

1 **The thin border between cloud and aerosol: sensitivity of several ground** 2 **based observation techniques.**

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11 **Abstract**

12 Cloud and aerosol are two manifestations of what it is essentially the same physical
13 phenomenon: a suspension of particles in the air. The differences between the two come from
14 the different composition (e.g., much higher amount of condensed water in particles
15 constituting a cloud) and/or particle size, and also from the different number of such particles
16 (10-10,000 particles per cubic centimeter depending on conditions). However, there exist
17 situations in which the distinction is far from obvious, and even when broken or scattered
18 clouds are present in the sky, the borders between cloud/not cloud are not always well
19 defined, a transition area that has been coined as the “twilight zone”. The current paper
20 presents a discussion on the definition of cloud and aerosol, the need for distinguishing or for
21 considering the continuum between the two, and suggests a quantification of the importance
22 and frequency of such ambiguous situations, founded on several ground-based observing
23 techniques. Specifically, sensitivity analyses are applied on sky camera images and
24 broadband and spectral radiometric measurements taken at Girona (Spain) and Boulder (Co,
25 USA). Results indicate that, at these sites, in more than 5% of the daytime hours the sky may
26 be considered cloudless (but containing aerosols) or cloudy (with some kind of optically thin
27 clouds) depending on the observing system and the thresholds applied. Similarly, at least
28 10% of the time the extension of scattered or broken clouds into clear areas is problematic to
29 establish, and depends on where the limit is put between cloud and aerosol. These findings
30 are relevant to both technical approaches for cloud screening and sky cover categorization
31 algorithms and radiative transfer studies, given the different effect of clouds and aerosols
32 (and the different treatment in models) on the Earth’s radiation balance.

33 **1. Introduction**

34 The Earth's atmosphere contains suspended particles, i.e. particles that because of their size
35 have terminal fall velocities of the order of centimeters per second at most, so they have
36 atmospheric residence times on the order of hours, days, or much longer in some cases. These
37 particles vary in their chemical composition, have concentrations that vary in space and time,
38 are present in both the solid and liquid phases and have sizes ranging over several orders of

39 magnitude. In gross aggregate, the suspension of particles receives two names: either cloud or
40 aerosol. Simplifying, a cloud is an aggregate of a number of particles formed mainly of water,
41 in liquid or solid state (i.e., hydrometeors) of sizes between a few microns to some
42 millimeters and in sufficient concentration to be perceived by human vision from the Earth's
43 surface. Any other aggregate of particles is called, generically, atmospheric aerosol, and
44 generally contains less liquid water than clouds. This includes wind-borne dust, sea spray
45 particles of salt, sulfate and organic particles, or ash and soot arising from combustion.
46 Precipitating particles such as rain, snow or hail (which have terminal fall velocity of the
47 order of meters per second) are excluded from this discussion.

48 Despite the above differences in origin and composition, clouds and aerosol could be
49 considered two manifestations of the same phenomenon. However, their description,
50 characteristics, and –in particular– interactions with solar and terrestrial radiation have
51 historically been studied separately. Indeed, the study of clouds extends back to ancient times
52 whereas the study of atmospheric aerosol is much more recent. In fact, the term was proposed
53 in the early 20th century, and has become popular within the atmospheric science
54 community only after the 1960s or so, as previously unspecific names (dust, smoke, etc.) or
55 more technical designations (lithometeor, etc.) were used. The interactions between clouds
56 and aerosols are known, although their climatic significance is far from being fully quantified
57 (see the reviews of Heintzenberg 2012; Rosenfeld et al. 2014; Seinfeld et al. 2016). The
58 presence of different types or concentrations of aerosols has impacts on clouds, as some
59 particulate matter (cloud condensation nuclei or ice nuclei) are more amenable for water
60 vapor to condense into droplets or crystals to form clouds. These effects, especially in the
61 field of energy balance, have been known as aerosol indirect effects (Albrecht, 1989;
62 Twomey, 1974) to distinguish from the direct (purely radiative by absorption and scattering)
63 effect that aerosols have on the radiative energy transfer in the atmosphere.

64 Broadly speaking, there are two features that distinguish a cloud from other suspension of
65 particles in the air: i) the content of water in droplets and/or ice crystals, and ii) the visibility,
66 i.e., the appearance of a more or less clearly delimited form of (usually) white/grey color,
67 which is possible to see evolve (it should be noted that some aerosol suspensions are also
68 clearly visible, for example, a smoke plume). Both features allow quantification, i.e. one can
69 propose a threshold for the concentration of droplets or ice crystals (or for the amount of
70 condensed water), and also for the optical effect (the optical thickness at a certain
71 wavelength). Dupont et al. (2008) showed that solar irradiance and sky imagery retrievals
72 tuned to reflect human observations allow up to a visible optical depth of 0.15 to 0.2 of
73 primarily high ice haze to be traditionally classified as “cloud free” sky. But historically the
74 decision on whether a volume of air is cloud or not (leaving no room for intermediate cases)
75 has been based on the judgment of a human observer on the ground. This does not seem very
76 scientific, since it can happen that the same volume of air containing aqueous particles are
77 labeled as cloud or not depending on the contextual conditions in which the observation is
78 made, subject to the judgment and perception of the observer. Similar difficulties arise when
79 clouds are observed from satellites (Koren et al., 2008).

80 Consequently, fundamental questions remain: What is the limit of visibility from which a
81 suspension of droplets must be considered cloud? Should this limit be set for an “average”
82 human eye, or can it be objectively established for some instrument as in Dupont et al.
83 (2008)? Or is it even reasonable to consider such a limit given that the aerosol/cloud particle
84 suspension could be considered as a continuum and not a dichotomic phenomenon. How does
85 one define visibility when observations are performed in a wavelength outside the visible
86 range of the human eye? Droplets form on soluble hydrophilic particles whereas many ice
87 particles form on insoluble hydrophobic particles so how does one decide if the suspended
88 particles are aerosol particles or hydrometeors? When observation is performed by automated
89 instruments, trying to reduce to a three level classification (cloud / aerosol / clear sky) is even
90 more difficult (Tapakis and Charalambides, 2013). Subsequently, this classification has
91 consequences for climate studies (Charlson et al., 2007), including trend analysis, as derived
92 trends may depend on the instrument and/or methodology used to infer cloud amounts (Wu et
93 al., 2014).

94 A good example of the difficulties of defining cloud and aerosol is found regarding sky
95 images taken by “all-sky” cameras (they “see” an entire 180° sky view from a particular point
96 at the surface). The digital images are analyzed to obtain information on the state of the sky,
97 in particular cloud cover and cloud type (Calbó and Sabburg, 2008; Heinle et al., 2010;
98 Kazantzidis et al., 2012; Long et al., 2006b). The problem is what thresholds to set to
99 distinguish between the “clear” and “cloudy” pixels. Even if more complex approaches are
100 adopted (Li et al., 2011; Saito and Iwabuchi, 2016), they rely on the initial human decision
101 taken on the training images. In fact, sky cameras have also been proposed as devices to
102 observe and characterize the atmospheric aerosol (Cazorla et al., 2008).

103 This is not unique for cloud observations by ground-based imaging in the visible. For
104 example, the difficulties in trying to distinguish clouds and aerosol in sunshine duration
105 records have been pointed out elsewhere (Sanchez-Romero et al., 2014). In addition, many
106 works focus on removing cloud “contamination” from aerosol observations performed with
107 sunphotometers or shadowband radiometers (Alexandrov et al., 2004; Kassianov et al., 2013;
108 Michalsky et al., 2010). The problem further expands when considering other views
109 (satellite) or other wavelengths (ceilometers in the infrared, microwave radiometers, weather
110 radars). All these difficulties have consequences in both meteorological and climatological
111 studies (e.g. Boers et al., 2010; Várnai and Marshak, 2011; Sanchez-Lorenzo et al., 2009; Wu
112 et al., 2014).

113 In general the distinction between a cloudy and a cloudless sky, and the separation between
114 cloud and aerosol, is appropriate for attribution studies and modeling radiative effects of
115 different climate forcing mechanisms, but imposing this classification may be unnecessary
116 (or inconvenient) in relation to new and advanced methods of observation and measurement.
117 If so, the distinction could also be unnecessary in radiative transfer models, or in future
118 parameterizations included in weather and climate models. This approach of a continuous
119 treatment of aggregates of particles in the atmosphere is relatively new, although some
120 previous works have already pointed in this direction.

121 For example, Charlson et al. (2007) highlighted the importance that has been given to the
122 separation between the “cloud” and “clear” regimes in various fields of study including the
123 radiative forcing by clouds and the quantification of direct effects and indirect radiative
124 forcing by aerosols. The paper questioned the separation between the two regimes, and
125 suggested the desirability of treating the phenomenon as a continuum. Similarly, Koren et al.
126 (2007) described a transition zone (“twilight” zone) around the cloud in which the optical
127 properties are close to those of the cloud itself. The authors estimated that an appreciable
128 fraction (between 30 and 60%) of the part of the globe at any given time considered free of
129 clouds could correspond to that area of transition, a fact that could have important climate
130 implications. The question of the climatic importance of clouds that are considered “small” in
131 size was addressed by Koren et al. (2008), as well as the effect of the aerosol in the regions
132 between clouds (Koren et al., 2009). Also, Bar-Or et al. (2010) introduced the concept of
133 cloud field as an area that includes detectable clouds and twilight zone, and found that the
134 cloud field fraction could be as large as 97% in an area where the detectable cloud fraction is
135 53%. In the cited works, several methodologies were used: spectral radiometry from the
136 surface in the visible and near infrared, satellite measurements, and modeling. Also long-
137 wave spectral radiometry is being used for the purpose of studying the properties of thin
138 clouds and the transition region (Hirsch et al., 2014, 2012).

