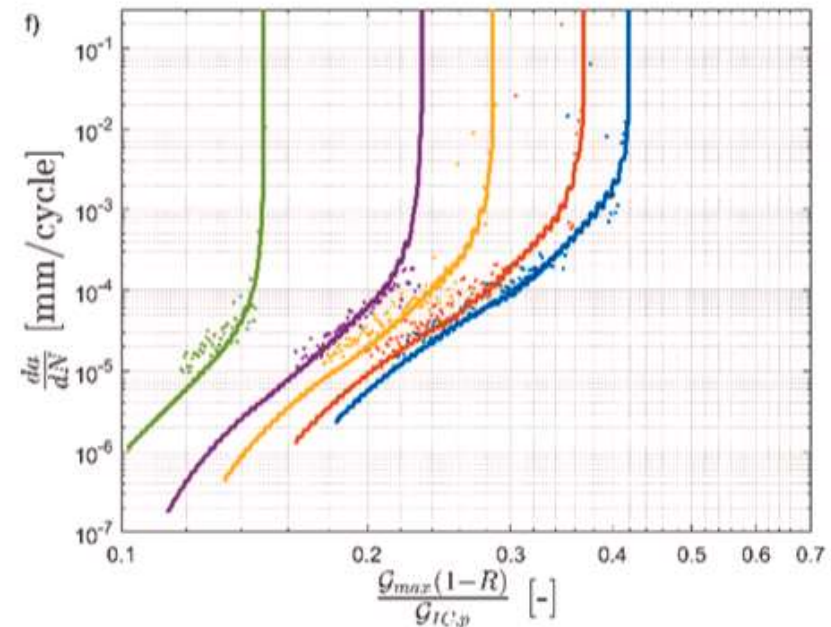
OPTION 1

- Same fatigue degradation parameters for CL1, CL2 and CL3



OPTION 2

- Different degradation parameters for the different damage mechanisms



Conclusions

- *Discussed about the mechanics of delamination onset and propagation*
- *“Linked” to the cohesive zone model concept*
- *Cohesive law shape “matters” and how it can be “measured”*
- *Discussed about the implementation using FEM of a general CL shape*
- *Discussed about the intrinsic relation between the shape of the cohesive law and the different damage mechanisms*
- *Discussed about the mixed-mode interpolation*

Keynote speakers selection by the conference committee (Sept. 2022)