139 Other researchers have studied radiative effects occurring in the vicinity of the clouds. Thus,
140 the question of increased reflectivity and the “bluish” aerosol in the vicinity of the visible
141 clouds has been attributed to the Rayleigh scattering of the radiation reflected by the cloud;
142 that is ultimately a three-dimensional effect (Eck et al., 2014; Kassianov et al., 2010;
143 Marshak et al., 2008; Várnai and Marshak, 2009; Wen et al., 2008). They have also studied
144 the transition region from satellite measurements and stated its important radiative effects
145 (Várnai and Marshak, 2011) and have explored the combination of data from two different
146 satellites with the goal of obtaining detailed information on aerosols near clouds (Várnai and
147 Marshak, 2012). Recently, Ten Hoeve and Augustine (2016) confirmed from ground-based
148 and satellite measurements that the aerosol optical depth increases in the vicinity of a cloud;
149 Jeong and Li (2010) had previously found that aerosol humidification effects could explain
150 one fourth of a reported correlation between cloud cover and aerosol optical depth. Moreover,
151 Chiu et al. (2009) and Marshak et al. (2009) addressed the description of the continuum from
152 measurements of zenith spectral radiance in the visible and near infrared, with the high
153 temporal resolution that the rapid transitions between cloud and clear sky require. Chiu et al.
154 (2010) successfully replicated these results by radiative modeling.

155 The goal of the current paper is to quantify the importance and frequency of situations where
156 ambiguity between clouds and aerosol occur; in other words, situations where the suspension
157 of particles depend on subjective definition to be classified as either cloud or aerosol. These
158 transition situations populate the continuum between what is clearly a cloud and what is to be
159 called undoubtedly an aerosol. We realize that such quantification depends both on the
160 instrument or technique used for observing the sky, and on the climate and geographical
161 conditions of the site. Therefore, several ground-based, passive observing techniques are
162 considered: specifically, sensitivity analyses are applied on sky camera images, broadband

163 radiation measurements, and spectral measurements. Two sites are considered: Girona
164 (Spain), and Boulder (Co, USA).

165 **2. Data, measurements, and observations**

166 The University of Girona has maintained a radiometric and meteorological station since the
167 early 1990s. Instruments are placed on the roof of a university building (41°58'N, 2°50'E, 110
168 m asl). The site is located in the northeast of the Iberian Peninsula, some 30 km from the
169 Mediterranean Sea and 40 km from the Pyrenees mountain range; the climate is
170 Mediterranean, meaning mild winters and hot summers, and relatively dry, with more rain in
171 equinoctial seasons. Characteristics of the site and of instruments of this station can be found
172 in Calbó et al. (2016); here we will only give some details of the relevant instruments used in
173 the current research. First, the site holds a set of instruments measuring downwelling
174 shortwave (solar) and longwave (atmospheric) radiation, including the three components for
175 the solar irradiance (global, direct, and diffuse). These instruments strive to adhere to the
176 specifications of the Baseline Surface Radiation Network (BSRN) for calibration, daily
177 routine supervision, and temporal resolution of sampling and recording data. Second,
178 operation of a Multifilter Rotating Shadowband Radiometer (MFRSR) began at the site in
179 2012. This instrument is oriented towards characterizing the atmospheric aerosol, specifically
180 its optical depth (AOD) at several visible and near infrared wavelengths and is described
181 elsewhere (Harrison et al., 1994; Sanchez-Romero et al., 2016). The MFRSR measures both
182 global and diffuse solar radiation in one broadband and six narrow bands of the solar
183 spectrum (specifically the narrow band filters are centered nominally at 400, 500, 615, 670,
184 870, and 940 nm). The MFRSR at Girona sampled at 1 minute time step until September
185 2014; since October 2014 it has sampled at 15 second intervals. Third, a whole sky camera is
186 used to take images of the sky during daylight hours, at 1 minute time steps. The camera is a
187 conventional digital CCD camera, provided with a fish-eye (i.e. >180° field-of-view) lens and
188 mounted on a sun tracker, in such a way that a black sphere projects its shadow on the lens,
189 blocking the direct sun from entering the camera. In the current research, one year (2014) of
190 data and observations from each of these instruments will be analyzed.

191 The Surface Radiation Budget Network (SURFRAD) was established in 1993 through the
192 support of the National Oceanic and Atmospheric Administration (NOAA) Office of Global
193 Programs. Its primary objective is to support climate research with accurate, continuous,
194 long-term measurements of the surface radiation budget over the United States. Thus,
195 currently seven SURFRAD stations are operating across the US (Augustine et al., 2005,
196 2000). Here we will use data and observations from one site, which is the NOAA-Earth
197 System Research Laboratory Test Facility at Table Mountain, located 13 km north of Boulder
198 (40°7'N, 105°14'W, 1689 m asl). The instruments used here are part of a larger set
199 maintained at this location and used for annual intercomparisons and other research.
200 Radiation measurements at SURFRAD stations cover the range of the electromagnetic
201 spectrum that affects the earth/atmosphere system. Like in Girona, total downwelling (global)
202 solar radiation is measured by an upward looking broadband pyranometer, the direct
203 component is monitored with a normal incidence pyrliometer mounted on an automatic sun
204 tracker, the diffuse component is measured by a shaded pyranometer that rides on the same

205 tracker, and an upward looking pyrgeometer measures longwave (thermal infrared) radiation
206 emitted downward by clouds and other atmospheric constituents. In addition, a third
207 pyranometer and another pyrgeometer are mounted facing downward, on cross arms atop of a
208 10-meter tower to measure solar radiation reflected from the surface and upwelling long
209 wave radiation respectively. Similar to Girona, the SURFRAD suite of instruments includes
210 an MFRSR. A sky camera of the model TSI (Total Sky Imager) from Yankee Environmental
211 Systems (YES) takes sky images at 1-minute time steps.

212 The two locations are middle-latitude, Northern Hemisphere sites. However, they hold some
213 geographic and climatic differences that make pertinent the use of data from both sites in the
214 current research. First, Girona is at low altitude and close to the sea, while Boulder is at high
215 altitude and thousands of km away from the closest coast. Therefore, climate in Boulder is
216 much more continental, in the sense that warmer summers and colder winters are likely; more
217 important here is that the atmosphere above Boulder is in general drier and cleaner, so
218 different cloudiness regimes and lower aerosol load are expected. Dominant aerosol types at
219 the two sites are likely different too, with maritime aerosol and Saharan dust relatively usual
220 at Girona, and continental dust and wildfire smoke more common at Boulder.”

221 **3. Methods**

222 Raw measurements and observations from the above instruments need to be processed in
223 order to obtain quantitative or qualitative information about the sky condition, clouds and/or
224 aerosol. In all processing and algorithms used (and explained below) decisions must be taken
225 to distinguish between clear sky (either clean or with a certain aerosol load) and clouds, or
226 between clouds and aerosol. These decisions usually take the form of thresholds, which are
227 somewhat subjectively selected after some tuning procedure. Sometimes, the human
228 intervention is obvious, for example when deciding which sky images are considered as
229 cloudless references. In the next paragraphs, we will explain the standard methods applied to
230 raw data, and will describe the sensitivity analyses that we have performed on them to reach
231 our goal.

232 Broadband solar radiation measurements at high temporal resolution (< 5 minutes) can be
233 used to infer the sky conditions. In this regard, after some initial attempts (Calbó et al., 2001;
234 Duchon and O'Malley, 1999) a Radiative Flux Analysis (RadFlux) technique was developed
235 to provide quantitative sky cover characteristics (Long et al., 2006a; Long and Ackerman,
236 2000) and is currently quite broadly used. Updated versions of this methodology also make
237 use of longwave irradiance measurements (Long and Turner, 2008) and of other
238 meteorological variables; here we will focus, however, on the use of solar radiation
239 measurements. In summary, the method comprises two steps. The first step (Long and
240 Ackerman, 2000) consists in identifying clear (i.e., totally cloudless) instances within a time
241 series of solar radiation data. Several conditions must be met: primarily global irradiance
242 must be between certain limits, diffuse irradiance must be less than an imposed threshold,
243 global irradiance must show low variability, and the ratio of diffuse to global solar irradiance
244 must also have low variability. These conditions are applied to “normalized” values (i.e., the
245 cosine and the longer path effects due to changing Sun's position are removed). On the basis

246 of the identified clear sky periods within the time series, empirically adjusted clear-sky
247 estimated values of global, direct, and diffuse irradiances are computed for the whole time
248 series, regardless of sky condition. In the second step (Long et al., 2006a) the daylight
249 fractional sky cover (f_{sc}) is estimated based upon the “diffuse cloud effect,” i.e., the ratio of
250 the difference between measured diffuse irradiance and the estimated clear-sky diffuse
251 irradiance normalized by the estimated clear-sky global irradiance. It should be noted that
252 other conditions are also applied to identify totally overcast and totally cloudless instances.

253 Although several empirically or subjectively given parameters are used within these
254 algorithms, the most relevant one regarding the differentiation between thin clouds, aerosols,
255 and a clean sky is the maximum diffuse irradiance that is admissible for clear skies. The
256 diffuse irradiance is produced by scattering, thus this setting limits how much scattering is
257 allowed for skies to be classified as “clear.” Indeed if the Max_Diff parameter is set to a very
258 low value, such as that for Rayleigh (molecular) scattering in the atmosphere, it is likely that
259 very few instances would be identified as clear. Similarly, when estimating cloud cover, cases
260 with heavy aerosol loading that produces large amounts of diffuse irradiance will be
261 considered as cloudy situations. If it is fixed to a too high value, cases with thin clouds may
262 be considered clear. In the original paper, Long and Ackerman (2000) suggested a value
263 around 120-150 $W m^{-2}$. Below we analyze the effect of changing this threshold on clear sky
264 determination and fractional sky cover estimation.

265 As its name indicates, the MFRSR uses a rotating shadowband to consecutively shade and
266 unshade the detector. In this way, direct (beam) radiation on the horizontal surface of the
267 detector is estimated by subtracting the shaded diffuse measurement from the corresponding
268 unshaded global measurement. These inferred beam measurements, if their value is greater
269 than zero, are then processed for aerosol optical depth. As explained in many papers
270 (Harrison and Michalsky, 1994; Michalsky et al., 2010; Sanchez-Romero et al., 2016), this
271 process has several steps, including continuous Langley calibration of the spectral sensors,
272 evaluation of total optical depth, subtraction of Rayleigh and ozone extinction, and –more
273 importantly here– cloud screening. Thus, after the first three steps, an optical depth (OD, that
274 might be due to water droplets or ice crystals, or aerosol particles, or both) for each
275 wavelength but the longest (940 nm), which is affected by water vapor absorption, is
276 computed. Using two of these values (OD at 500 and 870 nm) the Ångström exponent, that
277 accounts for the wavelength variation of OD and varies inversely with the particle size, is
278 also estimated. These values then must go through scrutiny to distinguish those that actually
279 correspond to the effect of aerosols in the atmosphere from those which are affected by
280 (necessarily) thin clouds. Obviously, a number of cases correspond to situations that cannot
281 be clearly identified as either clouds or aerosol, but in general, the cloud screening procedures
282 routinely implemented are conservative in the sense that they tend to guarantee that the
283 filtered cases are free of “cloud contamination.”

284 There are in the literature several suggestions for cloud screening the OD data from MFRSR.
285 The SURFRAD network applies the technique described in Augustine et al. (2008) that is a
286 hybrid of the cloud screening methods of Michalsky et al. (2010) and Alexandrov et al.
287 (2004). As in the case of identifying clear skies from solar radiation data, the variability of

288 the measurement is the basis of all methods: the underlying assumption is that clouds make
289 solar radiation (either broadband or spectral) more variable in time than aerosols. Here we
290 will use the methodology as presented by Michalsky et al. (2010), which consists of two
291 filters applied consecutively on a moving time window of a given width (10 minutes in the
292 original paper). The first, coarser filter takes the difference between each adjacent
293 measurement, and also calculates the maximum minus the minimum OD in the window. If all
294 differences are less than a given threshold, and if the range of measured OD within the time
295 window is less than another threshold, then the points pass the first filter. The second, more
296 stringent filter scales the allowed variability according to the magnitude of the OD, which is
297 estimated by applying a low-pass filter on the series. Thus, the absolute value of the largest
298 difference between adjacent data must be less than a given fraction of the estimated OD at the
299 midpoint of the sample window, and the range must be less than another fraction of the same
300 estimate. The values of the four thresholds were 0.02 and 0.03 (absolute differences of OD at
301 550 nm) and 10 and 20% respectively in the original paper. In the present study, we will
302 change these four values, and also the time window where differences and ranges are
303 calculated, to assess their effect regarding “transition” cases. The final result of the MFRSR
304 cloud screening is every sample tagged as “good” or “bad,” meaning that can be
305 representative of aerosols or not. In the current paper, we will assume that samples labeled as
306 “bad” correspond to the presence of some kind of clouds.

307 As mentioned above, images of the whole sky are becoming more ubiquitous both in
308 atmospheric research and in solar energy management applications. Automatically captured
309 sky images allow a continuous (many such cameras take images every minute or even more
310 often) visible record of the sky. Images can then be visually scrutinized to identify clouds,
311 aerosols, rain, and any other meteors. Usually, however, an automatic digital image analysis
312 is set to obtain an estimation of the fractional sky cover and (sometimes) other sky or cloud
313 characteristics. In the present research, one year of 1-minute sky images taken at Girona have
314 been visually inspected and tagged according the presence of situations where the distinction
315 between clouds and aerosols is unclear. In addition, one year of 1-minute images taken by the
316 TSI at Table Mountain have undergone digital processing to account for the fractions of sky
317 that is free of cloudiness, or covered by optically thin and thick clouds. The basis of the
318 distinction is the ratio between the red and the blue intensities (R/B) in the RGB image: a
319 clear (blue) pixel has a low value of R/B, while a cloud (white) pixel has a greater value. In
320 this case, the process uses mainly two R/B thresholds referenced to the baseline clear-sky
321 threshold set by the manufacturer to make these distinctions: one to distinguish between clear
322 sky and thin cloud, a second one to separate between thin and thick clouds. As explained
323 elsewhere (Long, 2010; Long et al., 2006b), a post-image-processing algorithm addresses
324 issues in regions of particular difficulty (a circle around the Sun, the region close the horizon
325 in the direction of the Sun), which occur due to forward scattering of visible light by aerosols
326 and haze, and the intensity range limitations of the detectors of the cameras used to record the
327 sky images. But in our analysis, we have focused mainly on the threshold that affects the
328 distinction between clear sky (with more or less aerosol content) and thin clouds.

329

330 **4. Results**

331 *4.1 Clear sky detection and cloud cover estimation from radiation flux analysis*

332 RadFlux analysis results for Girona, 2014 are presented below. The analysis was applied
333 twice, with values of Max_Diff equal to 100 and 200 W m⁻². We also checked the value of
334 300 W m⁻², but those results were nearly the same as those for the 200 W m⁻² setting,
335 indicating that when such high values of diffuse radiation are in principle set to correspond to
336 clear sky, other tests for clear-sky detection filter out these cases anyway. It should be noted
337 that even with the lower threshold, the diffuse irradiance allowed as “clear sky” is well above
338 the Rayleigh limit, i.e., a certain amount of scattering particles larger than molecular is
339 always allowed. A summary of results is presented in Table 1. There are almost 11,000
340 minutes identified as clear when the higher threshold is used but labeled as not clear when the
341 lower threshold is applied. This means that almost 5% of the daylight hours (specifically, of
342 the time when the Sun is more than 10° above the horizon, a condition for the RadFlux
343 algorithm to identify clear skies), may be considered clear or not depending on where we set
344 the maximum allowed diffuse limit. These situations often correspond to what can be
345 generically called “haze,” that is conditions that can hardly be classified as either cloud or dry
346 aerosol. For Boulder, results are similar. More than 15,000 minutes (7.5%) are considered
347 clear or not depending on the Max_Diff value (here the two tested values were 100 and 180
348 W m⁻²).

349 The difference in mean *fsc* when data are processed with one or the other threshold is 0.023
350 (0.022) in Girona (Boulder). This difference might not seem very large, but, as we will show
351 below, it is produced by larger differences for some particular conditions. Thus, differences
352 between the mean *fsc* when one or the other clear sky reference is used (i.e. based on clear
353 sky periods identified by using one or the other Max_Diff value) increase significantly when
354 cloudless and overcast conditions are not considered. Indeed (see Table 1), for scattered to
355 broken cloud conditions, the average difference is 0.044 (0.046), which is more than 10% of
356 the average *fsc* of about 0.4 at both sites. Logically, since RadFlux uses the difference
357 between measured and estimated clear-sky diffuse as the basis for *fsc* estimation, estimated
358 *fsc* tends to be lower when Max_Diff is greater. In absolute value, differences tend to be
359 greater for lower *fsc* (see Figure 1 corresponding to Girona data). Table 2 summarizes the
360 number of records with significant differences in *fsc*. It is worth noting that for about 15,000
361 (17,000) minutes the difference is greater than 0.10. This means that in about 14% (17%) of
362 non-cloudless and non-overcast cases, the average difference of *fsc* is a relatively high value
363 of 0.16 (0.15).

364 We will next present the evolution of solar radiation and results of RadFlux (and also from
365 MFRSR) for some particular days, as examples of the behavior of the algorithm with regard
366 to the objectives of the present research. The mean values of *fsc* for these days when using
367 the two Max_Diff values are shown in Fig. 1. Figure 2 presents in detail measurements and
368 processed results for two days that, based on visual inspection of the images (see Figure 3)
369 and the RadFlux with the greater threshold, are considered to be clear. March 6, 2014, is an
370 example of a cloudless and very clean atmosphere day. Measured diffuse and direct

371 (projected onto a horizontal surface) irradiances match almost exactly their clear sky
372 estimates. It should be noted that for this day, no significant difference exists between the
373 estimate of clear sky diffuse irradiance after using one or the other threshold of Max_Diff. As
374 a consequence, for this day, the estimate of f_{sc} is zero, whatever the threshold used.
375 Consistently, the MFRSR cloud screening algorithm flagged almost all minutes as “good”
376 (i.e., not contaminated by clouds), and the OD at 500 nm is less than 0.1 for the whole day,
377 while the Ångström exponent (AE) evolves between 1 and 2, indicating relatively small
378 particles. For June 21, 2014, both diffuse and direct irradiances follow a relatively smooth
379 evolution that matches the clear sky estimates quite well. For diffuse, this is true if the clear
380 sky estimate corresponds to the higher threshold. Therefore, if the higher Max_Diff is used,
381 the RadFlux produces an almost cloudless day (f_{sc} is very close to zero, with a daily average
382 of 0.02). In contrast, when a Max_Diff = 100 W m⁻² is used, not a single minute is considered
383 clear, and the f_{sc} is estimated to be between 0.2 and 0.4 (daily mean, 0.27). As mentioned
384 above, however, there are no “visible” clouds in the sky, and in fact, the MFRSR cloud
385 screening algorithm labels all records of this day as “good.” Nevertheless, the AOD for this
386 day is relatively high (0.15-0.30) and, more significantly, the AE is low (0.4-0.9) indicating,
387 as suspected, larger (and/or hydrated) particles.

388 Two particular cases of days with variable cloudiness are presented in Figure 4: one presents
389 almost exactly equal f_{sc} estimations, while the other presents notable f_{sc} differences between
390 the two estimations. As can be seen in the corresponding sky images (Figure 5), the first day
391 (April 24) shows middle and high clouds, and low aerosol load, which is confirmed by the
392 MFRSR OD data: for the times that pass the cloud screening, OD is around 0.15 and AE is
393 around 1.5. But the second day (June 23) has low level clouds in a more “whitish” sky, which
394 results from a greater OD (0.25) and lower AE (< 1).