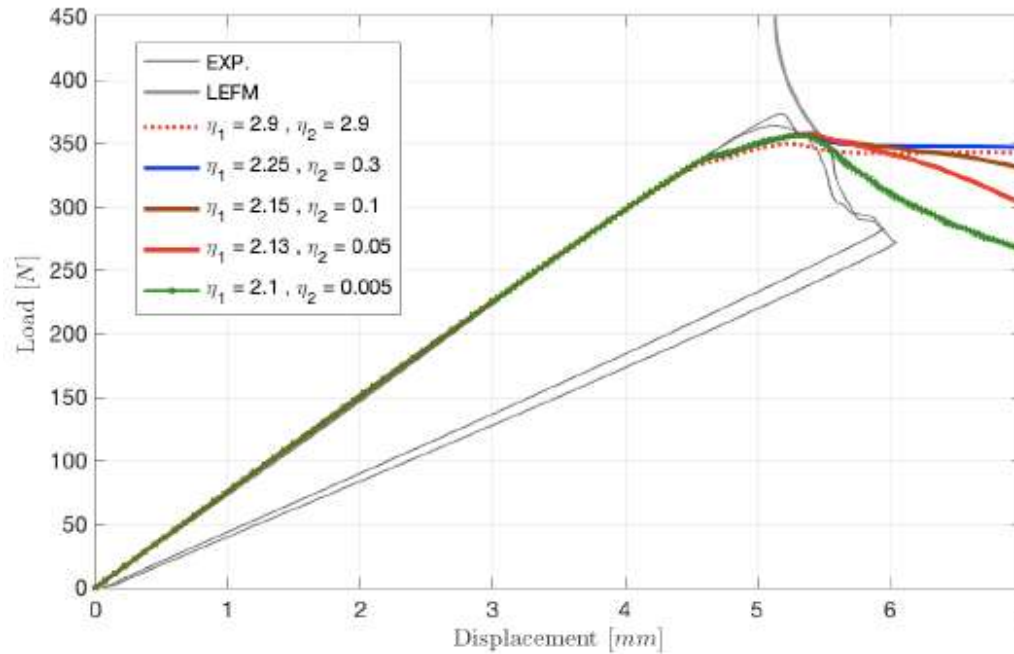
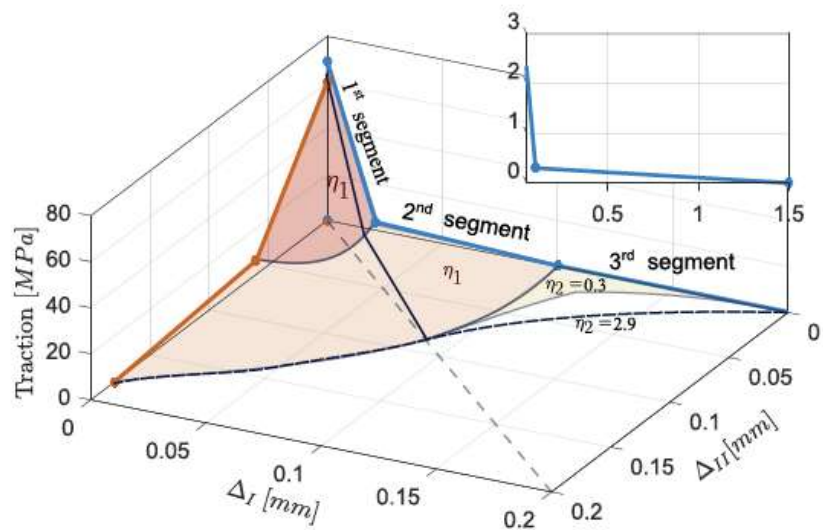
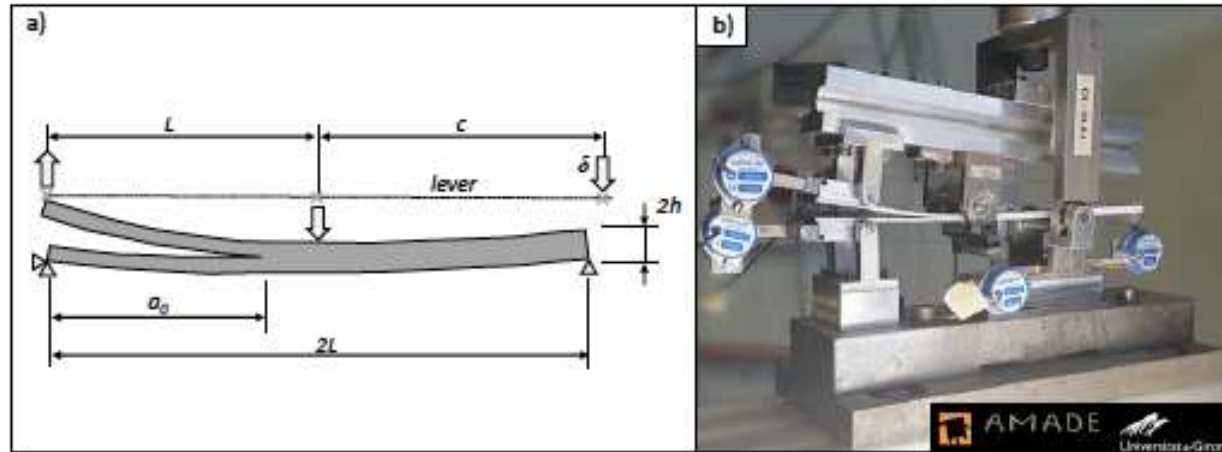
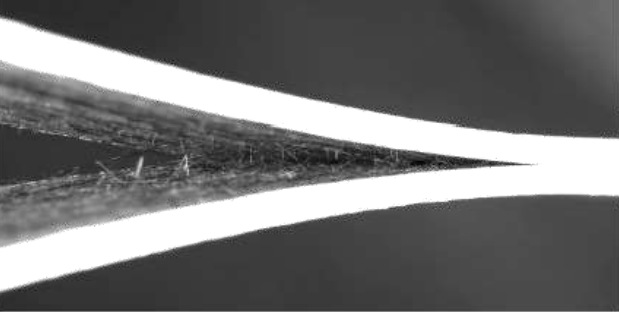
- ▣ *there are many researchers who use cohesive elements and never ask questions*
- ▣ *there is another (smaller) group that considers all this as nonphysical and rejects the method in spite of its applicability and practical usefulness*
- ▣ *there is a third group that HAS to use cohesive elements, but they want answers based on physics. (I hope we all belong to this group...)*