395 *4.2 MFRSR estimations of OD and AE, and cloud screening*

396 Figure 6 shows the behavior of the Ångström exponent versus the optical depth at 500 nm,
397 for all instantaneous measurements that are processed by the MFRSR algorithm, that is for all
398 instances when there is some direct irradiance and the solar zenith angle is less than 80°.
399 These are measurements from Girona for the year 2014. The whole unscreened dataset of
400 measurements are represented by black circles. It should be noted that plotted is the optical
401 depth of whatever is in the atmosphere (other than well-mixed gases and ozone) as we don't
402 know, in principle, if this optical depth is due to dry particles, water droplets or ice crystals.
403 There are many points with negative values of AE, which must be the result of the
404 uncertainties of the method to estimate AE. As shown by Sanchez-Romero et al. (2016), the
405 uncertainty attached to AE computation is of the order of 0.5 for OD values of about 0.1, and
406 greater for lower OD values. Therefore, when the true value of AE should be close to 0, the
407 random error associated with this uncertainty may result in negative values. A deeper analysis
408 of the effect of OD measurement errors on the computation of AE that explains how negative
409 AE values may be obtained, was developed by Wagner and Silva (2008). Their results
410 discourage the computation of AE when OD is less than 0.15, given the typical uncertainties
411 of the current instrumentation. That same study shows that the error in the AE estimation may
412 be skewed depending on the relative errors of each of the monochromatic ODs used.

413 The data points highlighted in red in Fig. 6 are all those that have passed the cloud screening
414 filter (i.e., labeled as “good”). Initially (Fig. 6a) we used the same time window and threshold
415 values for cloud screening as suggested in Michalsky et al. (2010). Subsequently, we changed
416 these values as summarized in Table 3. Changing the time window means that the filter
417 would take into consideration the variability of the computed OD over a shorter or a longer
418 period. Changing the other thresholds would mean that the filter accepts aerosol conditions
419 that show more or less variability. With the default cloud screening, 42% of points are
420 considered representative of atmospheric aerosol. Most of these points have $OD < 0.5$ and
421 AE between 0 and 2. The sensitivity analysis showed that shortening the time window has an
422 important effect of allowing more points to be considered aerosol. In contrast, lowering the
423 thresholds corresponding to relative values of differences and range substantially reduces the
424 number of points that pass the filter. We combined a shorter time window and higher values
425 of the thresholds to apply a “relaxed” cloud screening or conversely a longer time window
426 and lower thresholds to produce a more “strict” filter. When the former is applied, almost
427 58% of points are considered aerosol (Fig. 5b), but when the latter is used, less than 19% of
428 the points pass the filter (Fig. 5c). With very few exceptions, all points with $OD > 1.0$ and
429 most points with negative AE (and $OD > 0.1$) do not pass the cloud screening even with the
430 relaxed filter.

431 The numbers in Table 3 allow an estimation of the frequency of transition cases between
432 cloud and “pure” aerosol. We start with about 420,000 instantaneous measurements for
433 Girona performed by the MFRSR with solar zenith angle less than 80° (it should be noted
434 that this number is a combination of 1-min measurements during 9 months plus 15-sec
435 measurements during 3 months). From these, about 212,000 (50.5%) are not processed by the
436 MFRSR, due to the presence of clouds thick enough to occult the Sun and to preclude
437 obtaining valid optical depth results. From the rest of the samples (208,000) about 88,000
438 additional points must be considered clouds, as even the most relaxed cloud screening labels
439 them as “bad.” Therefore, in about 70% of instances, there are clouds (either optically thick
440 or thin) in front of the Sun. This “cloud occurrence” might be eventually an estimation of the
441 mean cloudiness, but it should be noted that only clouds that are in front of the Sun from the
442 perspective of the MFRSR are considered by the cloud screening algorithm, so it is not a
443 hemispheric view of the sky. In other words, whereas the clear sky identification from the
444 RadFlux refers to the whole hemispheric sky view, the cloud screening for the MFRSR refers
445 only to the direct sun, not the whole sky. From the rest of the samples, we can almost assure
446 (according to the result of applying the “strict” cloud screening) that about 39,000 data points
447 correspond to clear sky (in the direction of the Sun beam) affected by a certain amount of
448 aerosols. This means that about 81,000 measurements (19% of the initial number) are
449 affected by particles in the atmosphere that are problematic in being classified as aerosol or
450 as cloud, at least based on the cloud screening applied which is built upon the assumption that
451 clouds induce higher variability than aerosols in the measured irradiances.

452 The discussion above concerns results from Girona. When the same analysis is applied to
453 measurements from Boulder, the numbers obviously change, but not the main result of a large
454 percentage of cases in the transition zone. We started with 610,000 instantaneous

455 measurements (note that 20-sec resolution was used in Boulder for the whole year) from
456 which about 158,000 (25%) were not processed by the MFRSR, due to thick clouds occulting
457 the Sun. Then we applied the three cloud screenings (default, relaxed, strict) to the rest of the
458 samples (452,000, see Table 3). About 242,000 additional points were labeled as “bad” (i.e.
459 clouds) by the relaxed cloud screening, so in a total of 66% of instances there are clouds
460 before the Sun (note the important difference between the number of thick and thin clouds as
461 compared with Girona). From the remaining data, about 37,000 data points correspond to a
462 cloudless sky affected by aerosols. This means that about 173,000 measurements (28% of the
463 initial total) correspond to the kind of particle suspension that represents the transition region
464 between aerosols and clouds, at least regarding the observations by the MFRSR, which are
465 mostly affected by what is present in the direction of the Sun.

466 Again for Girona and for the four days analyzed in Figs. 2 and 4, Figure 7 presents the
467 periods that passed the MFRSR cloud screening (i.e., the calculated OD is considered to be
468 due to aerosols) for the three different settings (default, strict, relaxed). The first two days are
469 considered cloudless by the default screening (and obviously, by the relaxed one), and also
470 mostly cloudless by the strict screening. Somewhat surprisingly, a period of the first day
471 (10:00-11:30 approximately) is filtered out by the strict screening, owing to a relatively high
472 variability of the signal despite that sky images and the RadFlux analysis indicate that this is
473 a totally cloud free, clean day. Conversely, the second day raises some doubts about what it is
474 in the air according to images and RadFlux, but is considered almost totally cloudless even by
475 the strict MFRSR screening.

476 With all this in mind, we find that the variability of the optical depth (which is intended to
477 reflect the variability in the atmosphere, although we cannot rule out some contribution from
478 the instrument’s noise when the signal is very low) is not sufficient to discriminate between
479 cloud and aerosol. The optical depth itself and its wavelength dependence (AE) do not help
480 very much in this distinction (despite that Kassianov et al. 2013 suggested a method that
481 worked well for their Arctic site). Figure 8 shows the histograms of the populations of points
482 screened out as clouds (this is for Girona, so 88,000 points), points that passed the strict filter
483 so they are considered aerosol (39,000), and points that belong to the transitional zone
484 (81,000), as a function of OD and AE. It is obvious that the filter does a good job as the
485 dominant OD and AE values for clouds and aerosols respectively are quite different among
486 them (despite some data with large AE is labeled as cloud, and other minor inconsistencies
487 are found as well). But it is also apparent that the third group of points presents values of OD
488 and AE that cover a very broad range. Even if we assume that all points with $OD < 0.032$ or
489 $AE > 1.6$ must be considered aerosols, and all points with $OD > 0.32$ or $AE < 0.15$ must be
490 considered clouds (these values derived from the percentiles 1 and 99 of the distributions of
491 cloud and aerosol points), there are still about 58,900 points within the range of OD [0.032-
492 0.32] and AE [0.15 – 1.6] for which their corresponding variability is not either high enough
493 to be considered clouds nor low enough to be considered aerosols without some doubts. This
494 number represents 14% of the initial measurements and 28% of the instances processed by
495 the MFRSR. The corresponding relative values for Boulder data are 10.7% and 14.5%. It
496 should be noted that the previous thresholds for OD and AE, based upon the statistical

497 distributions of our data, must not be taken for general application to all atmospheric
498 situations. For example, Antón et al. (2012) found a very large OD (0.8-1.5) and very low AE
499 (0.1-0.25) under a strong Saharan dust event.

500 *4.3 Images from sky cameras*

501 For Girona, there are about 200,000 total sky images corresponding to 341 days during the
502 year 2014. The most significant gap in the series of sky images corresponds to the first
503 fourteen days of the year (there are also some missing days in April and June). Since visually
504 inspecting each and every one of these images is unfeasible, we built a movie for each day by
505 displaying all images successively. Watching these movies is much more practical, and
506 allows identifying the most important features in the images. Once some particularly
507 interesting days or periods within a day were selected, the individual images were visually
508 inspected in more detail. Some examples of these images have already been used to discuss
509 previous results (see Fig. 3 and Fig. 5). Overall, there is a high percentage of days when we
510 have detected some period (that may last less than one hour or may last the whole daylight
511 time) of challenging distinction between clouds and aerosols (40% of days). Indeed, most of
512 the other days (those without doubtful periods) correspond to mostly overcast days, or,
513 exceptionally, to unusually clear days. Regarding the challenging periods, there are a few
514 different situations. First are relatively clean and apparently cloudless skies where a kind of a
515 thin “veil” can be seen in the images, without an analyst being able to subjectively discern
516 whether it is made up of dry aerosols or extremely thin clouds (either low or high). Second
517 are hazy or foggy skies with corresponding difficulties in affirming what kind of suspension
518 is causing the haziness. Third are skies with scattered or broken clouds (typically, cumulus)
519 that have poorly defined boundaries or are continuously forming and vanishing, which makes
520 it difficult to decide whether a portion of the sky is cloudless or not.