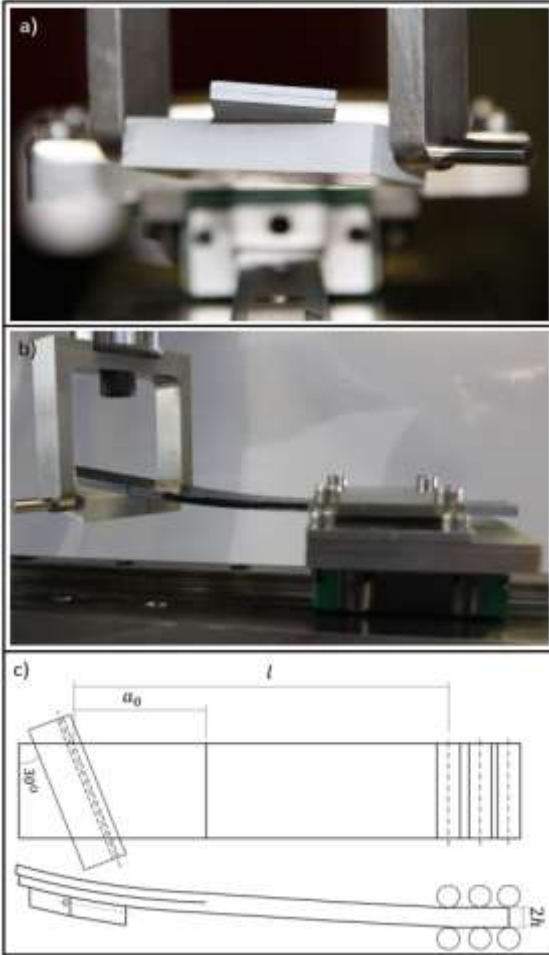
<http://amade.udg.edu>
testlab.amade@udg.edu





Fatigue simulation

📷 Challenging test case



Loading conditions of Hybrid benchmark test that can be considered as equivalent as in service loading:

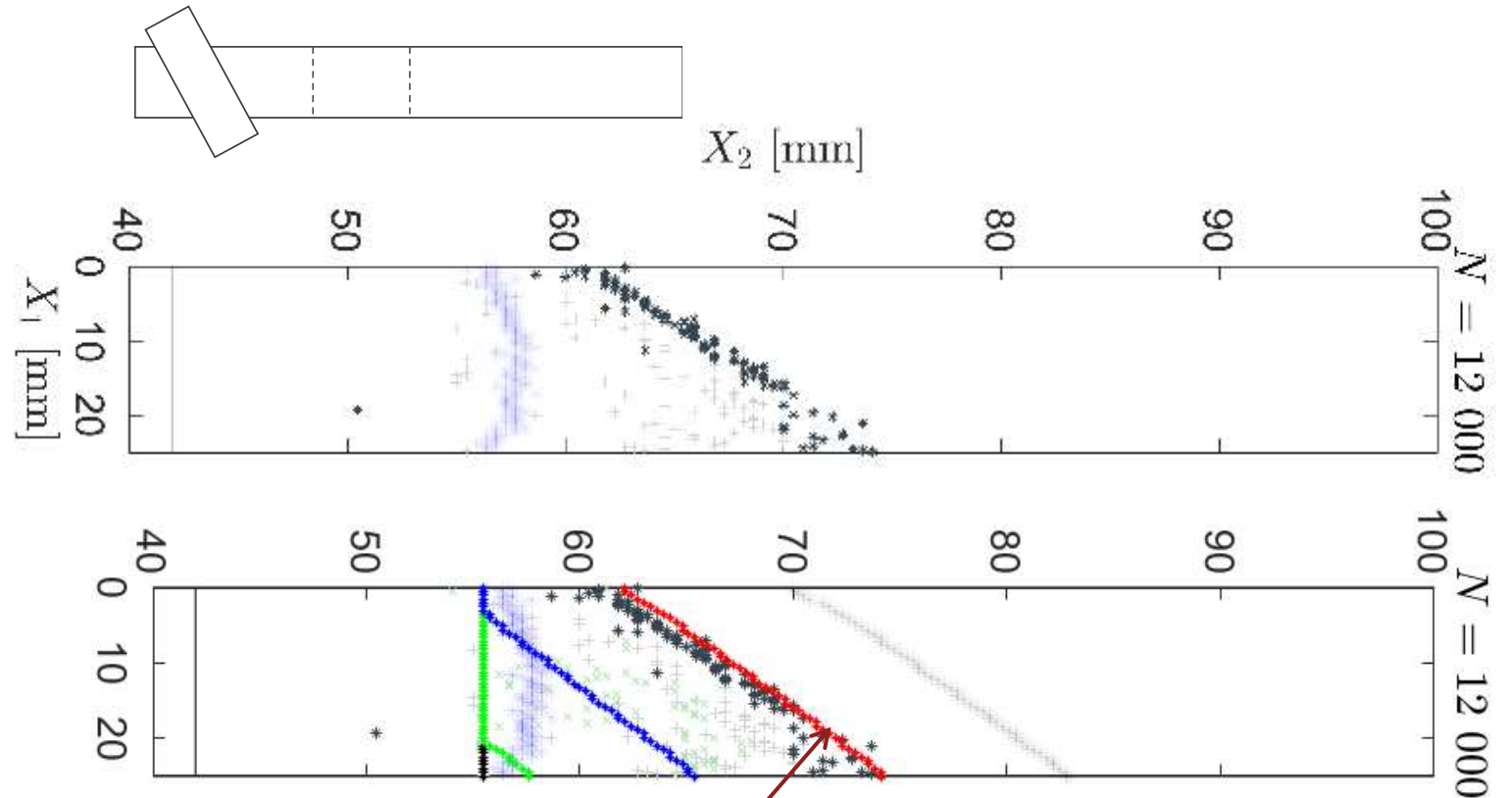
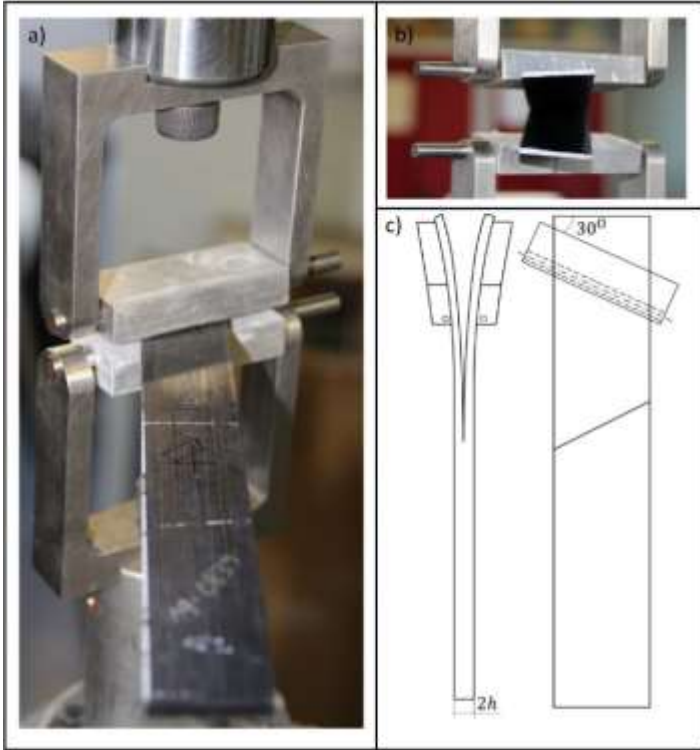
Step	Loading mode	Loading angle	Maximum displacement, δ_{max} [mm]	Number of cycles
0	Mode I	$+ 0^\circ$	-	-
1	Shear mode	$+ 30^\circ$	7	12 000
2	Mode I	$- 30^\circ$	5	30 000
3	Mode I	$- 30^\circ$	10	-
4	Mode I	$- 30^\circ$	10	400 000

Fatigue simulation

Challenging test case

Loading conditions of Hybrid benchmark test that can be considered as equivalent as in service loading:

Step	Loading mode	Loading angle	Maximum displacement, δ_{max} [mm]	Number of cycles
0	Mode I	+ 0°	-	-
1	Shear mode	+ 30°	7	12 000
2	Mode I	- 30°	5	30 000
3	Mode I	- 30°	10	-
4	Mode I	- 30°	10	400 000



Growth direction

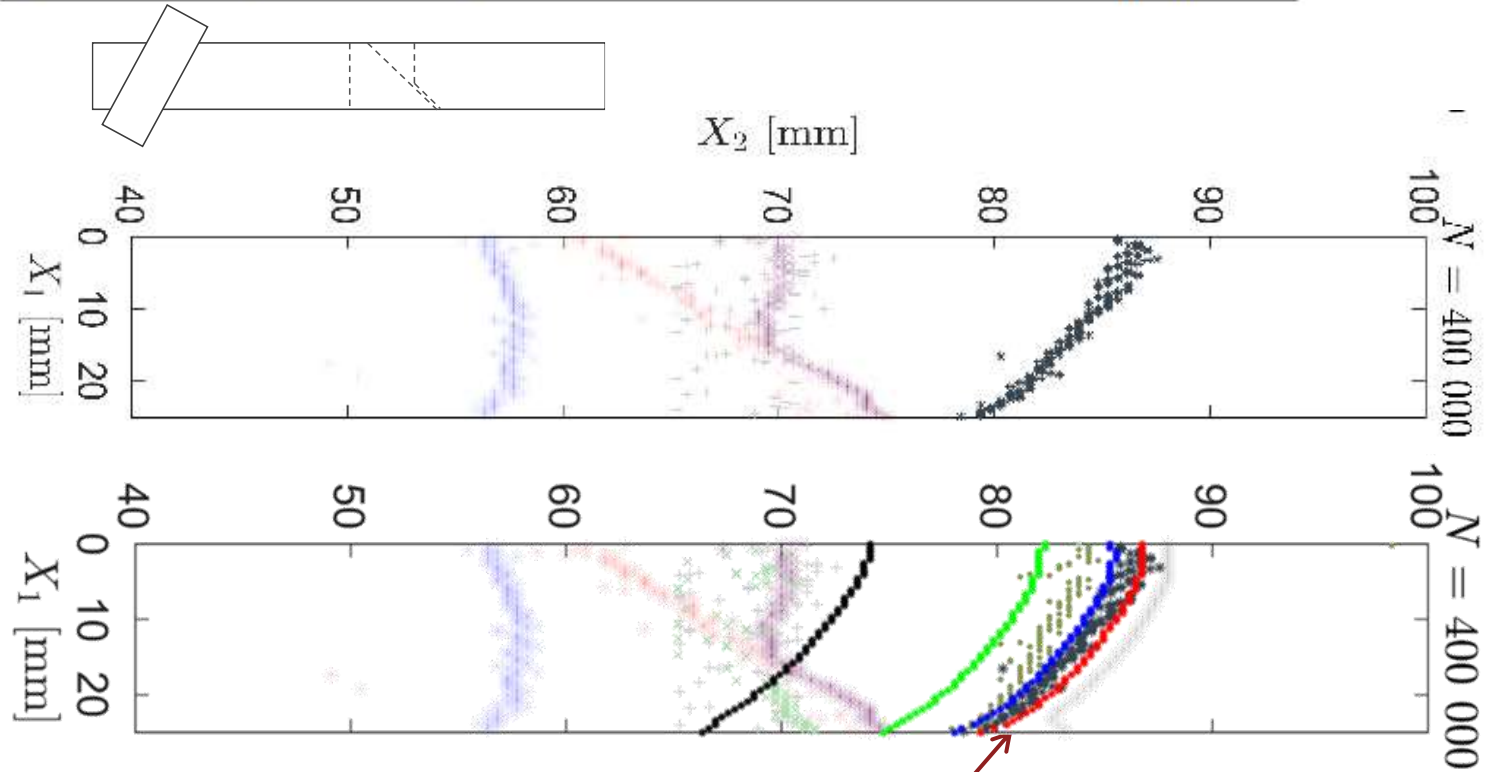
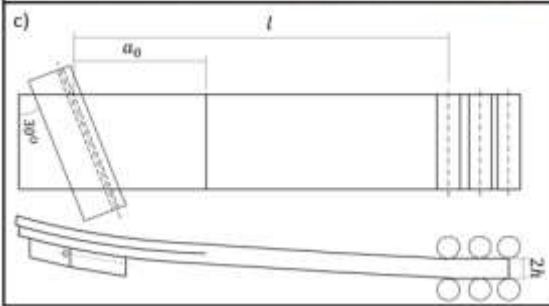
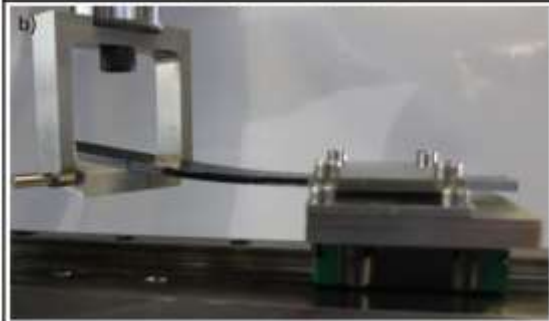
Numerical Leading crack tip

Fatigue simulation

Challenging test case

Loading conditions of Hybrid benchmark test that can be considered as equivalent as in service loading:

Step	Loading mode	Loading angle	Maximum displacement, δ_{max} [mm]	Number of cycles
0	Mode I	+ 0°	-	-
1	Shear mode	+ 30°	7	12 000
2	Mode I	- 30°	5	30 000
3	Mode I	- 30°	10	-
4	Mode I	- 30°	10	400 000



Growth direction →

Numerical Leading crack tip

Conclusions