521 We have been able to perform a more quantitative analysis on TSI images from the Boulder
522 site. In 2014, there are 217 days with images every 1 minute, which translates to 145,000
523 images being processed. The missing periods correspond to most of January, April, and July,
524 with some additional missing days randomly distributed across the other months. Main
525 reasons for missing images are a malfunctioning camera or rotating mirror, but sometimes the
526 outages are due to inclement weather. The original processing of the images produced an
527 average cloud fraction of 0.62 of which 0.13 is considered thin cloud (again, in average for
528 all images). These numbers are the result of using the SURFRAD operator settings in the TSI
529 image processing for the Table Mountain site, i.e. a nominal R/B threshold between clear sky
530 and thin clouds of 0.30 and an effective threshold between thin and thick clouds of 0.57. To
531 test the sensitivity of the cloud fraction results to the first threshold, we first lowered it to
532 0.20, and then raised it to 0.40. This produced, respectively, an increase in average *fsc* to
533 0.68, and a decrease to 0.57, mainly due to the change of the amount of thin clouds (since we
534 kept the thin to thick cloud threshold the same). It should be noted that the range of total
535 cloud fraction from TSI estimates (0.57-0.68) is relatively close to the estimate from the
536 Rad_Flux (0.54-0.56) and to the cloud occurrence found by the MFRSR (0.66), with the
537 difference likely mostly related to the circumsolar and near horizon issues described in Long

538 (2010) and Long et al. (2006b), besides different field of view (for MFRSR) and slightly
539 different periods (due to missing data or images).

540 More important than these aggregate numbers is to look at the particular cases with large (or
541 small) cloud fraction changes when the threshold is changed. In this sense, Table 4 shows the
542 differences in thin cloud fraction between the original processing and new processing using
543 two modified thresholds. For the case of the reduced threshold, the thin cloud fraction
544 estimate in almost 80% of images increases by less than 0.10. This of course includes those
545 images that presented a very high cloud fraction (overcast, or almost overcast), but there are
546 also a large number of images for which the change is very small independently of their
547 cloudiness. This illustrates the robustness of the digital image processing of TSI images, i.e.,
548 it shows that even if the “correct” threshold is unknown, the cloud fraction estimate is, in
549 general, quite consistent. Figure 9a presents an example of these cases: a totally cloudless
550 image, which is considered as such even by the lower threshold used. Similarly, Fig. 9b
551 shows a broken cloud sky, where again changing the threshold does not affect the result as
552 the clouds have very well defined limits and the sky is very clean (blue). On the other
553 extreme, more than 20% of images exhibit a change in the estimate of the thin cloud fraction
554 greater than 0.10 with the changing thresholds. It should be noted that this increase is not
555 always reflected in an equivalent increase of the total cloud fraction, since the sophisticated
556 algorithm that sets the particular thresholds that are used in each region of each image may
557 result in slight changes of the opaque cloud fraction too. Fig. 9c shows a sample of an image
558 where the change in the threshold produces a large change in the thin cloud fraction, because
559 a large part of that image is made up of what seems very thin clouds. In the example of Fig.
560 9d, the large differences seem to be related to a relatively high atmospheric aerosol load.

561 For the case of the increased threshold, the thin cloud fraction estimate in a little more than
562 80% of images decreases by less than 0.10 (Table 4). This includes a) some situations of
563 cloudless skies, b) situations with scattered to broken cloudiness but with a low amount of
564 thin clouds (in these two cases, the increase of the threshold of course makes it impossible to
565 get lower cloud fractions), and c) situations of overcast skies with thick clouds, that present
566 much higher values of the red to blue ratio (or that are set as cloudy because of very low light
567 intensity, i.e., very thick clouds). Again, this result confirms that the method is quite robust,
568 and also that almost 20% of time a change in the threshold produces a change in the thin
569 cloud fraction of more than 0.1. In Figures 9a-f the result of the cloud identification with the
570 higher threshold is also displayed, and we can see the moderate effect on cases of Fig. 9c and
571 9d, corresponding to clouds (or aerosols) with not well defined limits and that are mainly
572 visible when they are in front of the Sun due to their forward scattering characteristics. The
573 greatest effect of changing the threshold is found in situations such as those presented in Fig.
574 9e and 9f, where the hazy atmosphere (involving cumulus clouds formation) is too
575 problematic to be classified as “clear” or “cloudy” with thin or even opaque clouds by the
576 method applied to TSI raw images. It should be noted that in the cases where the effect of
577 changing the threshold is small (Fig. 9a and 9b), the optical depth as measured by the
578 MFRSR was also very low (around 0.02), while for the rest of cases (Fig. 9c-f) the optical
579 depth (in the nearest periods when is available) is always greater than 0.1 and in fact, close to

580 0.2, which is the value that Dupont et al. (2008) found as the limit related to the more
581 common differentiation between cloud and not cloud.

582 **5. Discussion, summary and conclusion**

583 We have presented observations from three ground based, passive systems, that are intended
584 to detect clouds and aerosols in the atmosphere. Indeed the three systems share one
585 characteristic, which is that they are sensitive to the solar radiation flux once it has been
586 modified (affected) by the presence of suspended particles in the air (of course, solar
587 radiation flux is also affected by atmospheric gases). Thus, sky cameras “map” radiation
588 coming from the whole sky dome and record this radiation in three color channels (red,
589 green, blue). The presence in the intervening atmosphere of particles (whether in the form of
590 clouds or aerosol) modifies the aspect of the sky, that is the partitioning of light
591 corresponding to each color. Broadband radiometers perceive the effect of clouds and
592 aerosols as these modify the total amount of solar radiation reaching the ground, and/or the
593 partitioning of radiation between the direct and diffuse components. Finally, the MFRSR
594 determines the effect on the direct solar beam so it can estimate the optical depth resulting
595 from the absorption and scattering (i.e. attenuation) phenomena associated with the
596 suspended particles. Since the latter is a spectral instrument, it can be used to evaluate optical
597 depths for several wavelengths and therefore, the variation of the optical depth with
598 wavelength, which is related with the size and characteristics of the particles.

599 The general conclusion of the analyses performed here is that the number of challenging
600 cases where distinction between aerosol and cloud is nebulous (in fact, only subjectively
601 resolved) is not negligible, for at least the two mid-latitude sites analyzed and for the
602 instruments used. A very rough estimate of the frequency of instances when the mentioned
603 cloud-aerosol distinction is challenging is a figure not less than 10%. This number includes
604 those cases that are cloudless in principle, but with a very thin veil in the sky that is hardly
605 visible but affects the partitioning of the solar radiation in the diffuse and direct components
606 (5 and 7.5% of time according to RadFlux in Girona and Boulder respectively, Section 4.1).
607 This gross estimate also includes cases with scattered and broken clouds, when the cloud
608 limits are not very definite, or when there is a suspension that somewhat attenuates the direct
609 beam in the “clear” patches between clouds. According with the MFRSR datasets and applied
610 analyses, the lowest estimates of these situations at Boulder and Girona respectively are 10.7
611 and 14% (Section 4.2). In all these cases the spectral signature of solar radiation is also
612 affected, which is reflected in the computation of the Ångström exponent. These numbers are
613 also in agreement with what we find from the sky images. The sensitivity analysis performed
614 showed that changing the threshold that distinguishes clear sky and thin cloud, which is
615 essentially how “whitish” the cloud-free sky (includes cases with relatively high aerosol) is
616 allowed to be, produces large differences (in the “thin” cloud fraction) a significant amount
617 of time. Specifically, we find a change in the thin cloud fraction of more than 0.1 in about
618 20% of images (Section 4.3). This latter result is for Boulder, but for Girona, a visual
619 inspection of images suggests similar results.

620 These values are quite in agreement with the few previous numbers given in the literature,
621 although they are not directly comparable. Indeed, Koren et al. (2007) estimated that between
622 30 and 60% of the part of the globe at any given time considered to be free of clouds could
623 correspond to the challenging characteristics transitioning between clouds and aerosols
624 (which they called “twilight zone”). Similarly, for a particular area of the Atlantic Ocean,
625 Bar-Or et al. (2010) found a value of about 35-45%. In these latter studies, a spatial approach
626 was considered, i.e., they accounted for the extension of this zone in a snapshot of the sky.
627 Our study, however, combines this approach (for sky camera images and partially for
628 broadband hemispheric solar radiation measurements) with a temporal approach, that is
629 accounting how often the atmosphere presents a state that cannot be distinctly categorized as
630 cloud or as aerosol (for broadband hemispheric radiation measurements and also for MFRSR,
631 Sun pointing, measurements). Therefore, our numbers correspond mainly to temporal
632 frequencies, are limited to two particular sites, and are quite conservative, but if we discard
633 the overcast conditions, the relative frequency of the transition cases increases to more than
634 15% of the remaining cases (this number is estimated by dividing the above overall value of
635 10% by the frequency of non-overcast cases, which is about 70% at the two involved sites).

636 Our results support the argument that clouds and aerosol are two extreme manifestations of
637 the same physical phenomenon, which is a suspension of particles in the atmosphere. This
638 reasoning was already suggested by other authors (e.g., Charlson et al. 2007). This of course
639 could be questioned, as the origin and the many processes involved differ quite a lot. On the
640 one hand, processes involved in producing different types of aerosols such as sea salt spray,
641 secondary pollutant particles, forest fire smoke, and desert dust, may be quite different. Also
642 different are processes leading to the formation of different types of clouds: for example
643 maritime thin stratus, cumulonimbus, or high ice clouds. Therefore, we can conclude that a
644 suspension of particles in the air may have many different origins, compositions, properties,
645 etc., but, despite their differences of origin and composition, their radiative effect as seen
646 from the ground does not easily distinguish the type of suspension. In particular, at times we
647 cannot classify the suspension in either of the two most usual cases: clouds (relatively large
648 condensed water particles) and aerosols (relatively small dry particles). Difficulties in
649 separating these cases may result from the fact that the instruments have a hemispheric view
650 of the sky (pyranometers, cameras) which may integrate radiation fluxes (radiances) that,
651 separately, could be distinctly affected by clouds or aerosols. Or even in the case of
652 directional measurements (such as the MFRSR measurements), the solar beam attenuation
653 that is obtained is the result of the light crossing through different layers of the atmosphere
654 which may contain a cloud at some height and suspended aerosols at other heights.

655 Many cases may correspond to a situation where the particles in the suspension show
656 characteristics (size and composition) that are somewhere in between what is typically
657 considered cloud and aerosol. In these situations, it might not make sense trying to classify
658 the suspension as a cloud or aerosol. Rather, it might be more convenient to treat the
659 phenomena as a continuum, of which the extremes would be the entities corresponding to the
660 usual definitions of cloud and aerosol, but with a non-negligible number of intermediate
661 conditions (Charlson et al., 2007). The two most common situations with the characteristics

662 in the “middle” of the continuum are those with clear skies with a thin veil showing some sort
663 of structure, and those with partly cloudy skies with poorly defined cloud boundaries (Koren
664 et al., 2008, 2009).

665 Although other active cloud observation instruments (such as ceilometers, radars, microwave
666 radiometers) do provide more detailed information on cloud structure and particles forming
667 the clouds, they in fact also support the case of a continuum of properties, and of the
668 difficulty in setting precise limits on what must be labeled as a cloud (Boers et al., 2010).
669 Similarly, the use of radiance measurements in several directions of the sky dome, as for
670 example those performed by CE-318 sunphotometers (CIMEL Electronique, France), can
671 map the presence of clouds in selected planes so helping in the detection of clouds and the
672 distinction from pure aerosol. The quantification of the transition situations as seen from
673 these other instruments could be a matter of future research.

674 As for the consequences of the above conclusions and suggestions, we think that considering
675 the intermediate situations between cloud and aerosol may have a significant impact in
676 energy balance studies, either local or global, and must be taken into account when
677 parameterizing radiation transfer within weather and climate models. The point here is that
678 cloud-screening algorithms for aerosol products and cloud detection algorithms for cloud
679 products both tend to be conservative, which bias both sets of products in a way that the
680 transition area is maximally omitted from products. For example, when considering scattered
681 cloud conditions, assuming that there are, or are not, condensed particles in the patches
682 between clouds will produce different downward and upward radiation fluxes (both in the
683 solar and in the thermal infrared bands), that would be different also from what is actually
684 observed by radiometers on the ground. The properties of the suspended particles that are
685 around or between the clouds are also relevant where radiation transfer is concerned (Schmidt
686 et al., 2009). High spatial resolution observations of cloud boundaries, such as in Schwartz et
687 al. (2017) where cloud structure is examined on scales 3 to 5 orders of magnitude finer than
688 satellite products, or high temporal sampling of radiation spectra at cloud boundaries by using
689 array spectrometers (González et al., 2017), open new paths for examination the cloud-
690 aerosol conundrum. Even if a homogeneous stratified atmosphere is assumed in a given
691 region, considering that there is a layer of a very thin cloud or a layer of aerosol particles
692 having differentiated radiative properties may also result in different estimates of the
693 radiation fluxes. If possible, it would be more realistic and accurate to treat the phenomenon
694 as a continuum in the radiative transfer calculations. Despite the existence of several studies
695 that already address some of these concerns (Charlson et al. 2007; Koren et al. 2008, 2009;
696 Hirsch et al. 2012, 2014; Yang et al. 2016), all these subjects must be the object of further
697 research.

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706

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- 886

887 **Table 1.** Summary of radiation flux analysis results for Girona and Boulder (Table Mountain), year
 888 2014, when using two different thresholds for Max_Diff.

Max_Diff	Girona		Table Mountain	
	100 W m ⁻²	200 W m ⁻²	100 W m ⁻²	180 W m ⁻²
Minutes analyzed	220,658		214,616	
Clear-sky minutes	25,998	36,988	33,813	49,587
Average fractional cloud cover, <i>fsc</i>	0.555	0.532	0.560	0.538
Average <i>fsc</i> for non-cloudless and non-overcast cases	0.430	0.386	0.441	0.395

889

890 **Table 2.** Average differences between the estimated fractional sky cover ($\Delta_{fsc} =$
 891 $fsc_{100} - fsc_{200}$) when using the two different Max_Diff thresholds for clear sky identification,
 892 only for the non-cloudless and non-overcast cases.

	Girona		Table Mountain	
	Number of minutes	$\langle \Delta_{fsc} \rangle$	Number of minutes	$\langle \Delta_{fsc} \rangle$
$\Delta_{fsc} > 0.05$	35,906	0.11	36,626	0.11
$\Delta_{fsc} > 0.10$	15,158	0.16	16,905	0.15
$\Delta_{fsc} > 0.20$	2,765	0.29	1,574	0.24
$\Delta_{fsc} > 0.30$	757	0.41	106	0.36
Total with $fsc_{200} \leq 0.95$ and $fsc_{100} \geq 0.05$	107,281		102,737	

893

894 **Table 3.** Sensitivity analysis of the cloud screening procedure applied to MFRSR measurements. See
 895 Michalsky et al. (2010) for details on the method. Total number of points scrutinized, 208,259
 896 (Girona), 451,793 (Table Mountain).

	Thresholds applied					Number of cases passing the screening	
	Time window (min)	Maximum difference	Maximum range	Maximum relative difference	Maximum relative range	Girona	Table Mountain
Default	10	0.02	0.03	10%	20%	86,701	125,084
1	5	0.02	0.03	10%	20%	103,615	
2	15	0.02	0.03	10%	20%	75,143	
3	10	0.01	0.02	10%	20%	78,604	
4	10	0.03	0.05	10%	20%	90,782	
5	10	0.02	0.03	5%	10%	52,801	
6	10	0.02	0.03	20%	40%	98,146	
Relaxed	5	0.03	0.05	20%	40%	120,221	209,847
Strict	15	0.01	0.02	5%	10%	38,971	37,184

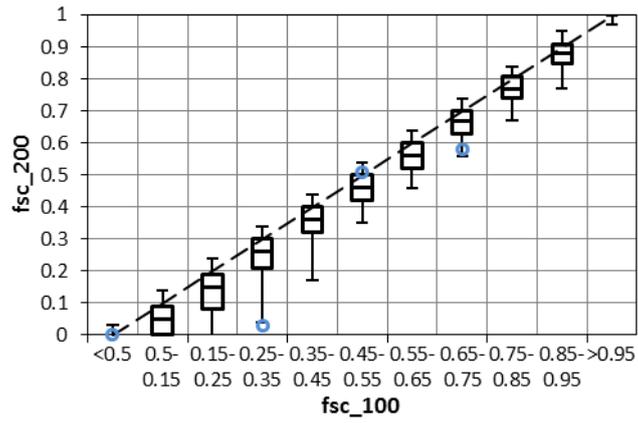
897

898

899 **Table 4.** Frequency of differences in the thin cloud fraction when two different thresholds are applied
 900 in the TSI image processing (instead of the default value of 0.30) for several values of the differences.

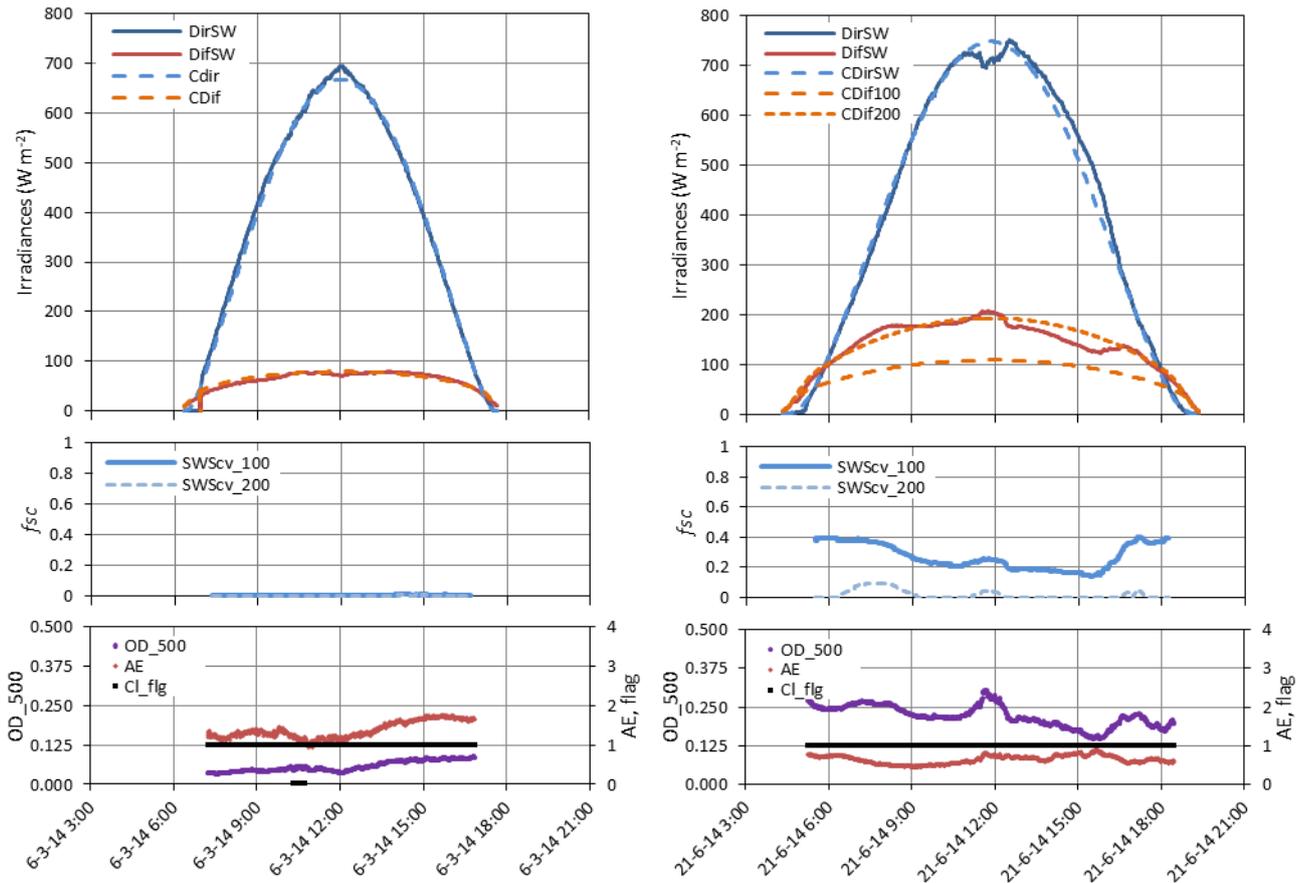
Range of differences	Threshold applied	
	0.20	0.40
≤ -0.30	0.0%	1.0%
$(-0.30, -0.20]$	0.0%	2.8%
$(-0.20, -0.10]$	0.0%	14.6%
$(-0.10, -0.05]$	0.0%	29.3%
$(-0.05, 0)$	0.0%	38.7%
$= 0$	6.2%	13.6%
$(0, 0.05]$	36.3%	0.0%
$[0.05, 0.10)$	35.7%	0.0%
$[0.10, 0.20)$	16.9%	0.0%
$[0.20, 0.30)$	4.3%	0.0%
≥ 0.30	0.7%	0.0%

901



902

903 Figure 1. Box-plot of the *fsc* estimated when using Max_Diff = 200 W m⁻² organized by bins
 904 of the *fsc* estimated when using Max_Diff = 100 W m⁻². Boxes indicate median and 1st and
 905 3rd quartiles, whiskers indicate percentiles 5 and 95. Data is from Girona. Blue circles
 906 indicate the mean values for days presented in Figures 2-5.

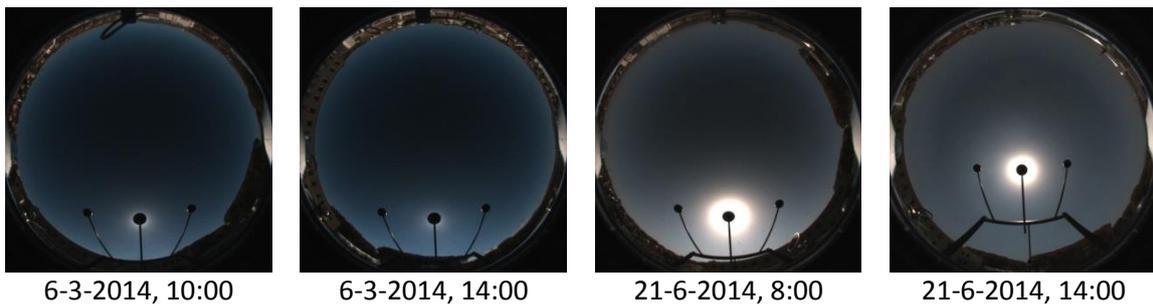


907

908 Figure 2. Two examples of “clear” days at Girona. Left, March 6, 2014; right, June 21, 2014. Top
 909 panels, diffuse and direct irradiances; middle panels, estimation of fractional sky cover; bottom
 910 panels, outputs from the MFRSR: OD, AE, cloud flag.

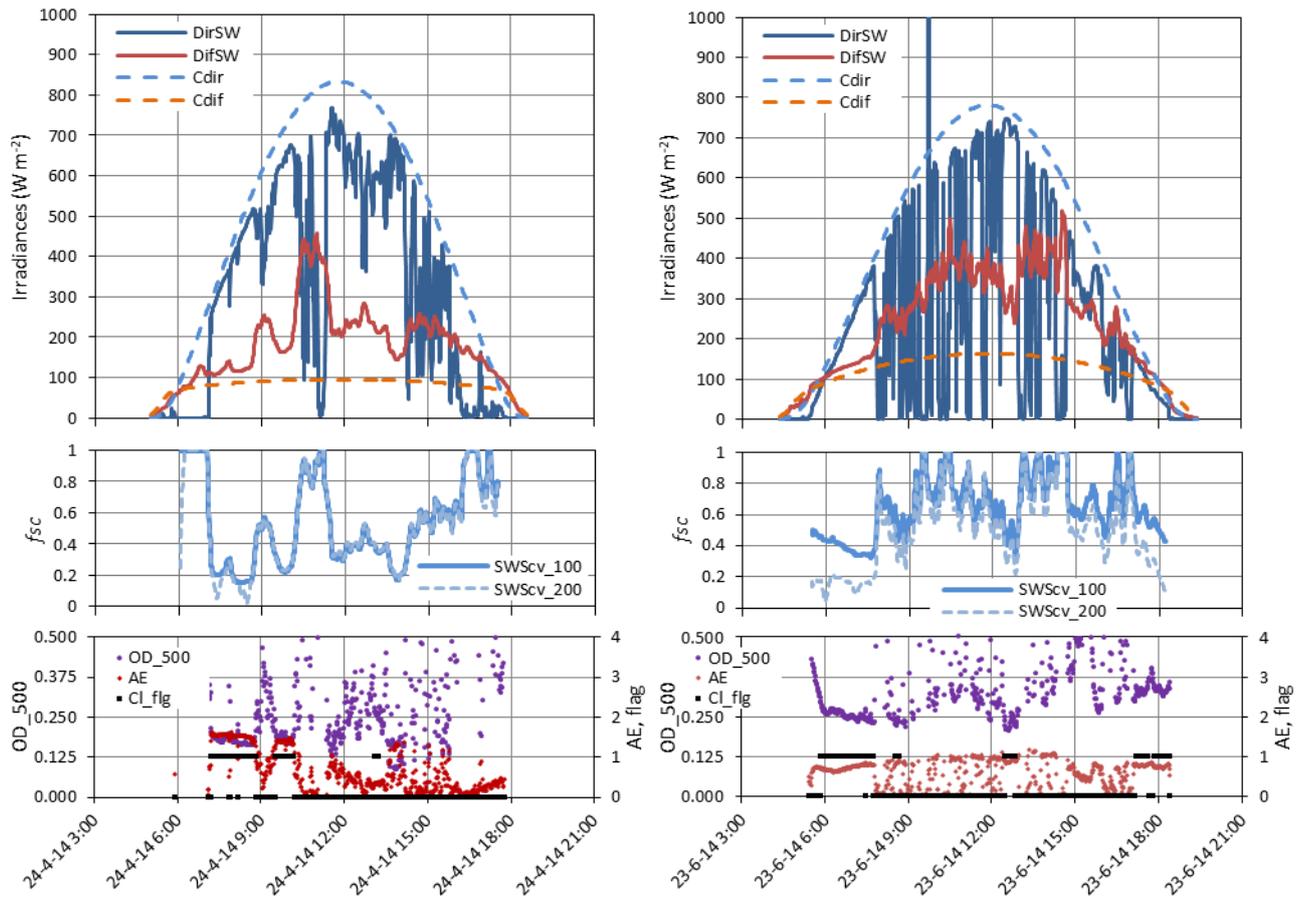
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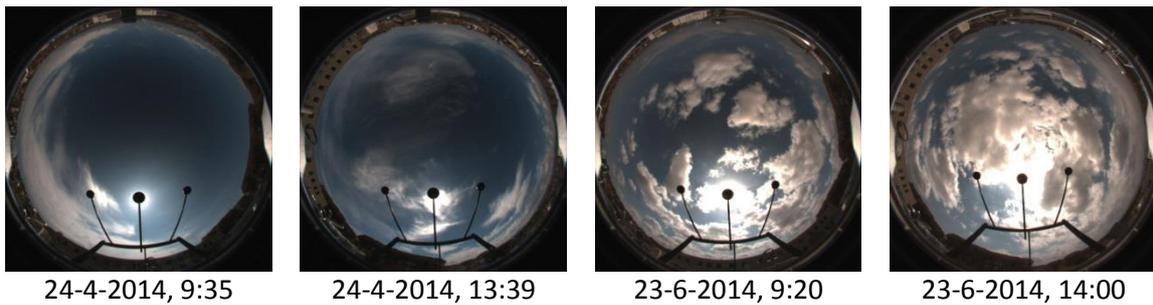
Figure 3. Two sky images for each of the two days represented in Figure 2.



914

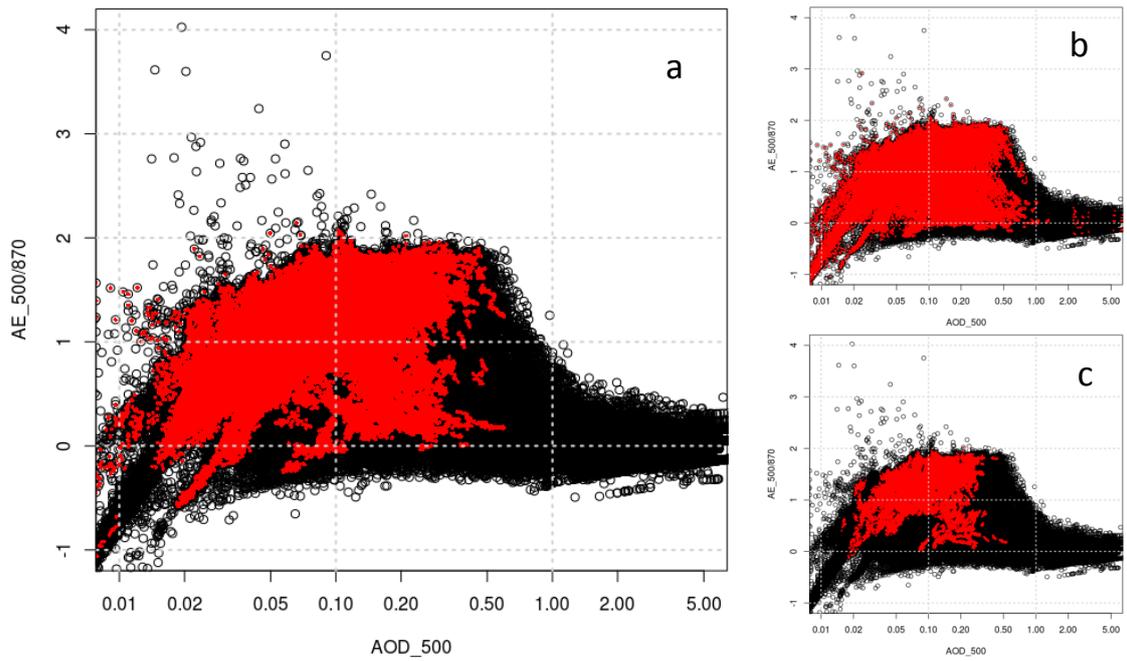
915 Figure 4. Two examples of variable cloudiness days at Girona. Left, April 24, 2014; right, June 23, 2014. Top panels, diffuse and direct irradiances; middle panels, estimation of fractional sky cover; 916 917 bottom panels, outputs from the MFRSR: OD, AE, cloud flag.

918

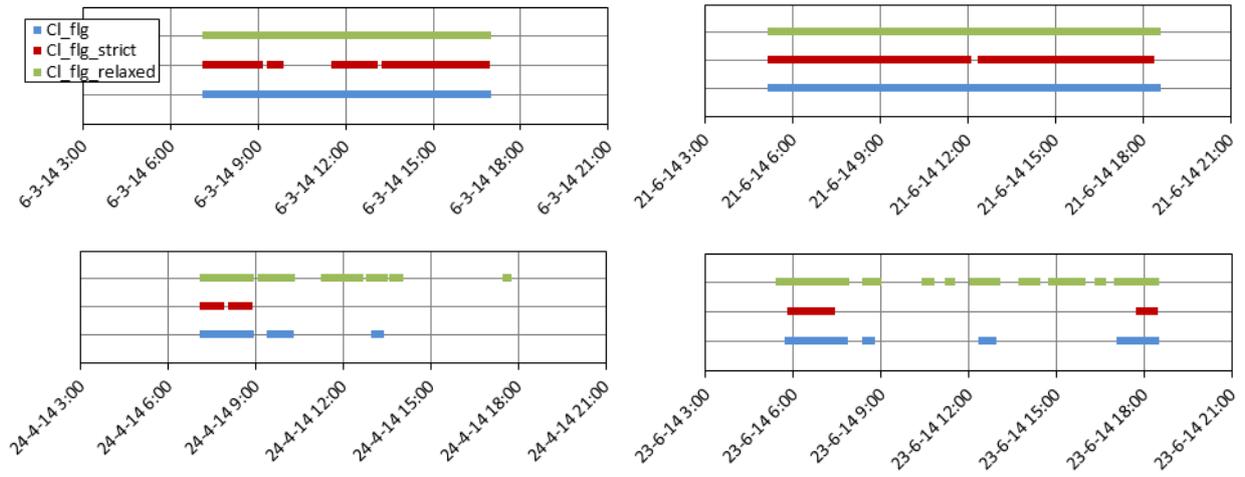


919

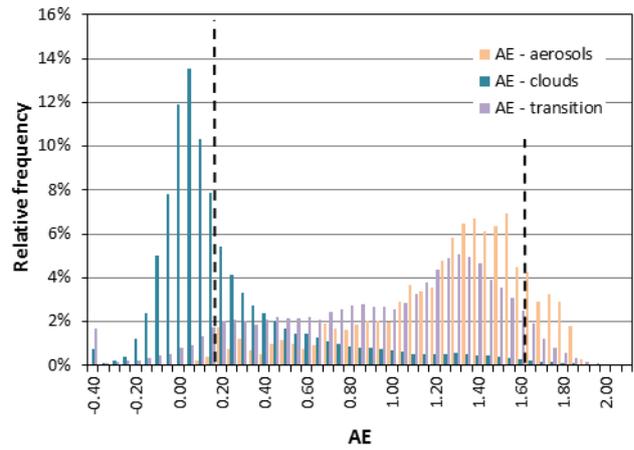
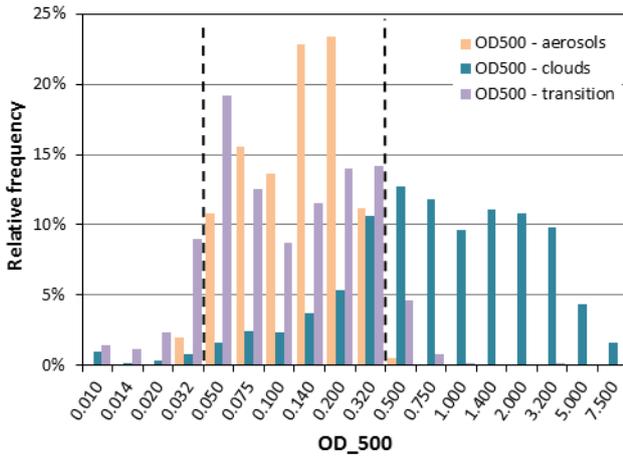
Figure 5. Two sky images for each of the two days represented in Figure 4.



920 Figure 6. The aerosol Ångström exponent (AE) versus the optical depth (OD) at 500 nm as result of
 921 processing the MFRSR spectral measurements of global and diffuse solar radiation. Note the
 922 logarithmic scale of the OD axis. Black circles, all data; red dots, data that pass the cloud screening
 923 filter. a) Default values in the cloud screening; b) “Relaxed” values; c) More “strict” values. It should
 924 be noted that there are points that do not pass the filter which are hidden by the red dots.

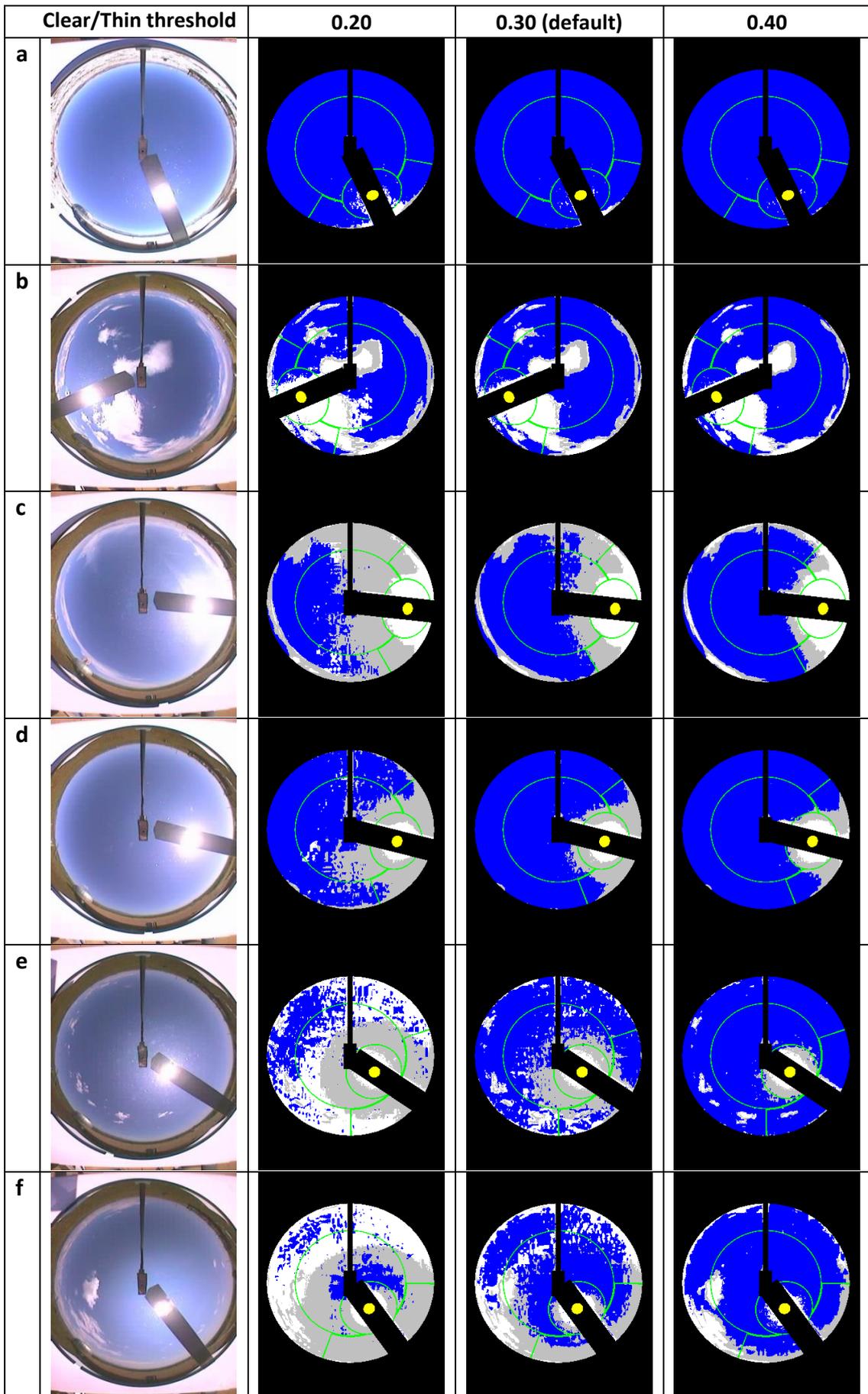


926 Figure 7. For the four days presented in Figures 1 and 3, periods that are considered “aerosols” by the
 927 “default” (blue), “strict” (red), and “relaxed” (green) MFRSR cloud screening.



929

930 Figure 8. Distribution of the points considered aerosols (38,971 points, orange bars), clouds (88,038
931 points, blue bars), and “transition” (81,250 points, purple bars) across the range of OD values (left)
932 and AE values (right), after applying the MFRSR cloud screening algorithm with different thresholds.
933 It should be noted that “clouds” refers to instances that have not passed the screening by the MFRSR.
934 Dashed lines indicate the (approximate) percentiles 1 and 99 of the “clouds” and “aerosols”
935 distributions.



936 Figure 9. Original and processed TSI images, with different thresholds for the distinction between
937 clear sky and thin clouds. a) March 8, 2014, 11:00. An example of very clean day, when changing the
938 threshold does not affect the cloud fraction estimation. b) August 23, 2014, 15:00. Very white clouds
939 in a very clean (blue) sky. Again, changing the threshold has a very minor effect on the estimation. c)
940 May 16, 2014, 08:14. An example with large circumsolar radiation, where lowering the threshold
941 greatly increases the thin cloud fraction estimation. d) May 19, 2014, 09:00. A similar case, but with
942 an apparently large aerosol load. e) June 10, 2014, 10:30. Small cumulus forming in a somewhat hazy
943 atmosphere. The effect of changing the threshold is huge. f) August 10, 2014, 11:00. A similar case,
944 showing again the large effect of changing the threshold.